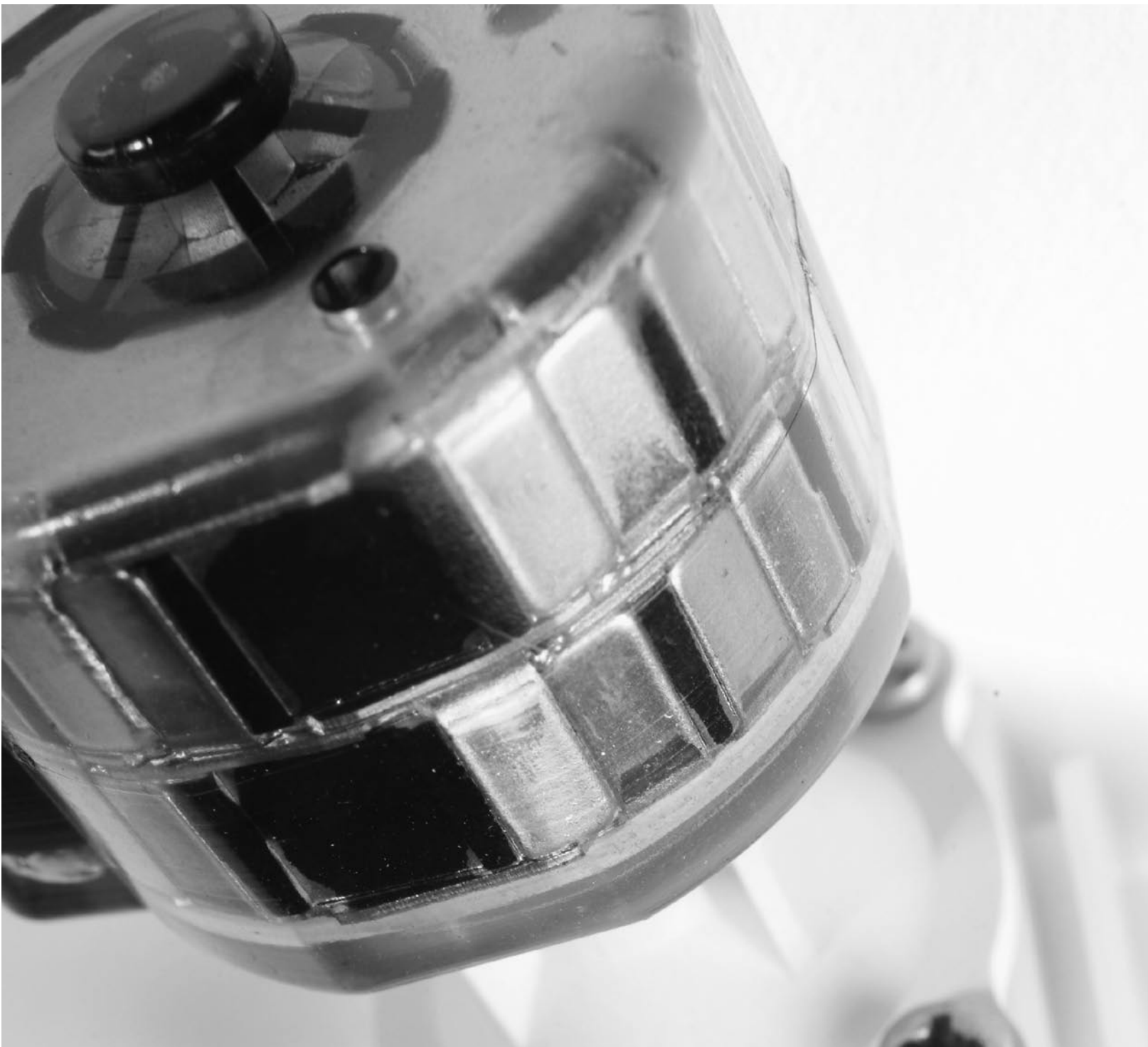


Motors

saia



The data used in this Product Overview may be used as a guideline only. Specific operational characteristics of our products may vary according to individual applications. It is strongly recommended that specific operating conditions are clarified with Johnson Electric before application.

Johnson Electric Terms and Conditions of Sale apply.

All data may be subject to change without notice.

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The Johnson Electric Group is one of the world's largest providers of motion actuators for automotive and industrial applications

Over the years, we have shipped billions of motors to more than thirty countries in over one hundred different motor applications. Johnson Electric has an annual production capacity of one billion motors.

to meet all of our commitments and to support our customers' success. Product reliability and assurance of supply are our commitment.

At the heart of Johnson Electric's success is our commitment to make our customers successful. Our customers include many of the world's leading industrial, consumer and automotive companies. We begin by understanding our customers' business needs, and the product application requirements of the end user of our customers' products. Then we design and deliver innovative motion solutions that help our customers to differentiate their products in the marketplace. Our goal is to be instrumental in the successful launch of our customers' products in their respective marketplaces.

Our Brand Promise

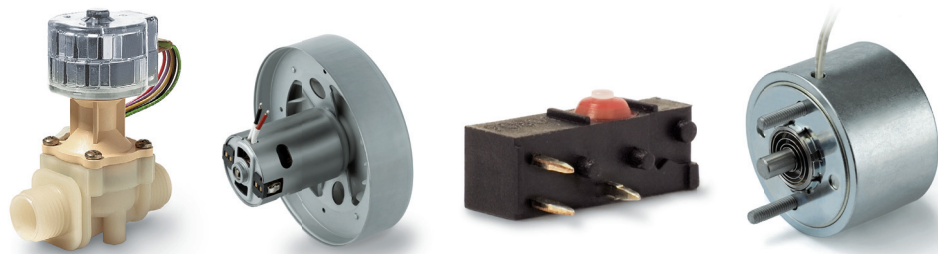
Johnson Electric is the most reliable partner

Johnson Electric is responsive and flexible; and has the financial stability and organizational integrity

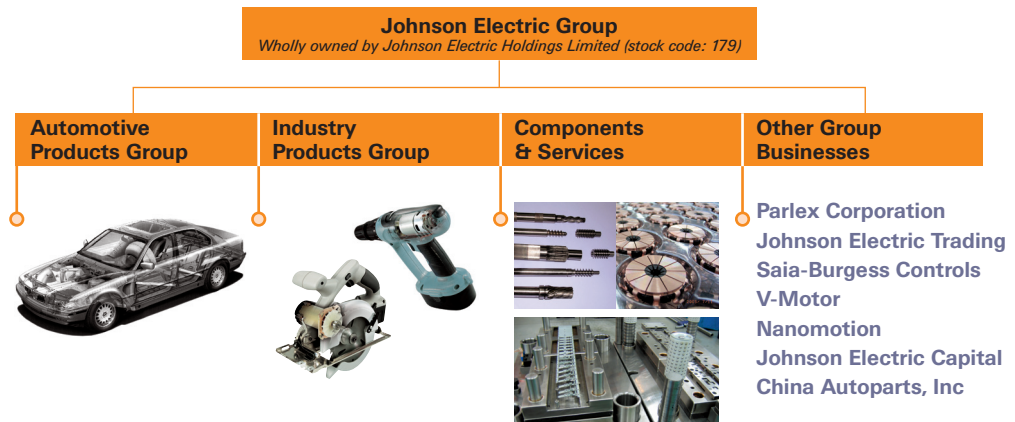
Johnson Electric delivers competitive advantage

Johnson Electric delivers differentiation and innovation through its motion products – subsystems comprising of Stepper Motors, DC Motors, AC Motors, Piezo-electric Motors, Switches, Solenoids, Flexi Circuits, Motion Control, Precision Plastics and Precision Gears.

Our business growth hinges with leading "branded" goods producers to deliver differentiation and innovation through our motion products. The core platform for delivering these solutions is a highly developed production base and focused customer support teams throughout the world. This combines scale advantages in production and procurement with skilled and dedicated motion application experts.



Johnson Electric Holdings Limited is the parent company of the Johnson Electric Group and has been listed on the Stock Exchange of Hong Kong since 1984. The Group structure consists of a number of operating divisions and business units focused on their particular customer application or product segment



The Group's motion systems, motors and switches businesses are managed through two primary operating divisions: Automotive Products Group and Industry Products Group.

The Automotive Products Group, which consists of Johnson Electric's Automotive Motors Group and the Automotive Division of Saia-Burgess Electronics, is focused on providing customized motion solutions for major automotive application segments that include powertrain, body and chassis.

The Industry Products Group is comprised of business units that provide motion products and solutions for various commercial and industrial application sectors, including home appliances, power tools, business equipment, personal care products, medical equipment and healthcare, building automation and security, audio-visual and other industrial products.

Supporting these two operating divisions is the Group's Components & Services function which produces metal and plastic parts, tooling and production equipment for motor and motion related products. Johnson Electric is a highly vertically integrated business that manufactures an exceptionally wide range of components that form the basis for its final assembled end products. We make magnets, bearings, shafts, housings, laminations, commutators and die cast parts. We also build tools, assembly fixtures, plastic molds as well as armature winding and other production machines.

In addition to motion systems and motors, the Group also consists of a number of complementary manufacturing businesses and other subsidiary companies. These include an innovative provider of flexible printed circuits and interconnect solutions; a successful niche player in the programmable controls industry; and a rapidly growing specialty metals and trading services company.

Looking for a specialized motor solution?

Look no further.

We offer the industry's most comprehensive combination of technology, engineering and manufacturing to satisfy all your actuation design needs. From stand-alone motor products to complete value-added solutions; we can do it all for you. The images shown are just a few samples that demonstrate our design and value-added assembly capabilities.

If your application requires more than a standard product solution, please consider us early in your design process. Our application engineering staff will be happy to discuss your requirements.



Saia – a leading global motor brand

We offer the best design resources for actuating solutions – whether it's one motor delivered tomorrow morning or a half million delivered just-in-time over the next year.

Machine and process automation can range from the most basic on-off function to extremely complex sequencing. When the process involves linear or rotary motion, motors are among the best actuation devices in terms of size, cost, simplified installation, and ease of use.

On this page are some of the primary functions which are ideally suited for Saia motors, followed by several pages of current application examples of our products applied in a wide variety of industries. If your design includes linear or rotary operations, we can help you determine the best product to meet your application design requirements.

Variable Positioning

Stepper motor for linear applications and rotary applications provide variable positioning capabilities.

Uncompromising Reliability

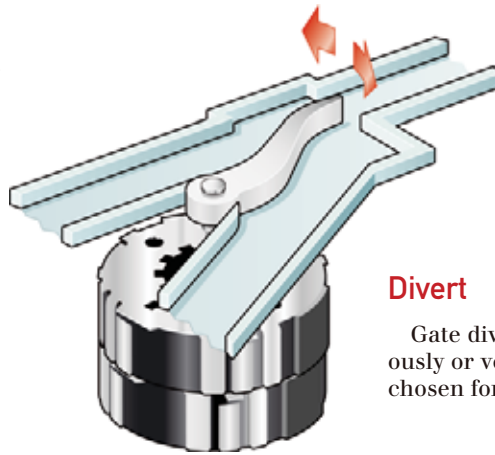
Saia motors provide repeatable, predictable performance.

Common Rotary Motor Applications

- Counters
- Circuit breakers
- Rotary valves
- Rotating lamps
- Textile machinery
- Flaps
- Level indicators
- Ticket machines
- Copiers

Common Linear Motor Applications

- Coffee machines
- Textile machinery
- Linear valves
- Vending machines

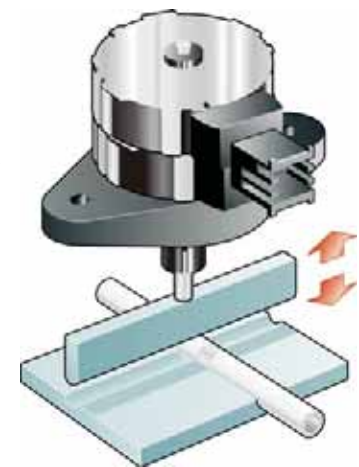


Divert

Gate diverters, depending on the application, can be used continuously or very infrequently. In this example, a stepper motor unit is chosen for its actuation life rating.

Pinch

In this example, a linear motor is utilized for its variable positioning capability to smoothly pinch the tube to the operator's precise demand.



Position

Positioning applications can range from a simple ratcheting device, such as this, to precise variable positioning using linear or rotary motor.



Motors for Pharmaceutical and Medical Equipment

Saia motors are ideally designed for precise, clean, quiet, reliable automation of a variety of medical equipment functions.

Inherent features which optimize linear and rotary motor use in the medical industry include:

- Easy control with simple electronics
- Instant actuation or smooth variable positioning
- High MTBF, reliable, repeatable operation without degradation due to wear
- Long, predictable life (10⁶ cycles)
- Ideal for both open loop or closed loop microprocessor controlled systems

Pharmaceutical Dispenser

- Locks storage trays closed
- Locks individual medicine compartments
- Counts tablets as dispensed

IV Fluid Metering

- Acting as pinch valves, motor offer a simple, direct, reliable means to start and stop fluid flow through valves or tubing
- Principle motor design advantages include non-contacting, quiet operation with minimal heat generation
- Also, depending on the design requirements of the application, either immediate on/off or slow, proportional actuation can be achieved

Intraocular Microsurgery

- Motors are used to control fluid flow through a series of tubes during intra-ocular surgery
- Reliability is a primary motor advantage because a malfunction during surgery could be detrimental

Surgical Laser

- Motors are commonly used as the shutter mechanism for surgical lasers.

Portable, Real-Time Blood Analyzer

- A bedside blood analyzer allows blood to be monitored during administration of medicines allowing doctors to prescribe medications in more exacting dosages based on the patient's condition

Motors as Locking Mechanism

Motors are found in numerous applications that require a locking device. Whether it is a medical application, an office automation application or a door lock, motors provide an effective, cost-efficient locking mechanism.

Security Applications

- Hotel room door lock
- Hotel safe lock
- Prison door lock
- Fire safety door opening lock

Office Automation

- Disk drive door lock
- Personal computer chassis lock
- Docking station lock
- Locks to hold peripherals in place
- Tape library index lock

Medical

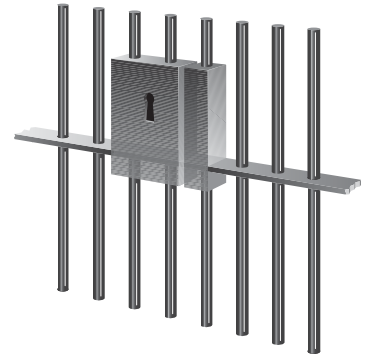
- Sterilizer lock
- Centrifuge lock
- Blood analysis machine lock

Consumer

- Oven door lock for self-cleaning function
- Garage door safety lock
- Home safe lock

Industrial

- Overhead door lock
- Fire safety door lock
- Prison locks
- Commercial laundry locks



Motors in the Appliance Industry

Motors are found in numerous applications in the appliance industry. AC and DC products are available for on/off operation on many types of consumer and commercial appliances.

Domestic Appliances

- Through the door refrigerator ice and water dispensers
- Door locks on self-cleaning ovens
- Gas valve control on gas ranges and ovens
- Drain control valves on domestic washing machines
- Brake motors on domestic washing machines



Commercial Appliances

- Dispensing valves
- Beverage dispensing valves
- Product dispensers on vending machines
- Coin changers on vending machines
- Actuating devices on commercial baking and food processing or packaging equipment
- Wrapping material cutters for food packaging
- Gas valve control on gas fired boilers and furnaces
- Industrial overhead door brake mechanisms

Table of typical applications & Saia Motor Series

In addition to the products shown in the Product Catalog pages, the Product Mapping table below shows a wide range of motor types for a selection of applications. Also, motors may be customized to fulfill your specific requirements, please feel free to contact us.

Application & Motor types	URT	UAT1/UAT3	UCM/UCR	UBR1/UBR2	UDR	UDS	UO	UFM/UFR	UHM	UP	UNUO	UOUO	UPUO	URG	UAG1/2	UAG3/4	UCD/UCB	UBD/UBB	UDB	UO	UFD/UFB	UHD	UP	UGA/UGD	UGM	UGB/UGF	UGO/UGP	UGJ	UGR	UCC/UCK	UBK	UO Linear actuator	UCE/UCL	UBL	
HVAC/Diverter valves		●	●	●		●									●	●	●	●											●	●		●	●		
HVAC/Thermostatic valves		●					●	●																											
Coffee machines		●													●	●	●													●			●		
HVAC / Air Flaps		●	●																											●	●		●	●	
Vending/Gaming		●	●	●	●	●	●	●							●	●		●		●	●	●								●	●		●	●	
Industrial Equipment		●	●	●	●	●		●		●		●			●	●	●	●	●	●	●	●		●	●		●	●		●	●	●	●	●	
ATM															●																				
Medical	●			●	●	●		●		●			●	●	●			●	●	●	●	●	●	●		●		●		●	●	●	●	●	
Commercial Equipment	●	●	●	●	●	●	●	●	●	●				●	●	●	●	●	●	●	●	●		●	●										
Pellet stoves								●														●													
Level indication						●																													
Textile machines																	●																	●	
Credit card readers															●	●																			
Pan and tilt cameras												●	●																						
Chart recorders															●	●																			
Tachograph															●	●																			
Conveying								●		●												●													
Mechanical handling																																			
Copier & Printer						●		●							●			●	●			●	●												
Distribution			●	●		●	●	●	●	●				●	●		●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	
Home Appliances				●	●	●		●								●	●							●			●						●	●	
Industrial automation			●																																
Specialist vehicles						●												●	●			●												●	
Waterheaters/Showers				●		●													●			●													
Circuit Breaker				●				●				●						●				●						●		●					
HVAC		●	●	●	●	●	●	●	●	●	●	●			●		●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	
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Saia Motors Important notes

General

All specifications for torque, force and power are representative only and maybe subject to variation due to manufacturing tolerances.

Saia motors motors, except UR types, fulfil basis insulation requirements of EN 60335-1: 2004.

Application advice

The requirements for protection class I, II or III according to EN 60355-1: 2004 have to be fulfilled by customer application.

Stepper motors

- Specified data for torque values is valid for
- a duty cycle of 100%, in Performance Charts additionally for 50% (cycle time: 5 min, type URG only 1 min.)
 - an ambient temperature of $25 \pm 5^{\circ}\text{C}$
 - a defined driver circuitry, with constant voltage supply
 - at rated voltage

If duty cycle or actual maximum ambient temperature is lower, the motor can be designed for higher performance (torque and power) by using a different winding.

Chopper driver circuits can be applied alternatively to a driver with constant voltage supply. They are more expensive, but bring higher performance. Additionally, they eliminate the effects of temperature and supply voltage change.

Performance charts available on request.

Step angle tolerance is about $\pm 5\%$ (not cumulative)

Synchronous motors

Specified data for torque/power values are valid for

- a duty cycle of 100%
- an ambient temperature of $25 \pm 5^{\circ}\text{C}$
- at rated voltage
- synchronous torque (not starting torque)

Torque is specified with maximum values, overloading is not permissible.

If duty cycle or actual maximum ambient temperature is lower, the motor can be designed with higher performance by using a different winding.

The basic design is the same as for our stepper motors, but the motors are operated by a sinus waveform voltage.

A capacitor, connected to one of the motor coils, is necessary for rotation in the appropriate direction.

Motor type UDS is a special design: It has only one coil, but is fitted with an internal ratchet. This ratchet determines the direction of rotation. A capacitor is not necessary.

Mechanical and electrical connections

- On request we can deliver other options, e. g.
- special motor shafts
 - pinions on shaft
 - special cable lengths
 - connectors

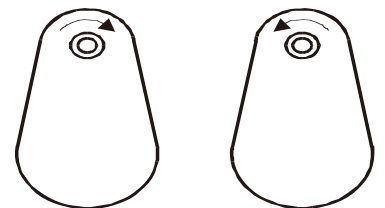
Saia motors Gearboxes

Saia motors gearboxes are available in a variety of sizes to meet a wide range of torque requirements. Ratios from 4 1/6 to 6.048.000 are available. The basic design is a spur gearbox with gear wheels in metal, plastics and combinations of the two materials. A particular feature is the availability of freewheels and slipping clutches.

The gearboxes are turned by the motor, energy flow is from input to output shaft. That means, they are not allowed to be driven by the output shaft (for instance turning manually). This can lead to damage of some internal components!

Direction of rotation

As a function of the number of stages, the direction of rotation can be either clockwise or counter clockwise. The direction of rotation of motor gearbox units is generally specified by the gearbox output shaft (drive-side, see DIN EN60034-7, IEC 60050-411).



clockwise counter clockwise

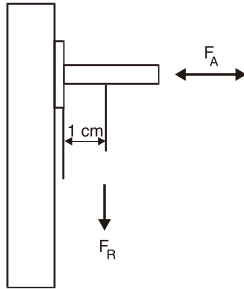
Ratio

A gearbox is characterised by its gear ratio i or its time T . Gear ratio i is the ratio of input speed n_e and output speed n_a . T is the time for one revolution of the output shaft.

Permissible force F_A and F_R at the output shaft

Permissible force loads at the output shaft are:

- Axial load F_A , pulling or pushing in axial direction of the shaft
- Radial load F_R acting laterally on the shaft. The catalogue value is referred to a distance of 1 cm to the bearing



Permissible Torque

The lifetime of a gearbox is determined by the load on the gear teeth and the number of revolutions of the gear wheels.

The maximum permissible torque M_n is defined by the load on the final stage of the gearbox and the stability of the housing.

Some gearboxes have lifetime graphs. It shows the relationship between ratio i and the associated torque for a fixed period of time, e.g. 1000 or 10000 hours. A conditional parameter is the input speed (equivalent to motor speed) corresponding to the total number of revolutions of all gear wheels. In the catalogue we show therefore two curves - for a motor having 250/300 rpm and 500/600 rpm.

For example: Max.output torque M_{x1} is permissible at a ratio of i_{x1} . With smaller ratios the max. permissible torque has to be reduced, because otherwise the first stages of the gearbox would be overloaded.

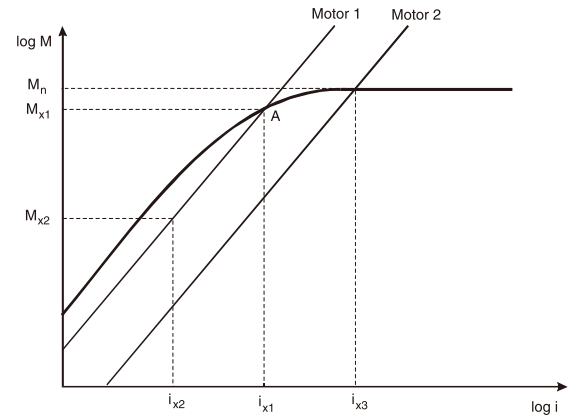
Additionally to the lifetime curve the motor torque M_m , multiplied by gear ratio and reduced by the gear efficiency, is shown (resulting in output torque M_i).

$$i = \frac{n_e}{n_a} \quad T = \frac{i \times 60}{n_e}$$

With n in rpm
 T in seconds

Saia motors Gearboxes

$$M_i = M_m \times i \times \eta_G$$



Example1: The application of motor 1 combined with a gearbox of ratio i_{x1} leads to an output torque M_{x1} at point A. The gearbox can transmit this torque, meeting its lifetime.

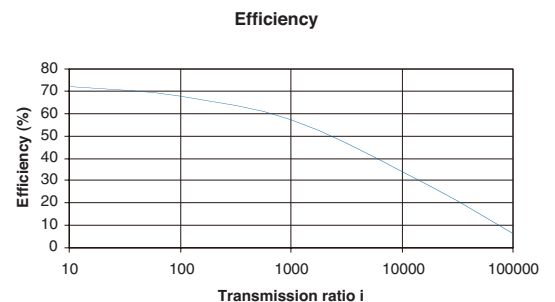
If a ratio of $i > i_{x1}$ is selected, actual torque would be $M > M_{x1}$. However lifetime cannot be guaranteed, as the operating point now lies above of the lifetime curve.

Example 2: Motor 1 with a ratio of i_{x2} . Torque generated is M_{x2} . This is below of the lifetime curve. The transmission can operate for an extended period without difficulty.

Example3: Motor 2 and a ratio of i_{x3} give a torque of M_n . When using a ratio of $i > i_{x3}$ - the gearbox cannot be loaded more than M_n .

Efficiency

The number of stages in the gearbox determines the efficiency. With high ratios of i this factor will decrease below 10%, as the graph below shows. (For UGO/UGP, UGR, see table in the chapter)



Saia motors Gearboxes

Clutches

Gearbox types UGA, UGB and UGD can be fitted with freewheels or slipping clutches. Freewheels transmit the max. torque M in the locked direction, <1 cNm in the opposite direction. One way slipping clutches behave similarly except that the slip torque has a higher value. Two way slipping clutches can only transmit a limited torque value in either direction lower than the slip torque.

Slipping clutches are used to: Protect the gearbox against torque overloads, or to adjust the load by turning from the load side (remember: turning the output shaft directly can otherwise damage the gearbox).



Slipping clutch	One way	One way	Two way
Freewheel	yes	yes	no
Torque, clockwise	full torque	< slipping torque	< slipping torque
Torque Anti clockwise	< slipping torque	full torque	< slipping torque
Output shaft turning, clockwise	slipping possible	blocking	slipping possible
Output shaft turning, anti clockwise	blocking	slipping possible	slipping possible

Common Explanations of characteristics

Power consumption P_{in}

The power consumption expressed in W was determined in no-load operation

Load

The total sum of all static and dynamic torques (e.g. friction torque, mass inertia, acting on the rotor).

Speed n

rmp revolution per minute

Torque

The running torque in cNm (also synchronous, braking or dynamic torque) defines the load at which the synchronous motor falls out of synchronism and stalls.

Power output

The power output expressed in W is determined according to the following formula

$$P_{out} = \frac{M_d \times 2 \pi \times n}{60} = [W]$$

M_d in Nm (1 cNm = 0,01 Nm), n in rpm

Pole pair number

The number of rotor pole pairs North/South.

Direction of rotation

This information always refers to the output shaft, either of the motor or of the gearbox.

Right = clockwise rotation (CW),

Left = counterclockwise rotation (CCW)

Gear torque

The maximum gear torque in cNm defines the maximum load for a required life of at least 1000 operating hours.

Running time

This value refers to the time (t) per revolution (U); they are calculated using the following formula

$$t/U = \frac{i}{n} \times 60 = [\text{sec.}]$$

i = transmission ratio

n = motor speed

Axial thrust / lateral force / lateral torque

These values refer to the loads on the standard output shaft of the respective gear.

The permissible lateral torque referring to the standard shaft must not be exceeded on special shafts either.

General technical terms relating to the synchronous motor and torque limited synchronous motor

Synchronous

The running of the rotor at the same speed as the stator field which is determined by the frequency of the supply.

Synchronous speed

Constant speed of rotation at constant frequency based upon the number of pole pairs of the motor

$$n = \frac{f \times 60}{p}$$

f = frequency (Hz), n = speed (rpm)
p = number of pole pairs

Synchronous torque

Torque which the motor is still capable of producing without falling out of synchronism, once the synchronous speed of rotation has been reached.

Starting torque

Load torque the motor is capable to start.

It is influenced by the type and manner of coupling to the load, the load inertia, the gearbox design and the supply voltage. In the case of a very large reduction ratio a small external moment of inertia and nominal gearbox play the starting torque becomes equal to the synchronous torque.

Detent torque (static)

Defines the maximum torque which can be applied to a deenergised motor without causing the motor to rotate. Catalogue specifications refer to the static detent torque.

Detent torque (dynamic)

Defines the maximum torque at which the motor comes to an immediate standstill from synchronous running when the excitation current is switched off.

Permissible load inertia

Is the maximum inertia load the motor can start without external help.

Stall-proof

Synchronous motors with permanent magnet rotors can be stalled without damage to the motor winding.

Torque limit (Torque limited motors)

The constant torque produced by the hysteresis-magnetic clutch within the torque limited synchronous motor in the stalled condition.

Design characteristics

The basic design is the same as for our stepper motors, but the motors are operated by a sinus waveform voltage.

General technical terms relating to the stepper motor

ED or Duty Cycle

Duty cycle of operation, based on a cycle time of 5 minutes (1 minute for URG) and a frequency f=0Hz; e.g. ED=30% means that the motor can be continuously powered 1.5 minutes (30% of 5 minutes) without overheating

Step

Rotary movement of the rotor through one step angle.

Step angle

Rotary angle through which the motor shaft turns per controlled pulse.

Stepping frequency

Number of steps of the stepping motor in 1 sec.

Driver

Electronics which convert step and direction input signals to high power currents and voltages to drive a step motor.

Unipolar driver

Unipolar means that every coil end has one polarity only. A unipolar coil consists in fact of 2 coils. Alternating the current flows through one of these coils and in one direction. Compared to a bipolar motor only half of the copper is used at time.

The motor phase winding must be center tapped. On the SAMOTRONIC101 this is already fixed on the board.

Often an additional Zener diode is used to ensure a fast current decay in the switched-off coil. This will give an increased motor torque especially at higher frequencies.

Torque graphs in this catalogue are measured with a 10V Zener diode.

Bipolar Driver

Bipolar indicates that every coil end is bipolar, during driving it will be „+“ as well as „-“. Since every coil is fully used the motor has a higher torque compared to a unipolar one.

Very often a bipolar driver has a constant current drive capability (also called chopper). That will give an increased torque output on higher frequencies and a lower influence of temperature and supply voltage variations. Typical applications use the SAMOTRONIC102.

Rotational speed

Revolutions of the motor per minute calculated from:

$$n = f \times \frac{\alpha \times 60}{360^\circ}$$

f = stepping frequency, α = step angle.

Detent torque (static)

Defines the maximum torque which can be applied to a deenergised motor without causing the motor to rotate. Catalogue specifications refer to the static detent torque.

Holding torque

Defines the maximum torque with which an energized motor can be loaded without giving rise to a continuous rotary movement.

Pull-in torque

Operation torque when switching on step frequency at once, without a ramp.

pull-out torque

Operation torque when applying an acceleration / deceleration ramp.

Load inertia moment

The sum of all the mass inertia moments occurring on the shaft of the stepping motor.

Steps/rev

The number of steps per 360° rotation.

Maximum operating torque

The maximum torque which a stepper motor without external mass inertia can generate without stepping losses.

Synchronous Motors

Rotational



Type	URT	UAT1/UAT3	UCM/UCR	UBR1/UBR2	UDR
Dimensions (mm)	∅ 13 x 11	∅ 20 x 17	∅ 28 x 24	∅ 36 x 21	∅ 48 x 24
Characteristics	<ul style="list-style-type: none"> ■ smallest motor ■ optional planetary gearbox with diameter 13mm ■ pin connection or flex print 	<ul style="list-style-type: none"> ■ long life ■ precision bearing ■ standard 24VAC motor ■ economic volume solution 	<ul style="list-style-type: none"> ■ standard modules ■ customer specific interfaces 	<ul style="list-style-type: none"> ■ wide range of customised versions available ■ up to 230 VAC supply voltage 	<ul style="list-style-type: none"> ■ compact reversible synchronous motor
Voltage (V)	3–24	12–48/24	12–230	12–230	12–230
Speed 50 Hz (rpm)	600	600	250/500	250/500	500
60 Hz (rpm)	720	720	300/600	300/600	600
Pole number	10	10	24/12	24/12	12
Running torque (cNm)					
50 Hz	0,06	0,31/0,32	0,8–1,3	0,75–0,9	1,5
60 Hz	0,06	0,3/0,3	0,8–1,3	0,72–0,9	1,4
Power output (W)					
50 Hz	0,038	0,19/0,2	0,31–0,58	0,24–0,39	0,77
60 Hz	0,038	0,23/0,23	0,38–0,69	0,28–0,45	0,87
Gear combination	on request	on request	on request	A, D, M, B, F, V, J	A, D, M, B, F, V, J
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Rotational



Type	UDS	UO (SM5021/SM5022)	UFM/UFR	UHM	UP (SM6443/SM6444)
Dimensions (mm)	∅ 48 x 18,5	∅ 50 x 21	∅ 52 x 28 (56)	∅ 59 x 35 (70)	∅ 64 x 43
Characteristics	<ul style="list-style-type: none"> ■ simple to connect, only two wires ■ no capacitor ■ uni-directional with anti-return mechanism 	<ul style="list-style-type: none"> ■ three speeds versions ■ wide range of torque capacities 	<ul style="list-style-type: none"> ■ three-phase AC operation possible ■ for high power 2, 3 or 4 coils 	<ul style="list-style-type: none"> ■ powerful motor ■ synchronous version of the stepper motor UHD 	<ul style="list-style-type: none"> ■ most powerful package with STG/V gearboxes
Voltage (V)	6–230	6–230	12–230	12–230	12–230
Speed 50 Hz (rpm)	500	250/375/500	250/500	250	250/375
60 Hz (rpm)	600	300/450/600	300/600	300	300/450
Pole number	12	24/16/12	24/12	24	24/16
Running torque (cNm)					
50 Hz	0,9	2,0–7,5	2,8–5,3	8,5–15	10,3–35
60 Hz	0,8	1,8–7	2,6–4,7	6,6–9,5	8,5–30
Power output (W)					
50 Hz	0,5	0,65–2,75	1–2,8	2,2–3,9	3,5–13,8
60 Hz	0,5	0,78–3,0	1,1–3	2,1–3	3,9–14,2
Gear combination	A, D, M, B, F, V, J	VK4, O, P, R	A, D, M, B, F, V, J, O	J	O, P, R
Page	41	43	48/50	54	57

Synchronous Motors

Rotational, Torque Limited



Type **UNU0**
(SM3532RG)

Type **UOU0**
(SM5032RG)

Type **UPU0**
(SM6469RG)

Dimensions (mm) \varnothing 35 x 32

\varnothing 50 x 32

\varnothing 64 x 69

Characteristics ■ torque limiting feature
■ abrasion-free, integrated low noise magnetic hysteresis clutch

Voltage (V) 24–230

24–230

24–230

Speed 50 Hz (rpm) 375
60 Hz (rpm) 450

375
450

375
450

Pole number 16

16

16

Torque Limited (cNm)

50 Hz 0,6
60 Hz 0,6

2
2

7
7

Power output (W)

50 Hz 0,25
60 Hz 0,3

0,8
0,95

2,75
3,3

Gear combination O, P, R

O, P, R

P, R

Page 62

65

68

Stepper Motors

Rotational



Type	URG	UAG1/2	UAG3/4	UCD/UCB	UBD/UBB
Dimensions (mm)	∅ 13 x 11	∅ 20 x 17	∅ 20 x 17	∅ 28 x 24	∅ 36 x 21
Characteristics	<ul style="list-style-type: none"> high dynamic performance optional planetary gearbox with motor diameter pin connection or flex print 	<ul style="list-style-type: none"> precision bearing standard motor 	<ul style="list-style-type: none"> economic volume solution 	<ul style="list-style-type: none"> standard modules customer specific interfaces 	<ul style="list-style-type: none"> wide range of customised versions available
Step angle(°)	18	18	18	7.5/15	7.5/15
Holding torque (cNm)	0.20	0.7/0.5	0.56/0.42	1.3–2.7	1.0–1.9
Detent torque (cNm)	0.03	0.14	> 0.06	0.26–0.42	0.22–0.36
Winding	bipolar	bipolar/unipolar	bipolar/unipolar	bipolar/unipolar	bipolar/unipolar
Gear combination	on request	on request	on request	on request	A, D, M, B, F, V
Page	72	75	78	81/85	89/92

Rotational



Type	UDB	UO (ST5021/ST5022)	UFD/UFB	UHD	UP (ST6443/ST6444)
Dimensions (mm)	∅ 48 x 24	∅ 50 x 21	∅ 52 x 28 (56)	∅ 59 Tx 35 (70)	∅ 64 x 43
Characteristics	<ul style="list-style-type: none"> compact reversible 15° stepper motor 	<ul style="list-style-type: none"> three step angle motor wide range of torque capabilities 	<ul style="list-style-type: none"> two step angle motor 	<ul style="list-style-type: none"> powerful standard motor 7.5° stepper motor 	<ul style="list-style-type: none"> most powerful package with STG/V gearboxes
Step angle(°)	15	7.5/11,25	7.5/15	7.5	7.5/11,25
Holding torque (cNm)	2.2–2.7	3.7–4	6.4–45.3	13–45.5	30–45
Detent torque (cNm)	0.35	0.25–1	0.45–0.8	1.3–5.3	2–7
Winding	bipolar/unipolar	bipolar	bipolar/unipolar	bipolar/unipolar	bipolar
Gear combination	A, D, M, B, F, V, J	VK4, O, P, R	A, D, M, B, F, V, J, O	J	O, P, R
Page	95	98	101/104	108	113

Gearboxes



Type	UGA/UGD	UGM	UGB/UGF
Dimensions (mm)	55 x 62/65.6	51 x 65.2	58 x 81
Characteristics	<ul style="list-style-type: none"> ■ established plastic gears ■ wide range of ratios ■ gears rotate on hardened steel shafts ■ optional integrated slipping clutches 	<ul style="list-style-type: none"> ■ volume metal and plastic spur gears ■ hardened steel shafts included in plastic housing and metal plate 	<ul style="list-style-type: none"> ■ robust metal spur gears, ■ plastic primary gears ■ die-cast aluminium housing
Height	12/13	15	17
Max. torque (cNm) ¹⁾	32	100	250/500
Ratios	A: 4 ¹ / ₆ ...360.000 D: 4 ¹ / ₆ ...6.048.000	12 ¹ / ₂ ...4800	B: 4 ¹ / ₃ ...345.600 F: 4 ¹ / ₆ ...5000
Internal slipping clutch	optional	–	optional (UGB)
Standard shaft (mm)	∅ 4 x 10	∅ 4 x 10	∅ 8 x 12
Page	117/119	121	124/126

¹⁾ max. value. for higher ratios



Type	UGV	UGO/UGP (STG60/STG61)	UGJ	UGR (STG200)
Dimensions (mm)	70 x 70	∅ 65/68 x 68	65 x 107	70 x 130
Characteristics	<ul style="list-style-type: none"> ■ solid metal spur gears ■ die-cast aluminium housing 	<ul style="list-style-type: none"> ■ high performance hardened steel spur gears ■ low teeth profile ■ optional interface plates for DC motors ■ option additional housing for IP 65 	<ul style="list-style-type: none"> ■ the most extensive gear ratio range ■ medium torque two plate gear type with metal spur gears 	<ul style="list-style-type: none"> ■ high performance metal gear type ■ robust aluminium twin plate design ■ can be used with DC motors
Height	17	29.8–38 ²⁾	28	38
Max. torque (cNm) ¹⁾	500	600	1500	2000
Ratios	8 ¹ / ₃ ...2.000	6 ¹ / ₄ ...5400	4 ¹ / ₆ ...36 Mill. ≥ 2500 with UGD	6 ¹ / ₄ ...375
Internal slipping clutch	–	–	–	–
Standard shaft (mm)	∅ 8 x 12	∅ 8 x 22	∅ 12 x 20	∅ 12 x 35
Page	128	130	135	137

¹⁾ max. value. for higher ratios ²⁾ depends on ratio

Synchronous Motors

Linear



Type **UCC/UCK**

UBK

UO
Linear actuator
(LA5021SM)

UO
Spindle actuator
(SP5021/5022SM)

Dimensions (mm)	∅ 28 x 31	∅ 36 x 36	∅ 50 x 76	∅ 50 x 27
Characteristics	<ul style="list-style-type: none"> ■ newlinear motor using modules of the UC range ■ integrated non-rotational threaded spindle 	<ul style="list-style-type: none"> ■ standardlinear motor for extended travel the spindle has to be retained externally 	<ul style="list-style-type: none"> ■ linear actuator with 3 speeds ■ 50 mm travel ■ integrated non-rotating threaded spindle 	<ul style="list-style-type: none"> ■ spindle type ■ threaded spindle has to be retained externally for extended travel
Travel (mm)	10/13	8/13/56	45–50	68–130
Voltage (V)	12–230	12–230	12–230	12–230
Thread pitch (mm)	1.0	1.0	1.5/1.5/1.5	1.5/1.5/1.5
Speed (mm/s)				
50 Hz	4.16/8.33	6.67/8.33	6.25/9.37/12.5	6.25/9.37/12.5
60 Hz	5/10	8/10	7.5/11.25/15	7.5/11.25/15
Pole number	24/12	12	24/16/12	24/16/12
Max Force (N)	35	35	45–50	45–70/50–70
Page	141/144	147	149	152

Stepper Motors

Linear



Type **UCE/UCL**

UBL

UO
Linear actuator
(LA5021ST)

UO
Spindle actuator
(SP5022ST)

Dimensions (mm)	∅ 28 x 33	∅ 36 x 36	∅ 50 x 76	∅ 50 x 27
Characteristics	<ul style="list-style-type: none"> ■ newlinear motor using modules of the UC range ■ integrated non-rotating threaded spindle 	<ul style="list-style-type: none"> ■ general purpose linear motor ■ for long travel version the spindle has to be retained externally 	<ul style="list-style-type: none"> ■ linear actuator with 3 step widths and 50 mm travel ■ integrated non-rotating threaded spindle 	<ul style="list-style-type: none"> ■ spindle type ■ threaded spindle has to be retained externally for extended travel
Travel (mm)	10/13	8/13/56	45–50	68–130
Travel per step (mm)	0.021/0.041	0.041	0.031/0.047/0.063	0.031/0.047/0.063
Thread pitch (mm)	1.0	0.8	1.5/1.5/1.5	1.5/1.5/1.5
Speed (mm/s)				
at 200 Hz	4.16/8.33	8.33	6.25/9.37/12.5	6.25/9.37/12.5
Step angle (°)	7.5/15	15	7.5/11.25/15	7.5/11.25/15
Max. Force (N)	35	35	45–50	50–70
Page	156/159	162	164	166

Electronics for Stepper Motors

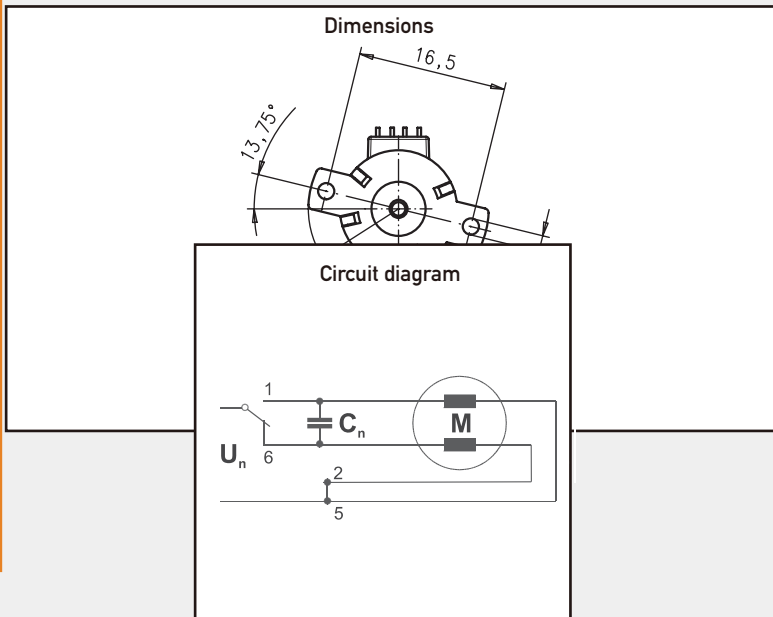
Driver Boards



Type **SAMOTRONIC101** **SAMOTRONIC102** **Evaluation-Kit 2**

Dimensions (mm)	55 x 40	84 x 54	metal case 164 x 130 x 45 (Euro-PCB)
Characteristics	<ul style="list-style-type: none"> ■ small unipolar driver board 	<ul style="list-style-type: none"> ■ small bipolar driver board ■ flash controller ■ optional customised software 	<ul style="list-style-type: none"> ■ tool for development, test and optimisation of stepper drive systems ■ windows-based software ■ quick parameter setup ■ visualisation of speed and position ■ positioning sequences capability
Driver	■ for unipolar motors	■ for bipolar motors	■ for unipolar and bipolar motors
Supply voltage (V)	10–24 DC	standard version 10–24 DC enhanced version 10–42 DC	3–48 DC 24 AC
Motor current	constant voltage drive	constant current drive (chopper controlled) adjustable via potentiometer	constant voltage drive and constant current drive (chopper controlled)
Step mode	full/half step	full/half step	full/half/micro step
Clock source	internal or external	internal or external	internal, programmable
Control inputs to	<ul style="list-style-type: none"> ■ inhibit internal clock ■ inhibit motor current ■ change direction of rotation 	<ul style="list-style-type: none"> ■ inhibit internal clock ■ inhibit motor current ■ change direction of rotation 	<ul style="list-style-type: none"> ■ 3 digital inputs ■ 4 signal outputs ■ 1 analog input 0...10 VDC ■ 1 relay contact
Configuration	via DIP-switch, potentiometer	via DIP-switch potentiometer	RS 232, USB
Page	170	171	172

Synchronous Motors



URT

Dimensions (mm)	∅ 13 x 11
Voltage (V)	3-24
Speed (rpm) 50 Hz	600
Pole number	10
Running torque * (mNm) 50 Hz/60 Hz	0,6
Power output (W) 50 Hz/60 Hz	0,038
Gear combination	-

* standard magnet



Standard Data

Climatic class	„wide-spread“ according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15 ... +60
Ambient temperature storage	°C -20 ... +100
Thermal resistance at f=0 R _{therm}	83 K/W
Thermal class	B according to DIN EN 60085
Approval	standard
Mounting	any position
Electrical connection	Pin, optional flex print
Protection	IP 40 according to DIN EN 60529
Weight	7 g
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	integrated high temperature plastic bearing

Order Reference

Type	Synchronous Motor	URT	1E	N	24 V / 50 Hz	R	N
Configuration	1E	standard magnet					
Approval	N						
Voltage/Frequency	See next page						
Direction	R	reversible					
Connector	N	Pin					
	C	flex print					

This motor type doesn't fulfil basis insulation requirements of EN 60335-1: 2004
Customer application must realize a suitable protection class.

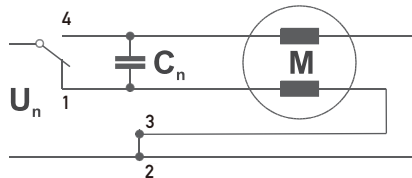
Technical Data

URT1

Rated frequency	Hz	50	
Speed n	rpm	600	
Running torque M_n^*	mNm	0.6	
Detent torque M_S^*	mNm	0.3	
Power output	W	0.038	
Power consumption	VA	0.75	
Rotor inertia J_R	gcm ²	0.033	
Tolerance of voltage		standard power supply system +10%/-10%	
Duty cycle		100%	
Winding temperature T_{max}	°C	130	
Direction of rotation		reversible	
<hr/>			
Capacitors	Rated voltage U_N	V	24
	Operating capacitor C_{50}	µF/40 VAC	2.2

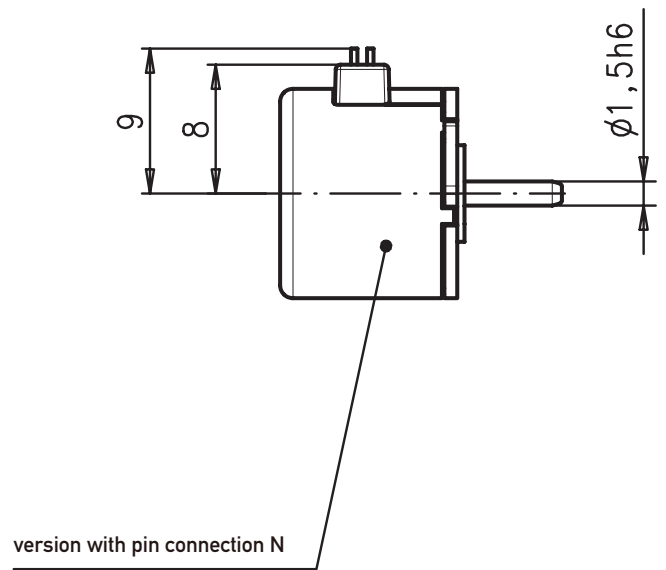
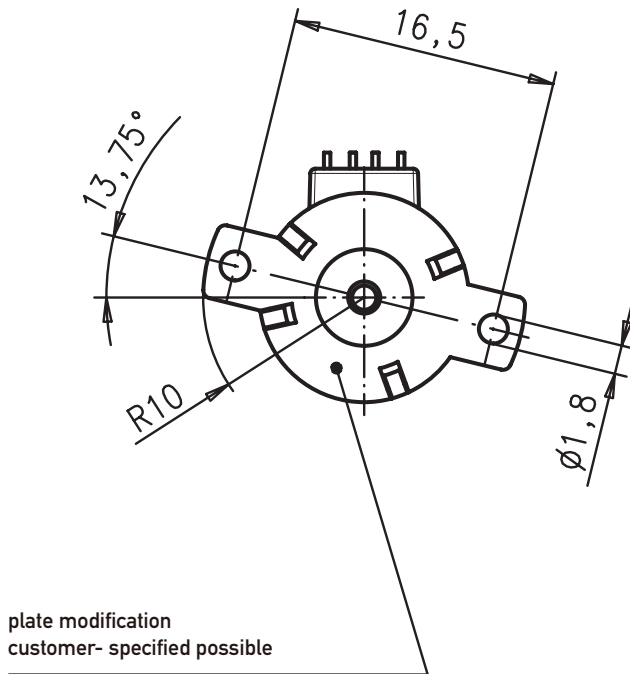
* standard magnet

Circuit diagram Parallel circuit

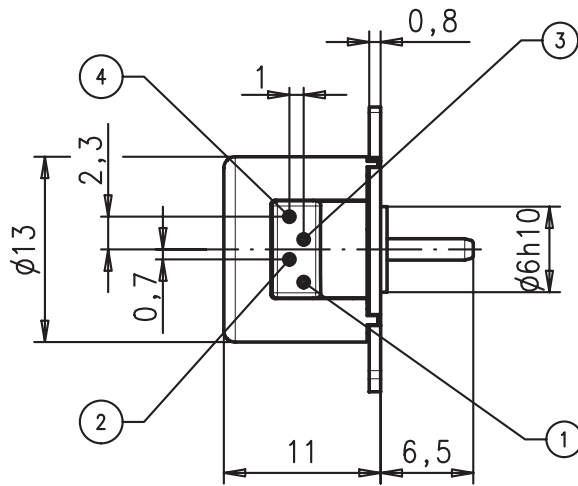


switch to
1 = clockwise rotation
4 = counter clockwise rotation

Dimensions

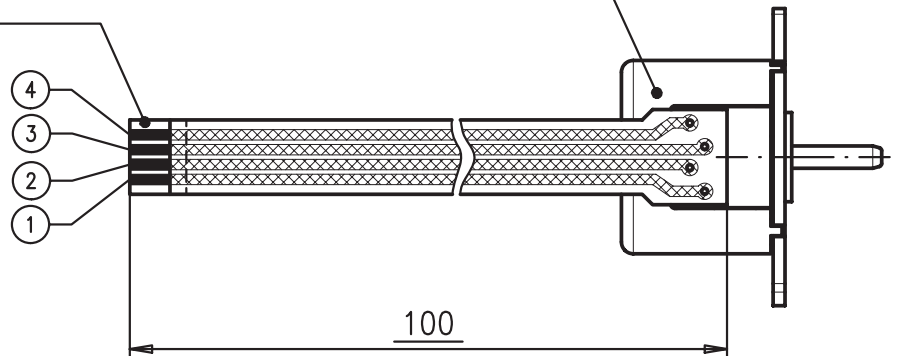


Dimensions



recommended FPC layout for flex print connector 1 mm

version with flex print circuit C



UAT1

Dimensions (mm) $\varnothing 20 \times 17.2$

Voltage (V) 12-48

Speed (rpm) 50 Hz 600
60 Hz 720

Pole number 10

Running torque
(cNm) 50 Hz 0,31
60 Hz 0,3

Power output (W)
50 Hz 0,19
60 Hz 0,23

Gear combination on request



Standard Data

Climatic class	„wide-spread“ according to DIN IEC 60721-2-1
Ambient temperature operation	°C -40 ... +60
Ambient temperature storage	°C -40 ... +100
Thermal resistance at f=0 R _{therm}	50 K/W
Thermal class	„B“ according to DIN EN 60085
Approval	standard
Mounting	any position
Electrical connection	insulation displacement connection, pins, lead wires
Protection	IP 40 according to DIN EN 60529
Weight	25 g
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	sintered bronze, self-lubricating

Order Reference

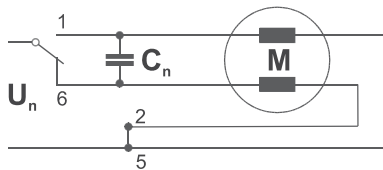
Type	Synchronous Motor	UAT1	0	N	24 V/50 Hz	R	E
Rotor shaft, mounting	0 centring 8 mm, screw plate with thread M2 3 centring 8 mm, screw plate with slotted hole A centring 6 mm, screw plate with thread M2 E centring 6 mm, screw plate with slotted hole						
Approval	N Approval Standard						
Voltage/Frequency	See next page						
Direction	reversible						
Cable	E Lead wires 150 mm with plug AMP MicroMatch 0-215083-6 (other on request)						

Technical Data

Rated frequency	Hz	50	60
Speed n	rpm	600	720
Power consumption	W	0,9	0,9
Power output	W	0,19	0,23
Running torque	cNm	0,3	0,3
Rotor inertia J_R	gcm ²	0,31	
Detent torque M_s	cNm	0,1	
Tolerance of voltage		standard power supply system + 10% / - 10%	
Duty cycle		100%	
Winding temperature T_{max}	°C	130	
Direction of rotation		reversible	

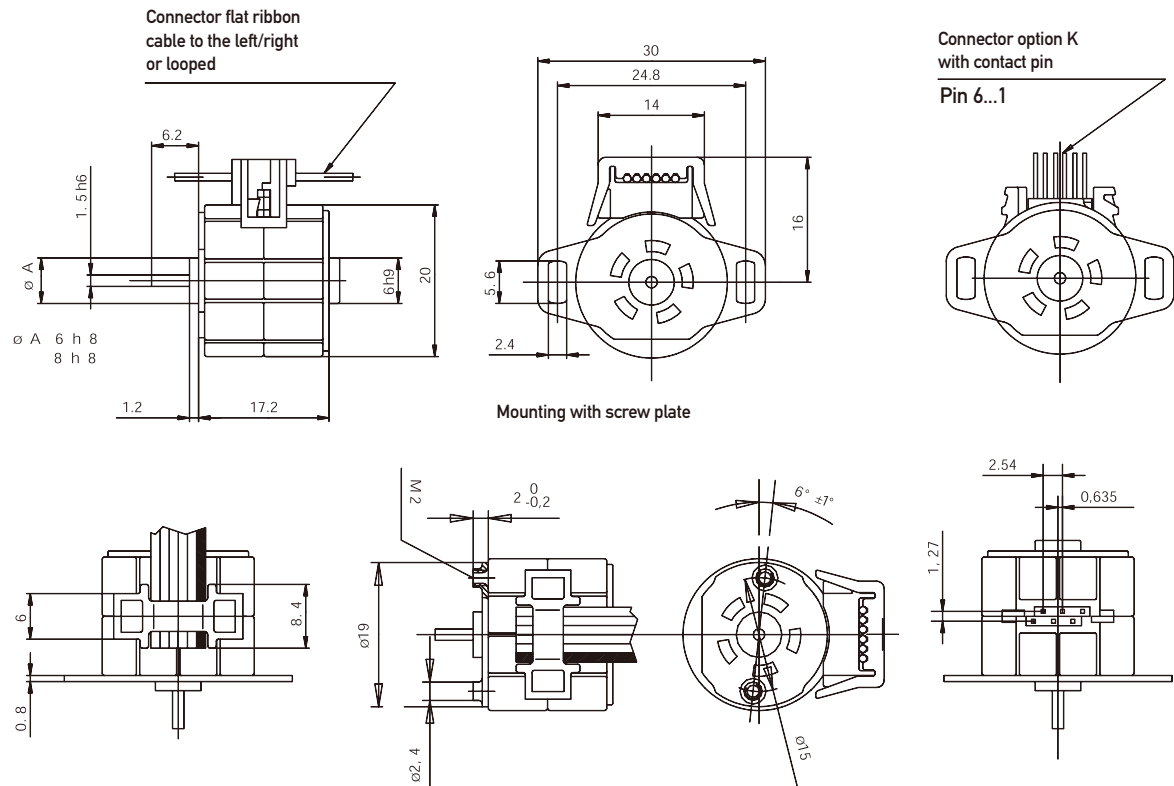
Capacitors	Rated voltage U_n	V	24	48
	Operation capacitor C_{50}	µF/VAC	2,2/40	0,68/80
	Operation capacitor C_{60}	µF/VAC	2,2/40	0,68/80

Circuit diagram Parallel circuit



6 = clockwise rotation
1 = counter clockwise rotation

Dimensions



UAT3

UAT3

Dimensions (mm) $\varnothing 20 \times 17,2$

Voltage (V) 24

Speed (rpm) 50 Hz 600
60 Hz 720

Pole number 10

Running torque (cNm) 50 Hz 0,32
60 Hz 0,3

Power output (W) 50 Hz 0,20
60 Hz 0,23

Gear combination on request



Standard Data

Climatic class	„wide-spread“ according to DIN IEC 60721-2-1
Ambient temperature operation	°C -20 ... +60
Ambient temperature storage	°C -40 ... +100
Thermal resistance at f=0 R _{therm}	47 K/W
Thermal class	„B“ according to DIN EN 60085
Approval	standard
Mounting	any position
Electrical connection	lead wires
Protection	IP 40 according to DIN EN 60529
Weight	22 g
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	sintered bronze, self-lubricating

Order Reference

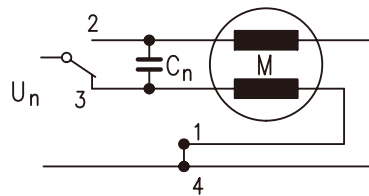
Type	Synchronous Motor	UAT3	3	N	24 V/50 Hz	R	E
Rotor shaft, mounting	3 centring 8 mm, mounting plate with long holes 5 centring 8 mm, mounting plate (for clipping) E centring 6 mm, mounting plate with long holes G centring 6 mm, mounting plate (for clipping)						
Approval	N Approval Standard						
Voltage/Frequency	See next page						
Direction	reversible						
Cable	E cable 150 mm with Tyco connector CT 173977-4 (other on request)						

UAT3 Synchronous Motors

Technical Data

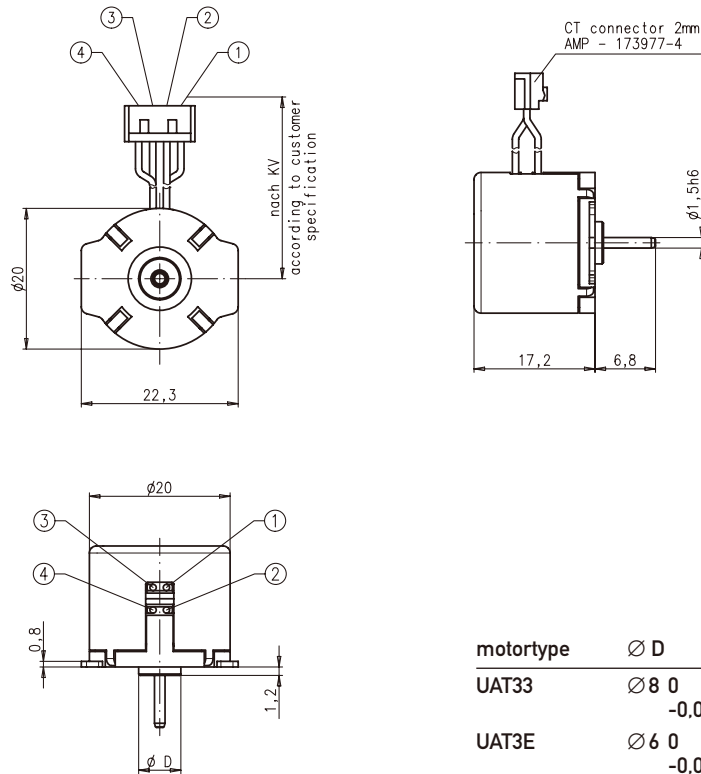
Rated frequency	Hz	50	60
Speed n	rpm	600	720
Power consumption	W	1,4	1,4
Power output	W	0,20	0,23
Running torque	cNm	0,32	0,30
Rotor inertia J_R	gcm ²	0,26	
Detent torque M_s	mNm	> 0,6	
Tolerance of voltage		standard power supply system + 10% / - 10%	
Duty cycle		100%	
Winding temperature T_{max}	°C	130	
Direction of rotation		reversible	
Capacitors			
Rated voltage U_N	V	24	
Operation capacitor C_{50}	µF/VAC	3,3/40	
Operation capacitor C_{60}	µF/VAC	2,7/40	

Circuit diagram Parallel circuit



switch to
 2 = clockwise rotation
 3 = counter clockwise rotation

Dimensions



motortype	ϕD
UAT33	$\phi 8 \ 0$ -0,05
UAT3E	$\phi 6 \ 0$ -0,05

UCM1/7

Dimensions (mm) $\varnothing 28 \times 24$

Voltage (V) * 12–230

Speed (rpm) 50 Hz 250

Pole number 24

Running torque **
(cNm) 50 Hz 1,2–1,3
60 Hz 1,2–1,3

Power output (W) **
50 Hz 0,31–0,34
60 Hz 0,38–0,41

Gear combination on request



* regard circuit diagram and connector type

** values for lead wire version (connection N) / connector versions up to 15 % higher

Standard Data

Climatic class	„wide-spread“ according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15 ... +60
Ambient temperature storage	°C -20 ... +100
Thermal resistance at f=0 R _{therm}	29 K/W
Thermal class	B according to DIN EN 60085
Approval	standard
Mounting	any position
Electrical connection	connector type D or N
Protection	IP 30 according to DIN EN 60529
Weight	54 g
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	Sintered bronze, self-lubricating

Order Reference

Type	Synchronous Motor	UCM	1	0	N	24 V / 50 Hz	R	D
Configuration	1 standard magnet 7 stronger magnet							
Rotor shaft, mounting	3 centring 8 mm, shaft 2.0 mm, screw plate 4 centring 8 mm, shaft 1.5 mm, screw plate 0 centring 8 mm, shaft 2.0 mm, clip 1 centring 8 mm, shaft 1.5 mm, clip	E centring 10 mm, shaft 2.0 mm, screw plate K centring 10 mm, shaft 1.5 mm, screw plate A centring 10 mm, shaft 2.0 mm, clip C centring 10 mm, shaft 1.5 mm, clip						
Approval	N Approval Standard							
Voltage/Frequency	see next pages							
Direction	R reversible							
Connection	D see next pages „Connection Types“ N							

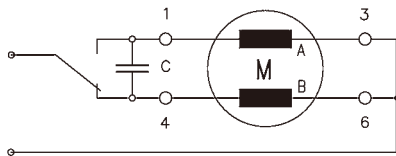
Technical Data

			UCM 1	UCM 1	UCM 5	UCM 5
bipolar	Rated frequency	Hz	50	60	50	60
	Speed n	rpm	250	300	250	300
	Running torque *	cNm	1.2	1.2	1.3	1.3
	Detent torque M_S	cNm	0.18	0.18	0.36	0.36
	Power output *	W	0.31	0.38	0.34	0.41
	Power consumption	VA	2.2	2.2	2.2	2.2
	Rotor inertia J_R	gcm ²	2.2	2.2	2.4	2.4
	Tolerance of voltage		standard power supply system +10%/-10%			
	Duty cycle		100%			
	Winding temperature T_{max}	°C	130			
Direction of rotation		reversible				

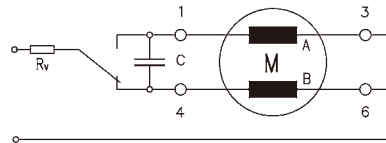
			12	24	110
Capacitors	Rated voltage U_N	V	12	24	110
	Operating capacitor C_{50}	$\mu F/V\sim$	18/20	4,7/40	0,33/200

* values for lead wire version (connection N) / connector versions up to 15 % higher

Circuit diagram Parallel circuit 12 V, 24 V, 48 V, 110 V



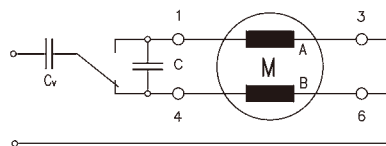
Parallel circuit 230 V (only for connector N) with 110 V motor and resistor R_V



switch to

- 1 clockwise rotation
- 4 counter clockwise rotation
- 6 counter clockwise rotation (for series circuit)

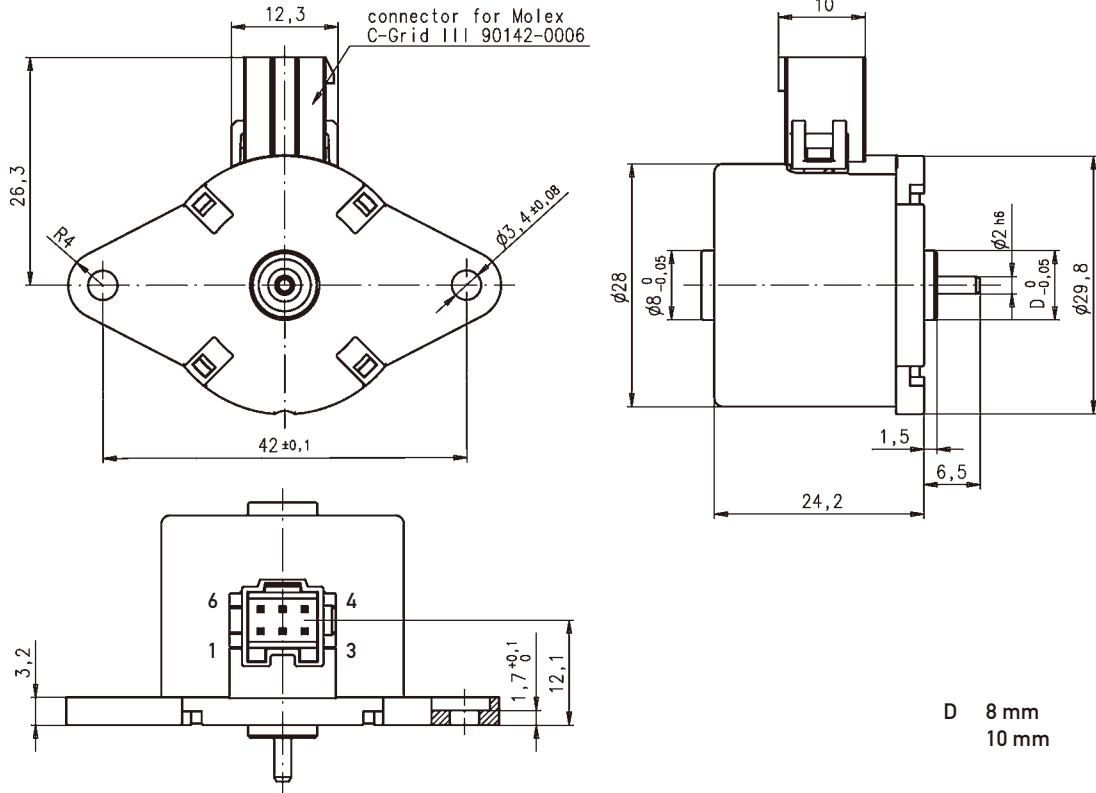
Parallel circuit 230 V (only for connector N) with 110 V motor and capacitor C_V



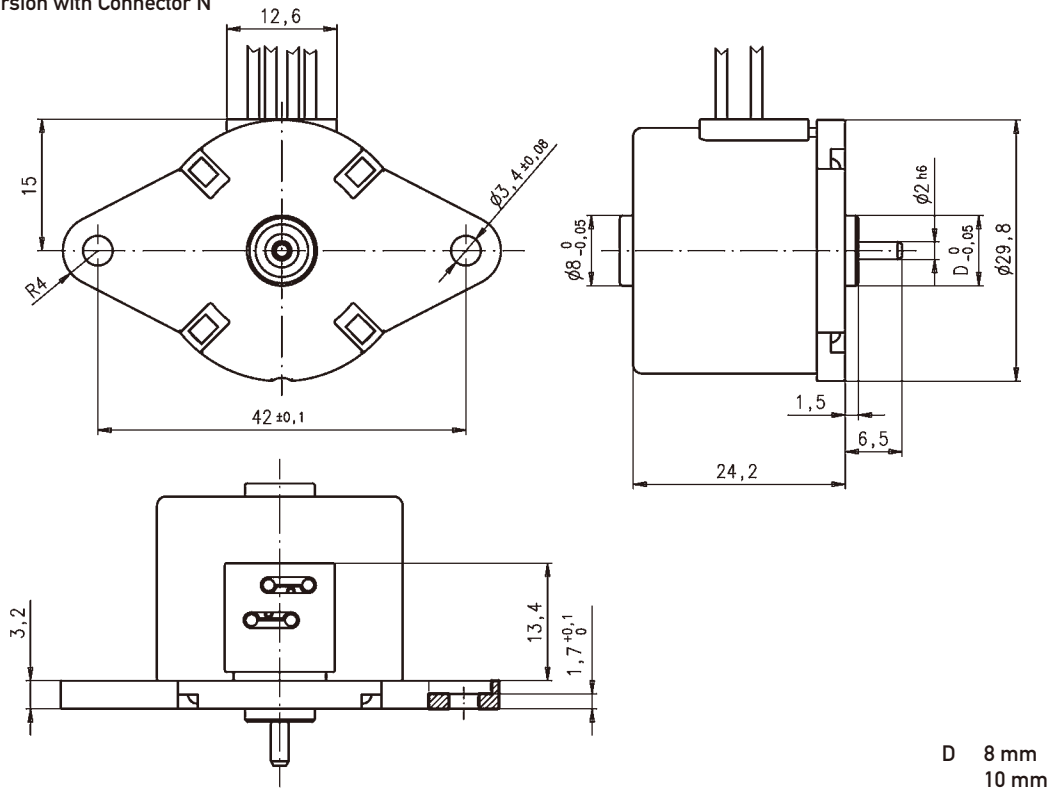
Series resistor $R_V = 5,6 \text{ k}\Omega, 3 \text{ W}$

Series capacitor $C_V = 0,33 \text{ }\mu\text{F}, 250 \text{ VAC}$

Dimensions Version with Connector D



Version with Connector N



UCR1/7

Dimensions (mm)	∅ 28 x 24
Voltage (V) *	12-230
Speed (rpm) 50 Hz	500
Pole number	12
Running torque ** (cNm) 50 Hz	0,8-1,1
60 Hz	0,8-1,1
Power output (W) ** 50 Hz	0,42-0,58
60 Hz	0,50-0,69
Gear combination	on request



* regard circuit diagram and connector type
 ** values for lead wire version (connection N) / connector versions up to 15 % higher

Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15 ... +60
Ambient temperature storage	°C -20 ... +100
Thermal resistance at f=0 R _{therm}	29 K/W
Thermal class	B according to DIN EN 60085
Approval	standard
Mounting	any position
Electrical connection	connector type D or N
Protection	IP 30 according to DIN EN 60529
Weight	54 g
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	Sintered bronze, self- lubricating

Order Reference

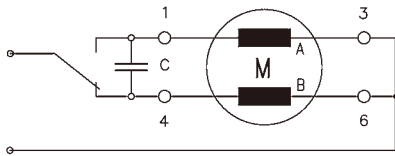
Type	Synchronous Motor		UCR	1	0	N	24 V / 50 Hz	R	D
Configuration	1	standard magnet							
	7	stronger magnet							
Rotor shaft mounting	3	centring 8 mm, shaft 2,0 mm, screw plate	E	centring 10 mm, shaft 2,0 mm, screw plate					
	4	centring 8 mm, shaft 1,5 mm, screw plate	K	centring 10 mm, shaft 1,5 mm, screw plate					
	0	centring 8 mm, shaft 2,0 mm, clip	A	centring 10 mm, shaft 2,0 mm, clip					
	1	centring 8 mm, shaft 1,5 mm, clip	C	centring 10 mm, shaft 1,5 mm, clip					
Approval	N	Approval Standard							
Voltage/Frequency	see next pages								
Direction	R	reversible							
Connection	D	see next pages „Connection Types“							
	N	Cable							

Technical Data

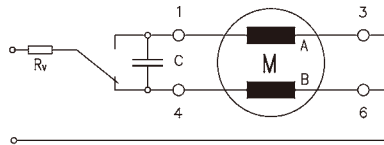
			UCR 1	UCR 1	UCR 5	UCR 5
bipolar	Rated frequency	Hz	50	60	50	60
	Speed n	rpm	500	600	500	600
	Running torque *	cNm	0,8	0,8	1,1	1,1
	Detent torque M_S	cNm	0,18	0,18	0,4	0,4
	Power output *	W	0,42	0,50	0,58	0,69
	Power consumption	VA	2,2	2,2	2,2	2,2
	Rotor inertia J_R	gcm ²	2,1	2,1	2,4	2,4
	Tolerance of voltage		standard power supply system +10%/-10%			
	Duty cycle		100%			
Winding temperature T_{max}	°C	130				
Direction of rotation		reversible				
Capacitors	Rated voltage U_N	V	12	24	110	
	Operating capacitor C_{50}	μF/V~	22/20	5,6/40	0,27/200	

* values for lead wire version (connection N) / connector versions up to 15 % higher

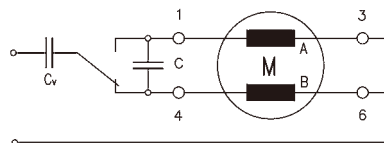
Circuit diagram Parallel circuit 12 V, 24 V, 48 V, 110 V



Parallel circuit 230 V (only for connector N) with 110 V motor and resistor R_V



Parallel circuit 230 V (only for connector N) with 110 V motor and capacitor C_V



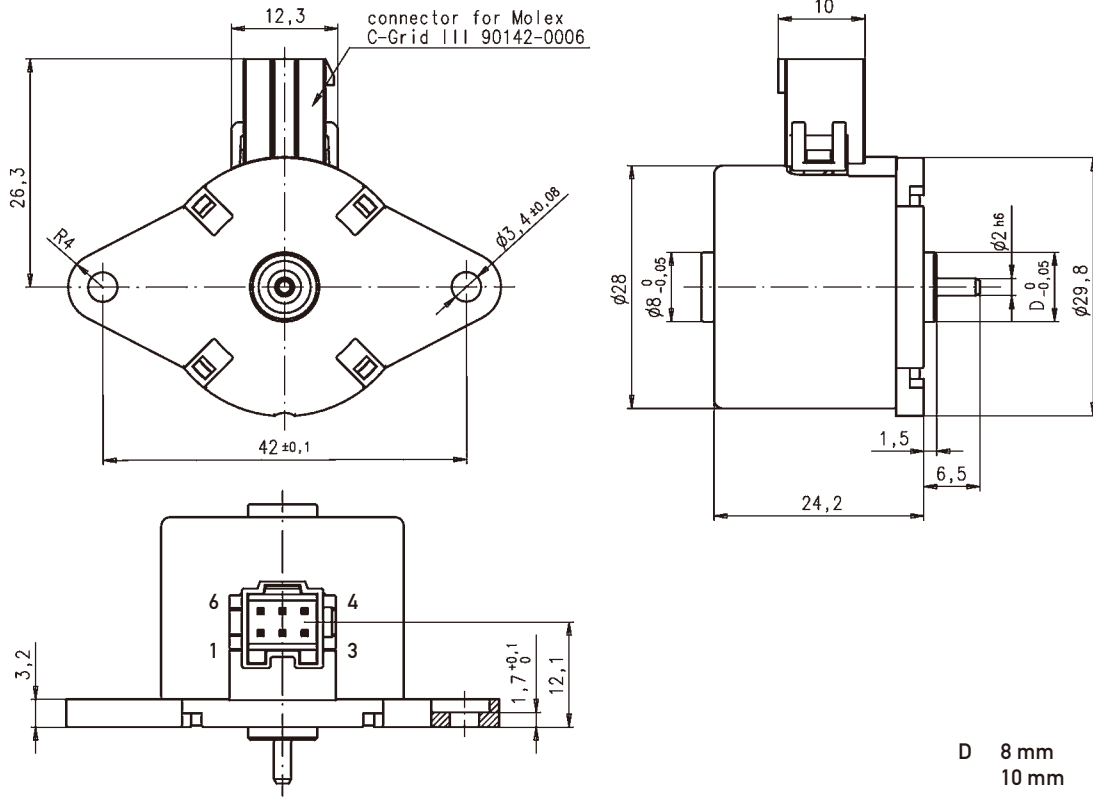
switch to

- 1 clockwise rotation
- 4 counter clockwise rotation
- 6 counter clockwise rotation (for series circuit)

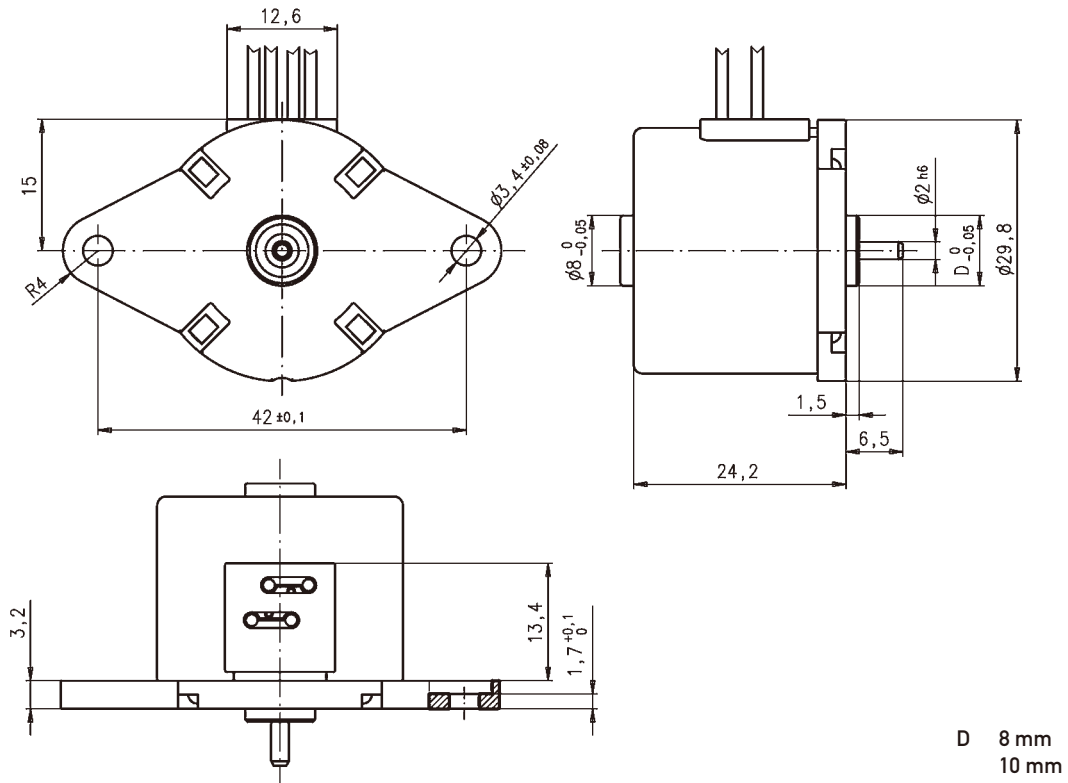
Series resistor $R_V = 5,6 \text{ k}\Omega, 3 \text{ W}$

Series capacitor $C_V = 0,33 \text{ }\mu\text{F}, 250 \text{ VAC}$

Dimensions Version with Connector D



Version with Connector N



UBR1

Dimensions (mm) \varnothing 36 x 21

Voltage (V) 12-230

Speed (rpm) 50 Hz 250
60 Hz 300

Pole number 24

Running torque (cNm) 50 Hz 0,9
60 Hz 0,9

Power output (W) 50 Hz 0,24
60 Hz 0,28

Gear combination A, D, M, B, F, V, J



Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15...+55
Ambient temperature storage	°C -20...+100
Thermal resistance at f=0 R _{therm}	27 K/W
Thermal class	A according to DIN EN 60085
Approval	standard (UL/CSA on request)
Mounting	any position
Electrical connection	cable
Protection	IP 40 according to DIN EN 60529
Weight	60 g
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	sintered bronze, self-lubricating
Electric strength	according to DIN EN 60034-1/DIN EN 60335-1

Order Reference

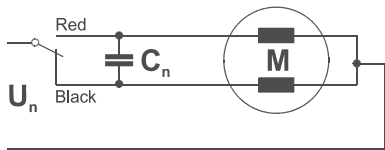
Type	Synchronous Motor		UBR1	0	N	24 V/50 Hz	R	E
Rotor shaft, mounting	0	centring 8 mm, shaft 2,0 mm, clip	A	centring 10 mm, shaft 2,0 mm, clip				
	1	centring 8 mm, shaft 1,5 mm, clip	C	centring 10 mm, shaft 1,5 mm, clip				
	3	centring 8 mm, shaft 2,0 mm, screw plate	E	centring 10 mm, shaft 2,0 mm, screw plate				
	4	centring 8 mm, shaft 1,5 mm, screw plate	K	centring 10 mm, shaft 1,5 mm, screw plate				
Approval	N	Approval Standard						
Voltage/Frequency	See next page							
Direction	reversible							
Cable	E	cable 150 mm (other on request)						

Technical Data

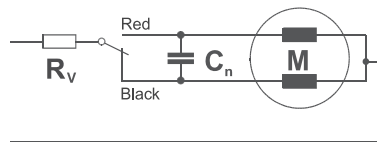
Rated frequency	Hz	50	60			
Speed n	rpm	250	300			
Power consumption	W	1,3	1,3			
Power output	W	0,24	0,28			
Running torque	cNm	0,9	0,9			
Rotor inertia J_R	gcm ²	2,8				
Detent torque M_s	cNm	0,22				
Tolerance of voltage		standard power supply system + 10% / - 10%				
Duty cycle		100%				
Winding temperature T_{max}	°C	105				
Direction of rotation		reversible				

Capacitors	Rated voltage U_N	V	12	24	48	110	230
	Operation capacitor C_{50}	μF/VAC	12/20	3,3/40	0,82/200	0,15/200	0,22/200
	Operation capacitor C_{60}	μF/VAC	12/20	3,3/40	0,82/200	0,15/200	0,12/200

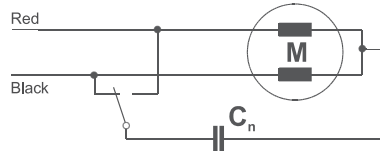
Circuit diagram Parallel circuit 12V, 24V, 48V, 110V



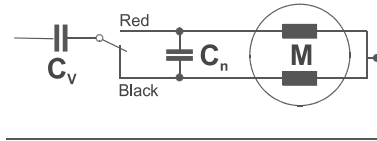
Parallel circuit 230V



Series circuit 230V

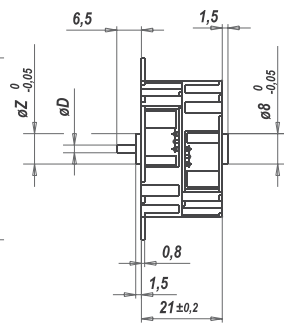
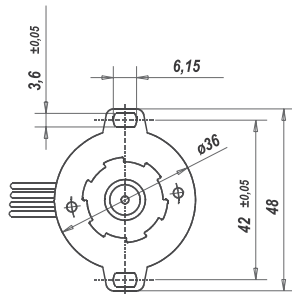


Parallel circuit 230V

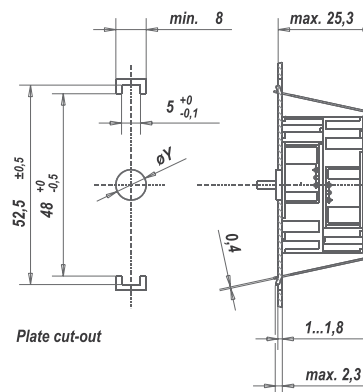


Red = clockwise rotation
Black = counter clockwise rotation

Dimensions Mounting with screw plate



Mounting with snap on clip



øD Rotor shaft

ø 2 h6

ø 1.5 js8

øZ øY

8 8F8

10 10F8

UBR2

Dimensions (mm)	∅ 36 x 21
Voltage (V)	12-230
Speed (rpm) 50 Hz	500
60 Hz	600
Pole number	12
Running torque (cNm) 50 Hz	0.75
60 Hz	0.72
Power output (W) 50 Hz	0.39
60 Hz	0.45
Gear combination	A, D, M, B, F, V, J



Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15...+55
Ambient temperature storage	°C -20...+100
Thermal resistance at f=0 R _{therm}	27 K/W
Thermal class	A according to DIN EN 60085
Approval	standard (UL/CSA on request)
Mounting	any position
Electrical connection	cable
Protection	IP 40 according to DIN EN 60529
Weight	60 g
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	sintered bronze, self-lubricating
Electric strength	according to DIN EN 60034-1/DIN EN 60335-1

Order Reference

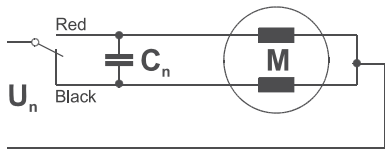
Type	Synchronous Motor	UBR2	0	N	24 V/50 Hz	R	E
Rotor shaft, mounting	0 centring 8 mm, shaft 2.0 mm, clip	A centring 10 mm, shaft 2.0 mm, clip					
	1 centring 8 mm, shaft 1.5 mm, clip	C centring 10 mm, shaft 1.5 mm, clip					
	3 centring 8 mm, shaft 2.0 mm, screw plate	E centring 10 mm, shaft 2.0 mm, screw plate					
	4 centring 8 mm, shaft 1.5 mm, screw plate	K centring 10 mm, shaft 1.5 mm, screw plate					
Approval	N Approval Standard						
Voltage/Frequency	See next page						
Direction	reversible						
Cable	E cable 150 mm (other on request)						

Technical Data

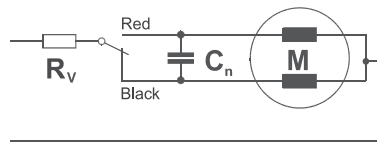
Rated frequency	Hz	50	60				
	Speed n	rpm	500	600			
	Power consumption	W	1,6	1,6			
	Power output	W	0,39	0,45			
	Running torque	cNm	0,75	0,72			
	Rotor inertia J_R	gcm ²	2,8				
	Detent torque M_s	cNm	0,25				
	Tolerance of voltage	standard power supply system + 10% / - 10%					
	Duty cycle	100%					
	Winding temperature T_{max}	°C	105				
Direction of rotation	reversible						

Capacitors	Rated voltage U_N	V	12	24	48	110	230
	Operation capacitor C_{50}	µF/VAC	15/20	3,9/40	1,0/70	0,18/170	0,27/170
	Operation capacitor C_{60}	µF/VAC	15/20	3,9/40	1,0/70	0,18/170	0,22/170

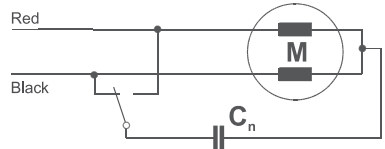
Circuit diagram Parallel circuit 12V, 24V, 48V, 110V



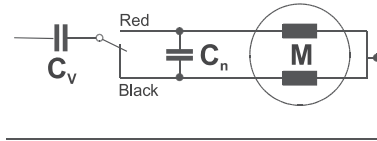
Parallel circuit 230V



Series circuit 230V

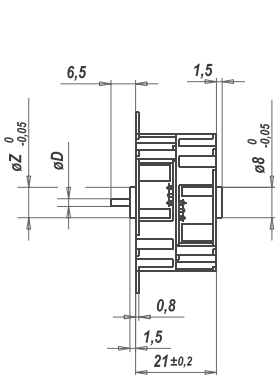
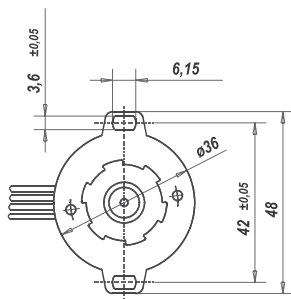


Parallel circuit 230V

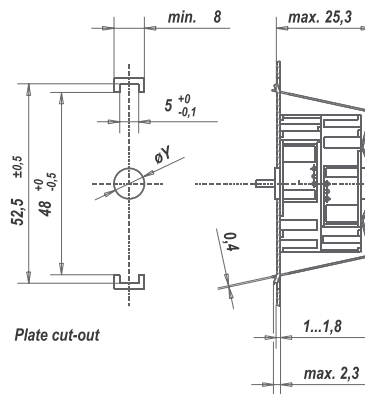


Red = clockwise rotation
Black = counter clockwise rotation

Dimensions Mounting with screw plate



Mounting with snap on clip



ØD Rotor shaft
Ø 2 h6
Ø 1.5 js8

ØZ ØY
8 8F8
10 10F8

UDR1

Dimensions (mm)	∅ 48 x 24
Voltage (V)	12-230
Speed (rpm) 50 Hz	500
60 Hz	600
Pole number	12
Running torque (cNm) 50 Hz	1,5
60 Hz	1,4
Power output (W) 50 Hz	0,77
60 Hz	0,87
Gear combination	A, D, M, B, F, V, J



Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15...+60
Ambient temperature storage	°C -20...+100
Thermal resistance at f=0 R _{therm}	18 K/W
Thermal class	A according to DIN EN 60085
Approval	standard/UL/CSA
Mounting	any position
Electrical connection	cabl
Protection	IP 40 according to DIN EN 60529
Weight	132 g
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	sintered bronze, self-lubricating
Electric strength	according to DIN EN 60034-1/DIN EN 60335-1

Order Reference

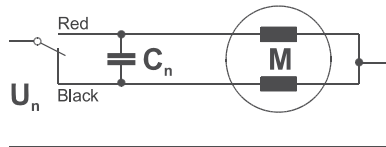
Type	Synchronous Motor	UDR1	0	N	24 V/50 Hz	R	N
Rotor shaft, mounting	0 centring 8 mm, shaft 1,5 mm, clip						
	1 centring 8 mm, shaft 2,0 mm, clip						
Approval	N Approval Standard						
	U Approval UL/CSA						
Voltage/Frequency	See next page						
Direction	reversible						
Cable	N cable 150 mm (other on request)						

Technical Data

Rated frequency	Hz	50	60				
	Speed n	rpm	500	600			
	Power consumption	W	2.1	2.2			
	Power output	W	0.77	0.87			
	Running torque	cNm	1.5	1.4			
	Rotor inertia J_R	gcm ²	6.3				
	Detent torque M_s	cNm	0.35				
	Tolerance of voltage	standard power supply system + 10% / - 10%					
	Duty cycle	100 %					
	Winding temperature T_{max}	°C	105				
Direction of rotation	reversible						

Capacitors	Rated voltage U_n	V	12	24	48	110	230
	Operation capacitor C_{50}	μF/VAC	27/20	6,8/40	1,5/100	0,27/200	0,068/350
	Operation capacitor C_{60}	μF/VAC	22/20	4,7/40	1,5/100	0,27/200	0,068/350

Circuit diagram Parallel circuit

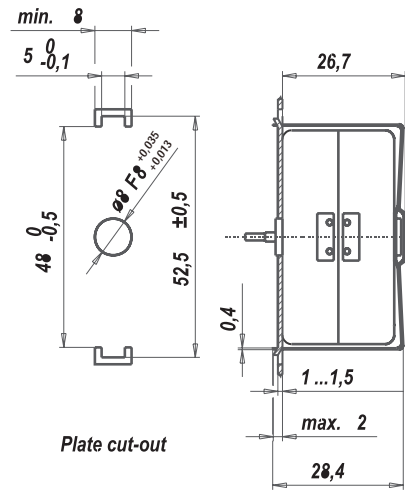
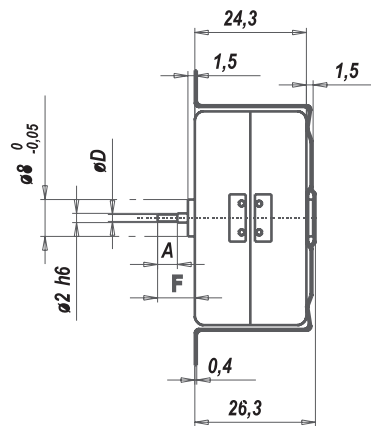
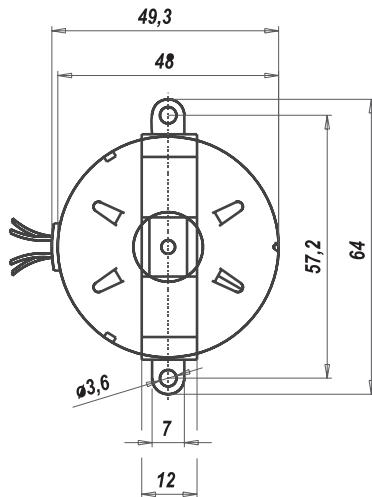


Red = clockwise rotation
Black = counter clockwise rotation

Dimensions

Mounting with screw clip

Mounting with snap-on clip



$\varnothing D$ Rotor shaft

$\varnothing 1.5 js8$ $\begin{matrix} +0,007 \\ -0,007 \end{matrix}$

$\varnothing 2 h6$ $\begin{matrix} 0 \\ -0,006 \end{matrix}$

Dimension A Dimension F

4,3 6,5

— 8,2

UDS1

Dimensions (mm) \varnothing 48 x 18,5

Voltage (V) 6–230

Speed (rpm) 50 Hz 500
60 Hz 600

Pole number 12

Running torque
(cNm) 50 Hz 0,9
60 Hz 0,8

Power output (W)
50 Hz 0,5
60 Hz 0,5

Gear combination A, D, M, B, F, V, J



Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15...+60
Ambient temperature storage	°C -20...+100
Thermal resistance at f=0 R _{therm}	17 K/W
Thermal class	A according to DIN EN 60085
Approval	standard/UL/CSA
Mounting	any position
Electrical connection	cable
Protection	IP 40 according to DIN EN 60529
Weight	102 g
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	plastic, self-lubricating
Electric strength	according to DIN EN 60034-1/DIN EN 60335-1

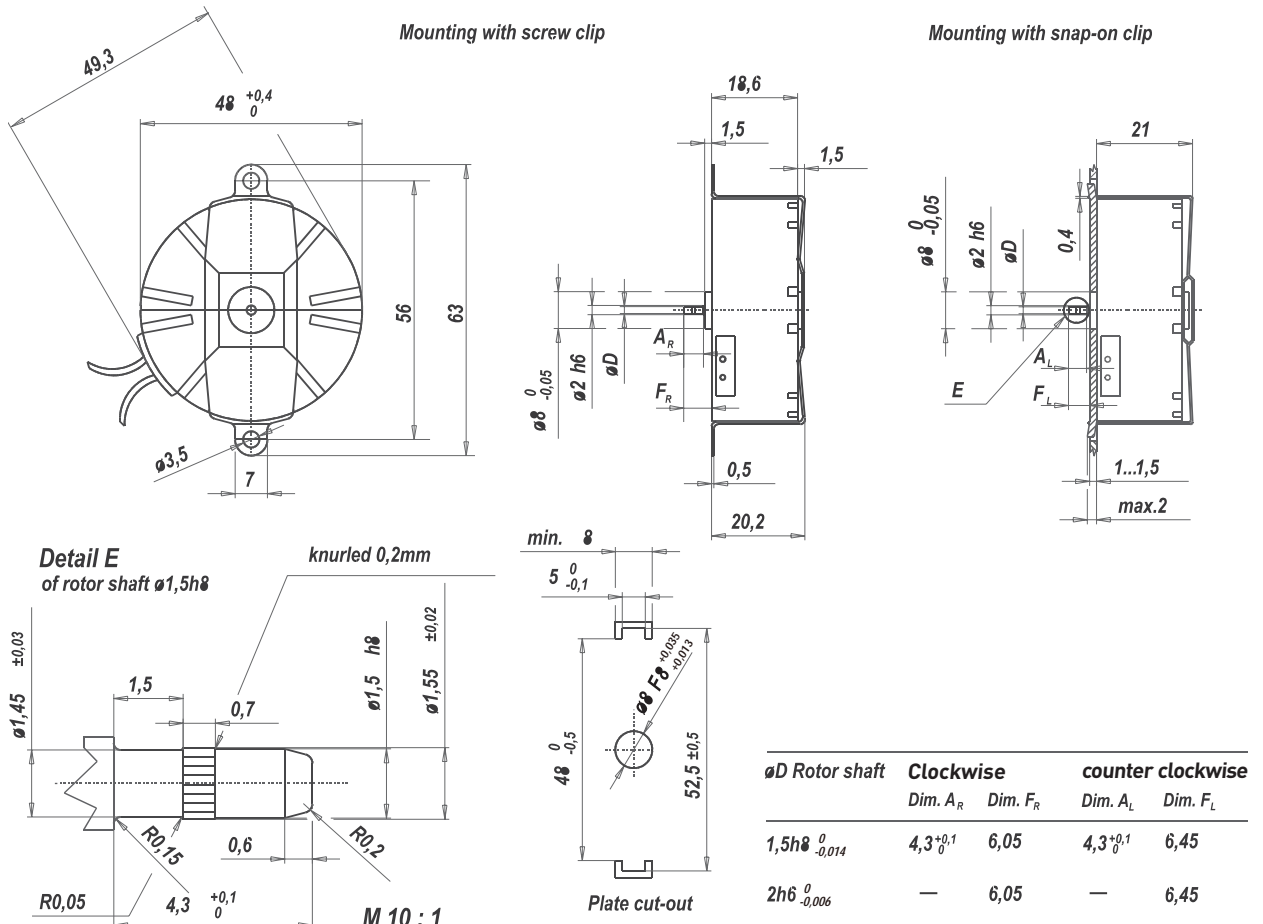
Order Reference

Type	Synchronous Motor	UDS1	0	N	24 V/50 Hz	R	N
Rotor shaft, mounting	0 centring 8 mm, shaft 1,5 mm, clip 1 centring 8 mm, shaft 2,0 mm, clip						
Approval	N Approval Standard U Approval UL/CSA						
Voltage/Frequency	See next page						
Direction	R clockwise rotation L Counter-clockwise rotation						
Cable	N cable 150 mm (other on request)						

Technical Data

Rated frequency	Hz	50	60
Speed n	rpm	500	600
Power consumption	W	2.4	1.8
Power output	W	0.5	0.5
Running torque	cNm	0.9	0.8
Rated voltage U_N	V	6, 12, 24, 48, 110, 230	
Rotor inertia J_R	gcm ²	11	
Detent torque M_s	cNm	0.27 (in direction of rotation)	
Tolerance of voltage		standard power supply system + 10% / - 10%	
Duty cycle		100 %	
Winding temperature T_{max}	°C	105	
Direction of rotation		clockwise or counter-clockwise	

Dimensions



U0 (SM5021; SM5022)

Dimensions (mm)	∅ 50 x 21
Voltage (V)	6–230
Speed (rpm) 50 Hz	250/375/500
60 Hz	300/450/600
Pole number	24/16/12
Running torque (cNm) 50 Hz	2,0–3,3 (SM5021); 3,3–7,5 (SM5022)
60 Hz	1,8–3 (SM5021); 4,5–7,0 (SM5022)
Power output (W) 50 Hz	0,65–2,75 (SM5021); 1,3–2,73 (SM5022)
60 Hz	0,78–3,0 (SM5021); 1,8–2,83 (SM5022)
Gear combination	VK4, O, P, R



Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15 ... +40
Ambient temperature storage	°C -20 ... +100
Thermal class	B (SM5021) ; A (SM5022) according to DIN EN 60085
Approval	standard
Mounting	any position
Electrical connection	cable
Protection	IP 30 according to DIN EN 60529
Weight	170 ... 180 g (SM5021); 180 ... 195 g (SM5022)
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	Sintered bronze, self- lubricating

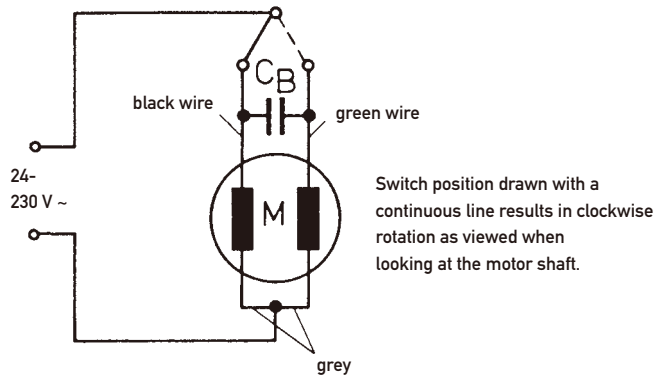
Order Reference

Type	Synchronous Motor	SM5021 R / SM5022 R	250	24 V	50 Hz
rpm	250 375 500				
Voltage	24 V 110 V 230 V				
Frequency	50 Hz 60 Hz 50/60 Hz				

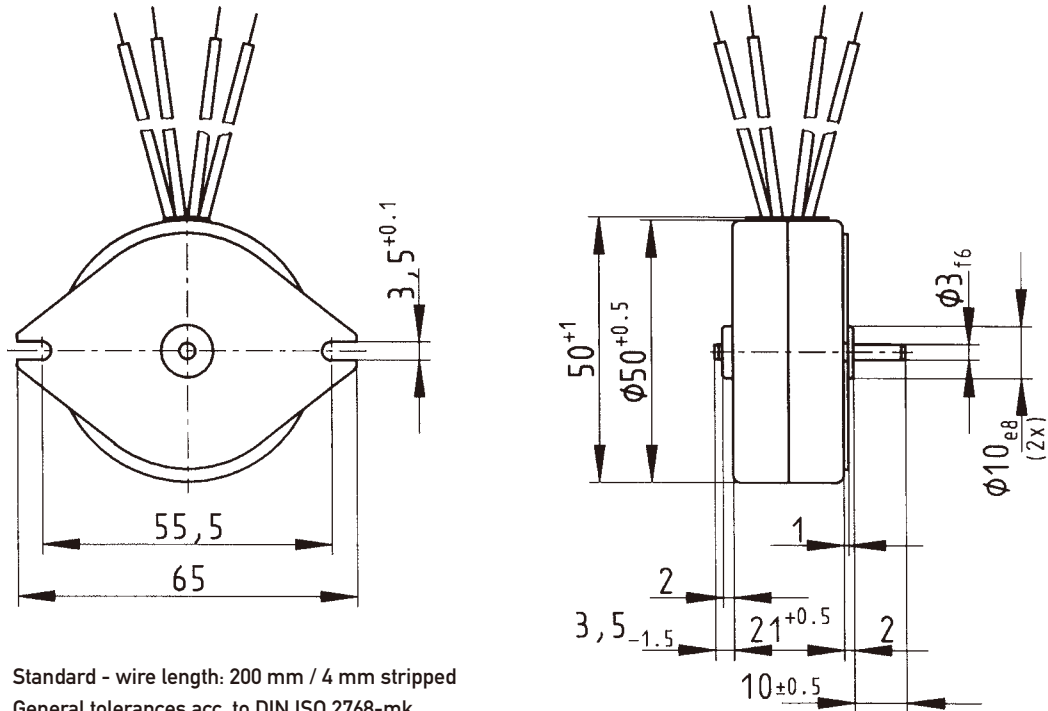
Technical Data

Motor type (SM5021)		R-250/1	R250/1	R-500/1	R-500/1	R-375/1	R-375/1	R-375/2	R-375/2
Rated frequency	Hz	50	60	50	60	50	60	50	60
Speed of rotation	rpm	250	300	500	600	375	450	375	450
Running torque M _n	cNm	2,5	2,5	2	1,8	2,3	2	3,3	3
Power output	W	0,65	0,78	1	1,1	0,9	0,95	1,3	1,4
Power consumption	VA	3,86	4,37	4,37	4,83	4,2	4,6	6	6,7
Nominal current at 230 V	mA	16,8	19	19	21	18,3	20	26	29
Max. permissible ext. inertia	gcm ²	30	10	10	10	15	10	10	10
Detent torque M _s	cNm	0,25	0,25	0,25	0,25	0,25	0,25	0,25	0,25
Winding temperature increase	K	55	60	63	70	60	65	80	85
Weight	g	180	180	170	170	180	180	180	180
Capacitors	at U _N : 24 V	μF/V~	10/63	10/63	10/63	10/63	10/63	15/63	15/63
	at U _N : 110 V	μF/V~	0,47/250	0,47/250	0,47/250	0,47/250	0,47/250	0,75/250	0,75/250
	at U _N : 230 V	μF/V~	0,12/500	0,12/500	0,12/500	0,12/500	0,12/500	0,18/500	0,18/500
Motor type (SM5022)		R-250/1	R-250/1	R-250/S2	R-250/S2	R-375/1	R-375/1	R-375/S2	R-375/S2
Rated frequency	Hz	50	60	50	60	50	60	50	60
Speed of rotation	rpm	250	300	250	300	375	450	375	450
Running torque M _n	cNm	6	5,7	7,5	7	4,7	4,5	7	6,5
Power output	W	1,57	1,8	2	2,2	1,85	2,1	2,7	3
Power consumption	VA	6,1	6,6	9	9,7	6,45	6,9	9,2	10,4
Nominal current at 230 V	mA	26,5	28,7	39,1	42,2	28	30	40	45
Max. permissible ext. inertia	gcm ²	50	20	60	30	60	40	20	40
Detent torque M _s	cNm	1	1	1	1	1	1	1	1
Winding temperature increase	K	85	90	60 (S2 10 min.)		85	90	60 (S2 10 min.)	
Weight	g	195	195	195	195	195	195	195	195
Capacitors	at U _N : 24 V	μF/V~	15/63	15/63	25/63	25/63	15/63	15/63	25/63
	at U _N : 110 V	μF/V~	0,75/250	0,75/250	1,2/250	1,2/250	0,75/250	0,75/250	1,2/250
	at U _N : 230 V	μF/V~	0,18/500	0,18/500	0,27/500	0,27/500	0,18/500	0,18/500	0,27/500
Motor type		R-500	R-500	R-500/S2	R-500/S2				
Rated frequency	Hz	50	60	50	60				
Speed of rotation	rpm	500	600	500	600				
Running torque M _n	cNm	3,7	3,2	5,2	4,5				
Power output	W	1,94	2	2,73	2,83				
Power consumption	VA	6,21	6,67	8,85	9,2				
Nominal current at 230 V	mA	27	29	38,5	40				
Max. permissible ext. inertia	gcm ²	35	15	45	25				
Detent torque M _s	cNm	1	1	1	1				
Winding temperature increase	K	85	90	55 (S2 10 min.)					
Weight	g	195	195	195	195				
Capacitors	at U _N : 24 V	μF/V~	15/63	15/63	25/63	25/63			
	at U _N : 110 V	μF/V~	0,75/250	0,75/250	1,2/250	1,2/250			
	at U _N : 230 V	μF/V~	0,18/500	0,18/500	0,27/500	0,27/500			

Circuit diagram Parallel circuit



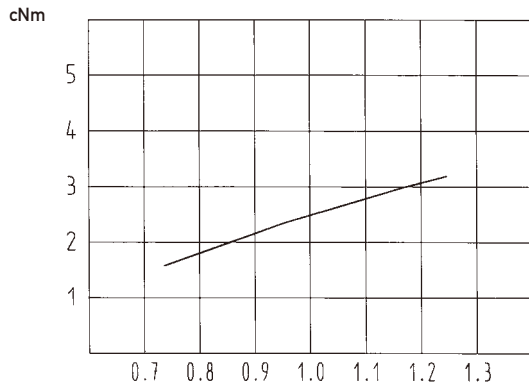
Dimensions



Standard - wire length: 200 mm / 4 mm stripped
General tolerances acc. to DIN ISO 2768-mk

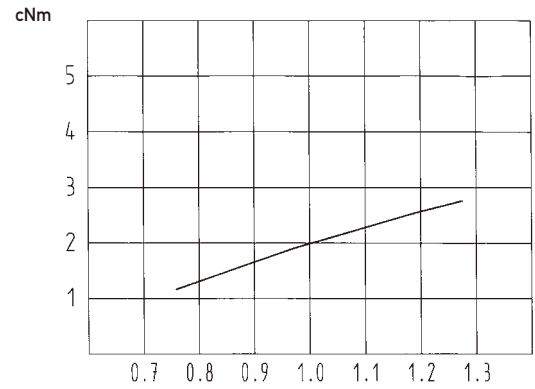
Chart: Torque versus voltage

UOM1 (SM 5021 R-250/1)



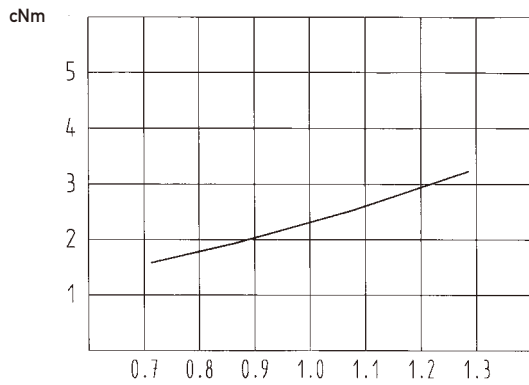
Supply voltage / Nominal voltage

UOR1 (SM 5021 R-500/1)



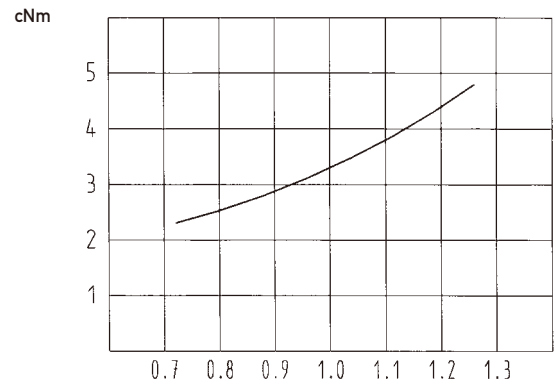
Supply voltage / Nominal voltage

UOU1 (SM 5021 R-375/1)



Supply voltage / Nominal voltage

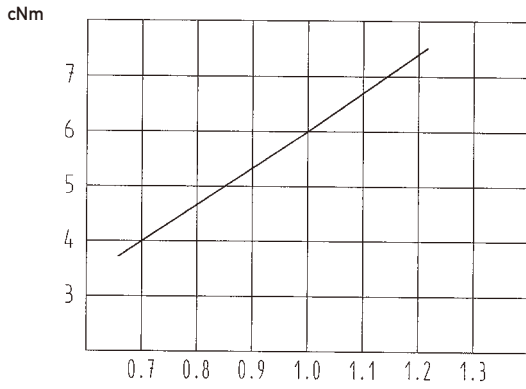
UOU1 (SM 5021 R-375/2)



Supply voltage / Nominal voltage

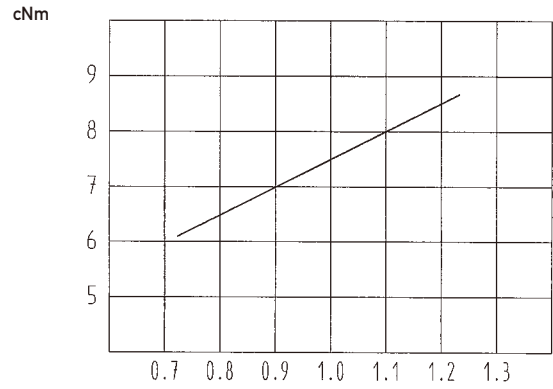
Chart: Torque versus voltage

UOM5 (SM 5022 R-250)



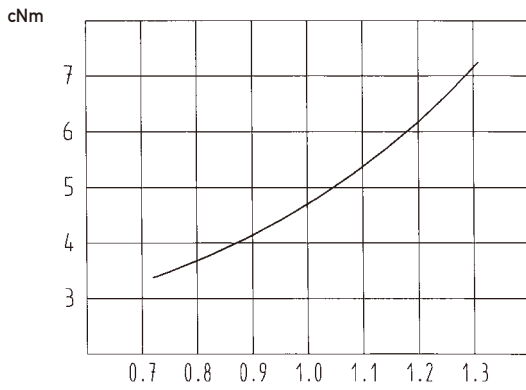
Supply voltage / Nominal voltage

UOM5 (SM 5022 R-250/S2)



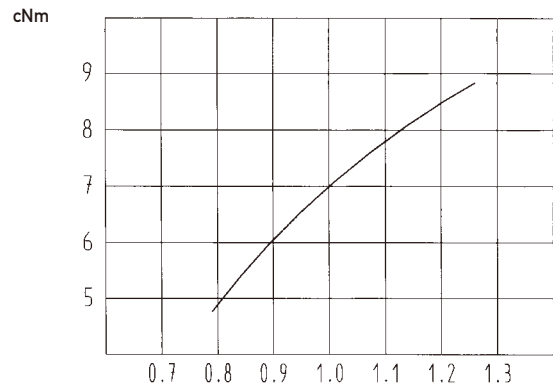
Supply voltage / Nominal voltage

UOU5 (SM 5022 R-375)



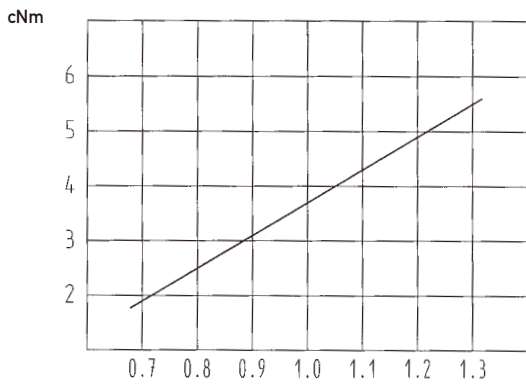
Supply voltage / Nominal voltage

UOU5 (SM 5022 R-375/S2)



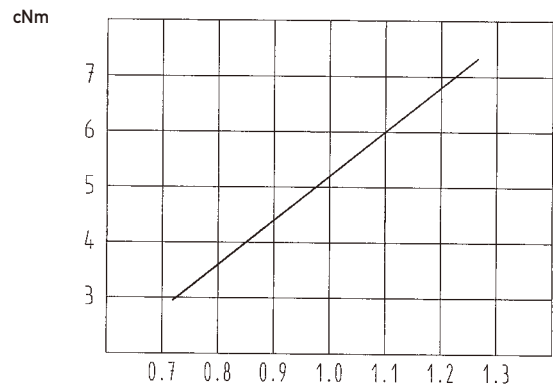
Supply voltage / Nominal voltage

UOR5 (SM 5022 R-500)



Supply voltage / Nominal voltage

UOR5 (SM 5022 R-500/S2)



Supply voltage / Nominal voltage

UFM1

Dimensions (mm)	∅ 52 x 28
Voltage (V)	12–230
Speed (rpm)	50 Hz 250 60 Hz 300
Pole number	24
Running torque (cNm)	50 Hz 3.8 60 Hz 3.5
Power output (W)	50 Hz 1 60 Hz 1.1
Gear combination	A, D, M, B, F, V, J, O



Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15...+55
Ambient temperature storage	°C -20...+100
Thermal resistance at f=0 R _{therm}	13 K/W
Thermal class	A according to DIN EN 60085
Approval	standard (UL/CSA on request)
Mounting	any position
Electrical connection	cable
Protection	IP 30 according to DIN EN 60529
Weight	180 g
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	sintered bronze, self-lubricating
Electric strength	according to DIN EN 60034-1/DIN EN 60335-1

Order Reference

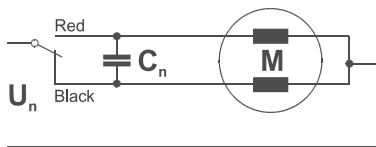
Type	Synchronous Motor	UFM1	0	N	24 V/50 Hz	R	N
Rotor shaft, mounting	0 centring 8 mm, shaft 3,0 mm, clip 1 centring 8 mm, shaft 2,0 mm, clip 2 centring 8 mm, shaft 1,5 mm, clip 3 centring 8 mm, shaft 3,0 mm, screw plate 4 centring 8 mm, shaft 2,0 mm, screw plate 5 centring 8 mm, shaft 1,5 mm, screw plate	E centring 10 mm, shaft 3,0 mm, screw plate K centring 10 mm, shaft 2,0 mm, screw plate M centring 10 mm, shaft 1,5 mm, screw plate					
Approval	N Approval Standard						
Voltage/Frequency	See next page						
Direction	reversible						
Cable	N cable 150 mm (other on request)						

Technical Data

Rated frequency	Hz	50	60			
Speed n	rpm	250	300			
Power consumption	W	4	3.1			
Power output	W	1	1.1			
Running torque	cNm	3.8	3.5			
Rotor inertia J_R	gcm ²	14.4				
Detent torque M_s	cNm	0.45				
Tolerance of voltage		standard power supply system + 10% / - 10%				
Duty cycle		100%				
Winding temperature T_{max}	°C	105				
Direction of rotation		reversible				

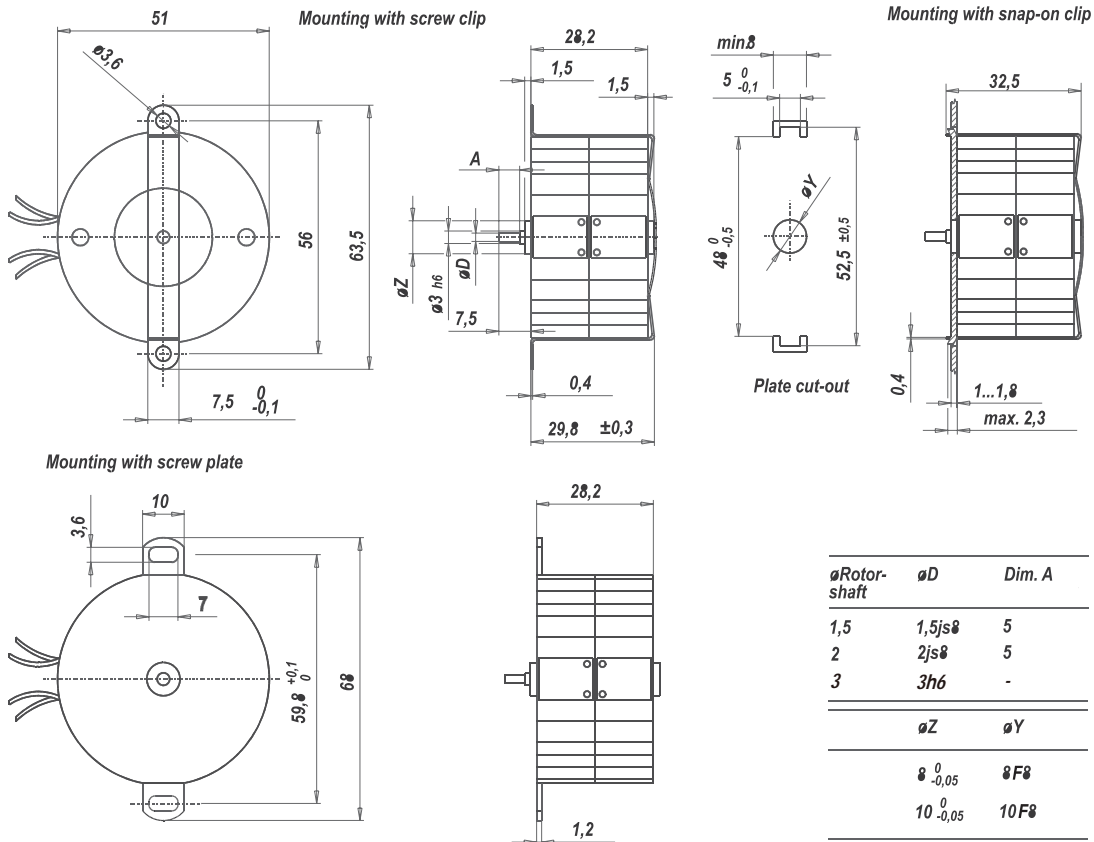
Capacitors	Rated voltage U_N	V	12	24	48	110	230
	Operation capacitor C_{50}	µF/VAC	39/24	10/45	2.2/90	0.39/240	0.1/440
	Operation capacitor C_{60}	µF/VAC	33/24	8.2/45	1.8/90	0.33/240	0.082/440

Circuit diagram Parallel circuit



Red = clockwise rotation
Black = counter clockwise rotation

Dimensions



UFR1/UFR3/UFR4

Dimensions (mm)	∅ 52 x 28 / ∅ 52 x 42 / ∅ 52 x 56
Voltage (V)	12–230
Speed (rpm) 50 Hz	500
60 Hz	600
Pole number	12
Running torque (cNm) 50 Hz	2,8 / 3,7 / 5,3
60 Hz	2,6 / 3,1 / 4,7
Power output (W) 50 Hz	1,5 / 1,9 / 2,8
60 Hz	1,6 / 2 / 3
Gear combination	A, D, M, B, F, V, J, O



Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15...+55
Ambient temperature storage	°C -20...+100
Thermal resistance at f=0 R _{therm}	11 K/W (UFR1), 7 K/W (UFR4)
Thermal class	A according to DIN EN 60085
Approval	standard (UL/CSA on request)
Mounting	any position
Electrical connection	cable
Protection	IP 30 according to DIN EN 60529
Weight	180 g (UFR1), 370 g (UFR4)
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	sintered bronze, self-lubricating
Electric strength	according to DIN EN 60034-1/DIN EN 60335-1

Order Reference

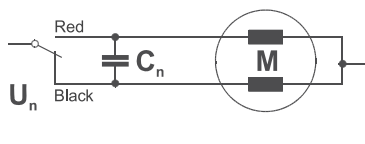
Type	Synchronous Motor	UFR	1	0	N	24 V/50 Hz	R	N
Configuration	1 Two coils 3 Three coils 4 Four coils							
Rotor shaft, mounting	0 centring 8 mm, shaft 3,0 mm, clip 1 centring 8 mm, shaft 2,0 mm, clip 2 centring 8 mm, shaft 1,5 mm, clip 3 centring 8 mm, shaft 3,0 mm, screw plate* 4 centring 8 mm, shaft 2,0 mm, screw plate* 5 centring 8 mm, shaft 1,5 mm, screw plate*	A centring 12 mm, shaft 3,0 mm, clip E centring 10 mm, shaft 3,0 mm, screw plate* K centring 10 mm, shaft 2,0 mm, screw plate* M centring 10 mm, shaft 1,5 mm, screw plate*						
Approval	N Approval Standard							
Voltage/Frequency	See next page							
Direction	reversible							
Cable	N cable 150 mm (other on request)							

* screw plate not for UFR3 and UFR4

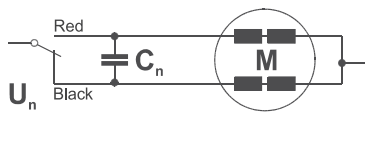
Technical Data

UFR1	Rated frequency	Hz	50	60		
	Speed n	rpm	500	600		
	Power output P_{mech}	W	1,5	1,6		
	Running torque M_n	cNm	2,8	2,6		
	Power consumption P_{el}	W	3,3	3,6		
	Detent torque M_s	cNm	0,46			
	Rotor inertia J_R	gcm ²	14,2			
Capacitors at Rated voltage U_n		V	24	48	110	230
Operation capacitor C_{50}		μF/VAC	10/45	2,7/90	0,47/200	0,12/400
Operation capacitor C_{60}		μF/VAC	8,2/45	2,2/90	0,39/200	0,10/400
UFR3	Rated frequency	Hz	50	60		
	Speed n	rpm	500	600		
	Power output P_{mech}	W	1,9	2		
	Running torque M_n	cNm	3,7	3,1		
	Power consumption P_{el}	W	6,1	5,1		
	Detent torque M_s	cNm	0,54			
	Rotor inertia J_R	gcm ²	17			
Capacitors at Rated voltage U_n		V	24	48	110	230
Operation capacitor C_{50}		μF/VAC	39/24	10/50	1,8/110	0,39/240
Operation capacitor C_{60}		μF/VAC	27/24	6,8/50	1,2/110	0,27/240
UFR4	Rated frequency	Hz	50	60		
	Speed n	rpm	500	600		
	Power output P_{mech}	W	2,8	3		
	Running torque M_n	cNm	5,3	4,7		
	Power consumption P_{el}	W	6,4	6,9		
	Detent torque M_s	cNm	0,8			
	Rotor inertia J_R	gcm ²	24,2			
Capacitors at Rated voltage U_n		V	24	48	110	230
Operation capacitor C_{50}		μF/VAC	18/45	4,7/90	0,82/200	0,22/440
Operation capacitor C_{60}		μF/VAC	15/45	3,9/90	0,68/200	0,18/440
Tolerance of voltage		standard power supply system + 10% ... - 10%				
Winding temperature T_{max}		105°C				
Duty cycle		100%				
Direction of rotation		reversible				

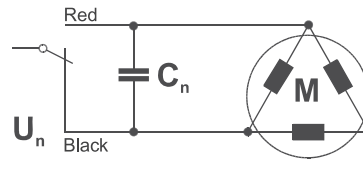
Circuit diagram UFR1 Parallel circuit



UFR4 Parallel circuit



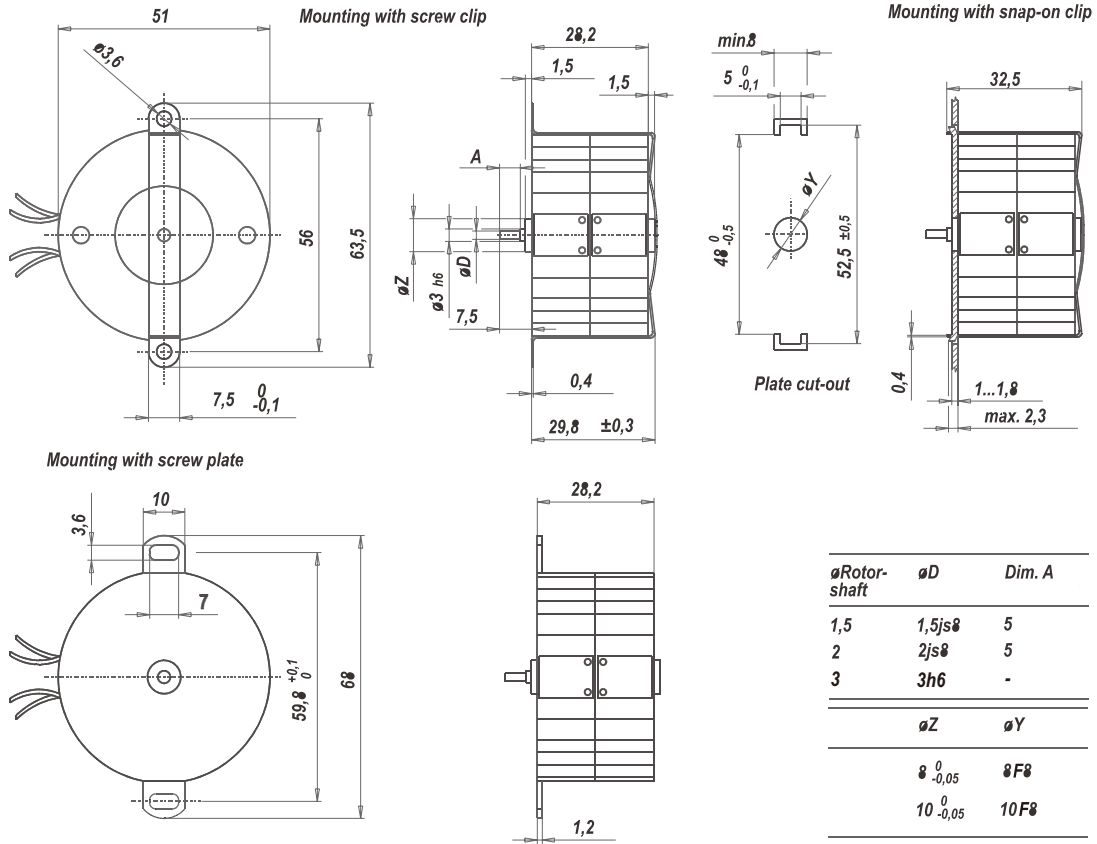
UFR3 Parallel circuit



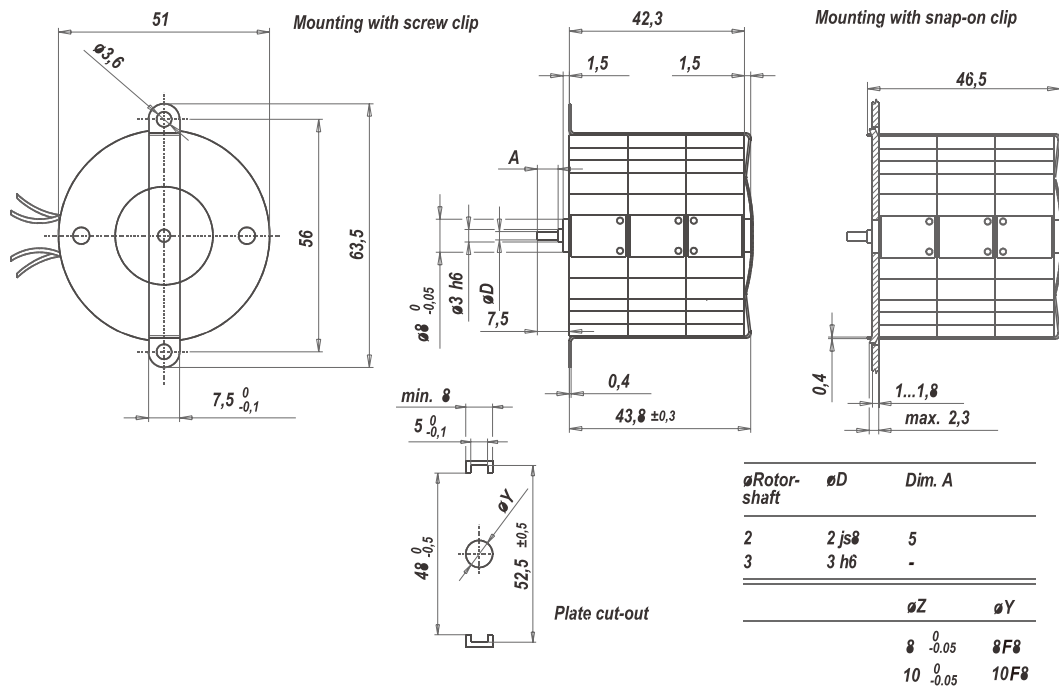
Red = clockwise rotation
Black = counter clockwise rotation

Dimensions

UFR1

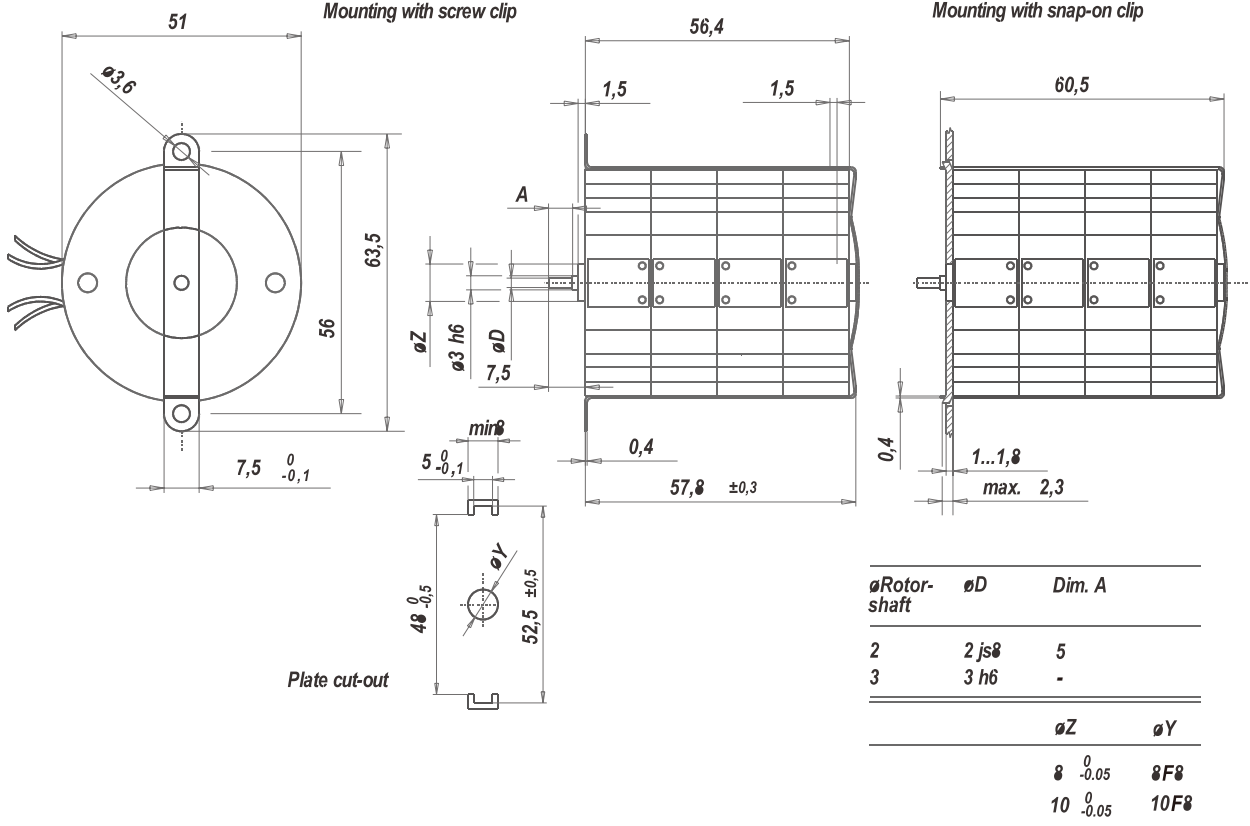


UFR3



Dimensions

UFR4



UHM1/5; UHM4/8

Dimensions (mm) $\varnothing 59 \times 35 / \varnothing 59 \times 70$

Voltage (V) 12–230

Speed (rpm) 50 Hz 250
60 Hz 300

Pole number 24

Running torque (cNm)
50 Hz 8.5–15
60 Hz 6.6–9.5

Power output (W)
50 Hz 2.2–3.9
60 Hz 2.1–3

Gear combination J



Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	-15 ... +55° C
Ambient temperature storage	-20 ... +100° C
Thermal resistance at f=0 (R_{therm})	10 (UHM 1/5), 6.5 (UHM 4/8) K/W
Thermal class	A according to DIN EN 60085 (B on request)
Approval	standard (UL / CSA on request)
Mounting	any position
Electrical connection	cable
Protection	IP 30 according to DIN EN 60529
Weight (g)	300 (UHM1/5), 580 (UHM4/8)
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	sintered bronze, self-lubricating
Electric strength	according to DIN EN 60034-1/DIN EN 60335-1

Order Reference

Type	Synchronous Motor		UHM	1	0	N	12V/50Hz	R	N
Configuration	1	two coils, standard magnet	4	four coils, standard magnet					
	5	two coils, stronger magnet	8	four coils, stronger magnet					
Rotor shaft mounting	0	centring 12 mm, shaft 6.35 mm, clip **	3	centring 12 mm, shaft 6.35 mm, screw plate *					
	1	centring 12 mm, shaft 4.0 mm, clip **	4	centring 12 mm, shaft 4.0 mm, screw plate *					
	2	centring 12 mm, shaft 3.0 mm, clip **	5	centring 12 mm, shaft 3.0 mm, screw plate *					
Approval	N	Approval Standard							
Voltage/Frequency	See next page								
Direction	reversible								
Cable	N	cable 150 mm (other on request)							

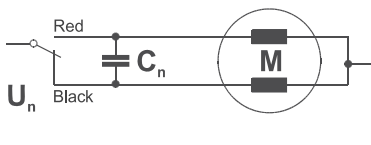
* not for UHM4/8

** not for UHM1/2

Technical Data

UHM1/5	Rated frequency	Hz	50			60	
	Speed n	rpm	250			300	
	Power output P_{mech}	W	2.2 (UHM 1); 2.5 (UHM 5)			2.1 (UHM 1)	
	Running torque M_n	cNm	8.5 (UHM 1); 9.5 (UHM 5)			6.6 (UHM 1)	
	Power consumption P_{el}	W	5			4.5	
	Detent torque M_s	cNm	1.3 (UHM1); 2.1 (UHM5)				
	Rotor inertia J_R	gcm ²	49 (UHM1); 56 (UHM5)				
Capacitors at Rated voltage U_n		V	12	24	48	110	230
Operation capacitor C_{50} UHM1/5		μF/VAC	56/24	15/50	3.9/100	0.68/220	0.18/440
Operation capacitor C_{60} UHM1/5		μF/VAC	39/24	10/50	2.7/100	0.47/220	0.12/440
UHM4/8	Rated frequency	Hz	50			60	
	Speed n	rpm	250			300	
	Power output P_{mech}	W	3.9 (UHM4); 3.9 (UHM8)			3.0 (UHM4)	
	Running torque M_n	cNm	15 (UHM4)			9.5 (UHM4); 14.7 (UHM8)	
	Power consumption P_{el}	W	10 (UHM4)			9.0 (UHM4)	
	Detent torque M_s	cNm	3.4 (UHM4); 5.3 (UHM8)				
	Rotor inertia J_R	gcm ²	135 (UHM4); 141 (UHM8)				
Capacitors at Rated voltage U_n		V	12	24	48	110	230
Operation capacitor C_{50} UHM4/8		μF/VAC	100/24	27/50	6.8/100	1.2/220	0.33/440
Operation capacitor C_{60} UHM4/8		μF/VAC	47/24	15/50	4.7/100	0.82/220	0.15/440
Tolerance of voltage		standard power supply system + 10% ... -10%					
Winding temperature T_{max}		105°C					
Duty cycle		100%					
Direction of rotation		reversible					

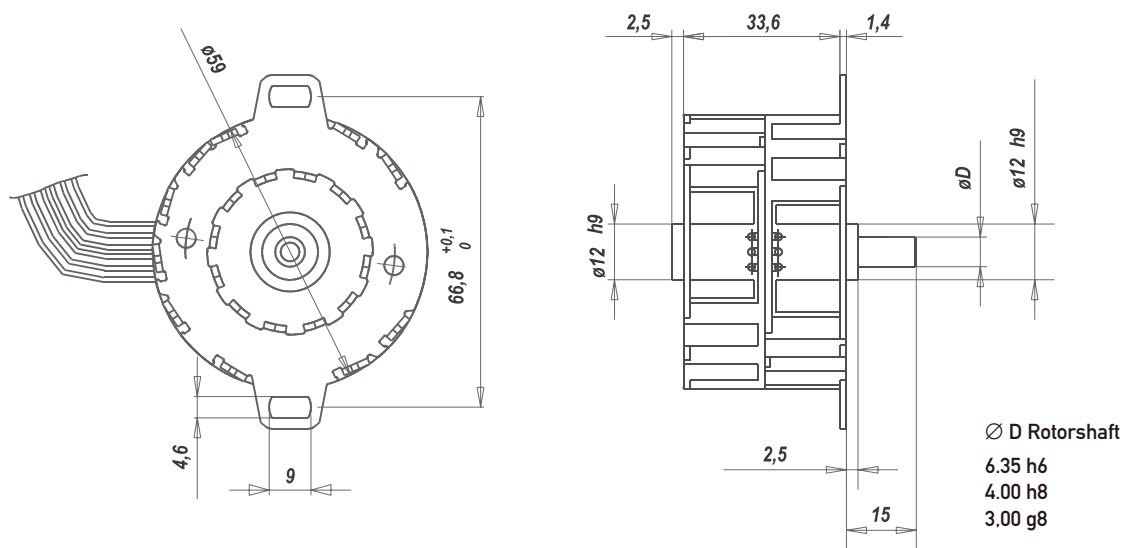
Circuit diagram Parallel circuit



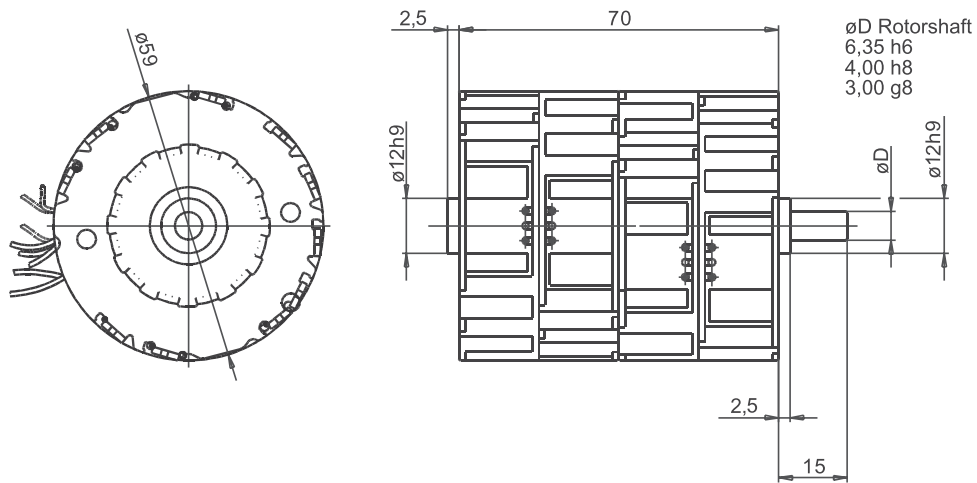
Red = clockwise rotation
Black = counter clockwise rotation

Dimensions

UHM1/5



UHM4/8



UP (SM6443; SM6444)

Dimensions (mm)	∅ 64 x 34
Voltage (V)	12–230
Speed (rpm) 50 Hz	250/375 (SM6443); 375 (SM6444)
60 Hz	300/450 (SM6443); 450 (SM6444)
Pole number	24/16 (SM6443); 16 (SM6444)
Running torque (cNm) 50 Hz	10,3–18,5 (SM6443); 28–35 (SM6444)
60 Hz	8,5–17 (SM6443); 21–30 (SM6444)
Power output (W) 50 Hz	3,5–7,3 (SM6443); 11–13,8 (SM6444)
60 Hz	3,9–8,0 (SM6443); 9,9–14,2 (SM6444)
Gear combination	O, P, R



Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15 ... +40
Ambient temperature storage	°C -20 ... +100
Thermal class	B (SM6443) ; A (SM6444) according to DIN EN 60085
Approval	standard
Mounting	any position
Electrical connection	cable
Protection	IP 30 according to DIN EN 60529
Weight	500 g (SM6443); 550 g (SM6444)
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	Sintered bronze, self- lubricating

Order Reference

Type	Synchronous Motor	SM6443 R / SM6444	250	24 V	50 Hz
rpm	250 (SM6443 R) 375 (SM6443 R / SM6444 R)				
Voltage	24 V 110 V 230 V				
Frequency	50 Hz 60 Hz 50/60 Hz				

Technical Data

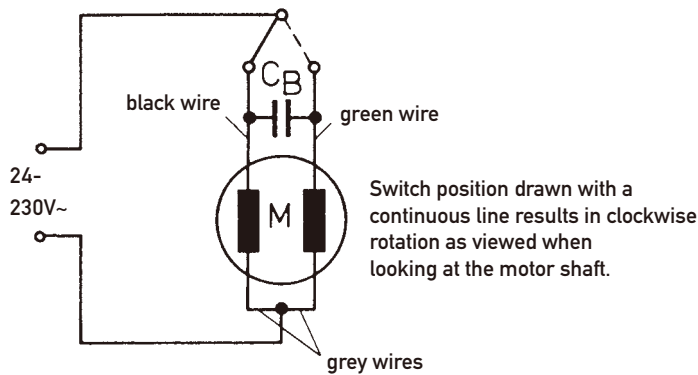
Motor type (SM6443)		R-250/1	R-250/1	R-375/1	R-375/1	R-375/2	R-375/2	R-375/S2/1	R-375/S2/1
Rated frequency	Hz	50	60	50	60	50	60	50	60
Speed	rpm	250	300	375	450	375	450	375	450
Running torque M_N	cNm	13,5	12,5	12	10,5	10,5	8,5	18,5	17
Power output	W	3,54	3,94	4,7	4,95	4,13	4	7,3	8
Power consumption	VA	10,3	11,3	11,7	12,65	9,55	9,7	18	21
Nominal current at 230 V	mA	44,5	49	51	55	41,5	42	78,2	91,3
Max. permissible ext. inertia	gcm ²	200	130	100	50	80	40	130	60
Detent torque M_S	cNm	2,5	2,5	1,8	1,8	1,8	1,8	2	2
Winding temperature increase	K	85	90	95	100	80	80	90 (S2 60 min.)	
Weight	g	500	500	500	500	500	500	500	500

Capacitors	at U_N : 24 V	$\mu\text{F}/V\sim$	25,8/63	25,8/63	30/63	30/63	25,8/63	25,8/63	47/63	47/63
	at U_N : 110 V	$\mu\text{F}/V\sim$	1,3/250	1,3/250	1,3/250	1,3/250	1,3/250	1,3/250	2,2/250	2,2/250
	at U_N : 230 V	$\mu\text{F}/V\sim$	0,27/500	0,27/500	0,33/500	0,33/500	0,27/500	0,27/500	0,47/500	0,47/500

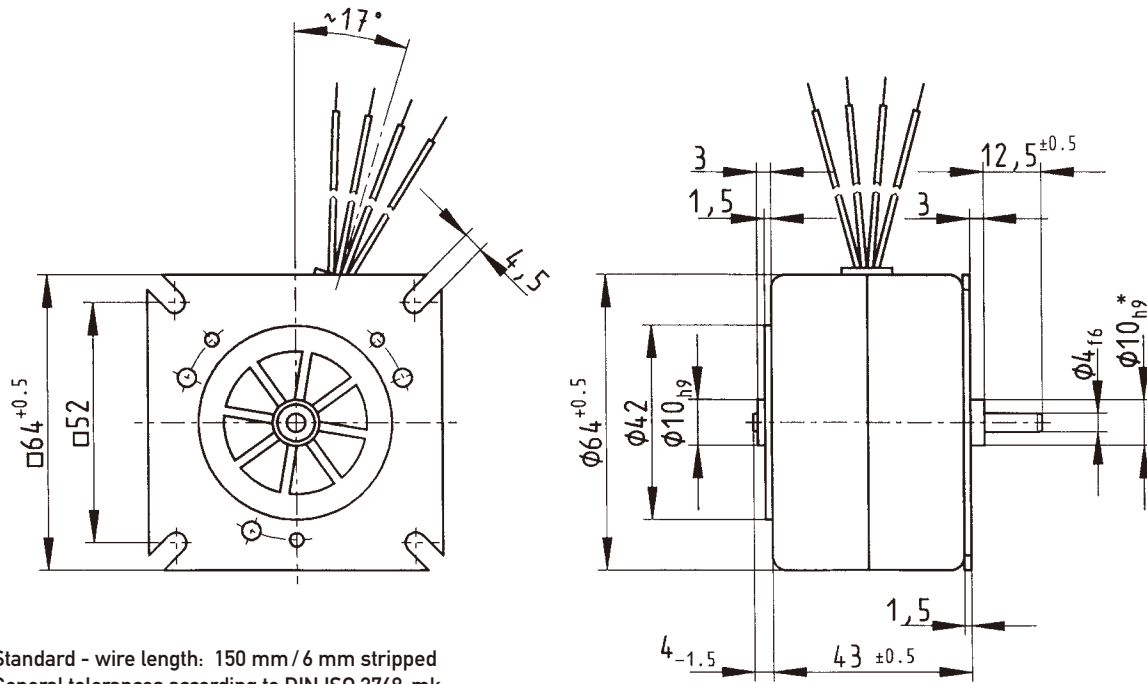
Motor type (SM6444)		R-375/S2/1	R-375/S2/1	R-375/S2/2	R-375/S2/2
Rated frequency	Hz	50	60	50	60
Speed	rpm	375	450	375	450
Running torque M_N	cNm	28	21	35	30
Power output	W	11	9,9	13,8	14,2
Power consumption	VA	26	28	31	33,5
Nominal current at 230 V	mA	113	122	135	145
Max. permissible external inertia	gcm ²	500	350	600	400
Detent torque M_S	cNm	7	7	7	7
Winding temperature increase	K	85 (S2 6,5 min)	85 (S2 6,5 min)	95 (S2 5 min.)	95 (S2 5 min.)
Weight	g	550	550	550	550

Capacitors	at U_N : 24 V	$\mu\text{F}/V\sim$	68 / 63	68 / 63	82 / 63	82 / 63
	at U_N : 110 V	$\mu\text{F}/V\sim$	2,7 / 250	2,7 / 250	3,3 / 250	3,3 / 250
	at U_N : 230 V	$\mu\text{F}/V\sim$	0,68 / 500	0,68 / 500	0,82 / 500	0,82 / 500

Circuit diagram Parallel circuit



Dimensions

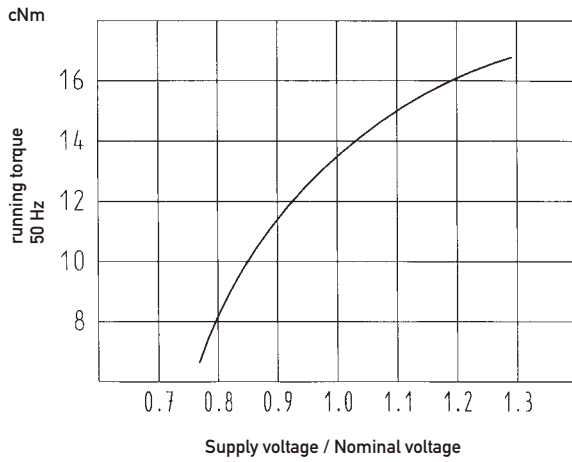


Standard - wire length: 150 mm / 6 mm stripped
 General tolerances according to DIN ISO 2768-mk

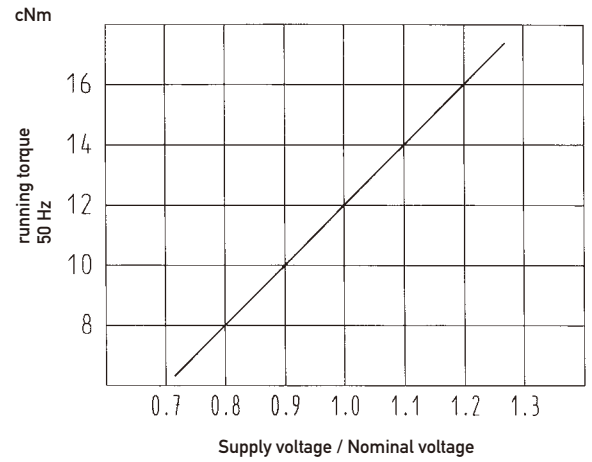
* on request 14h9

Chart: Torque versus voltage

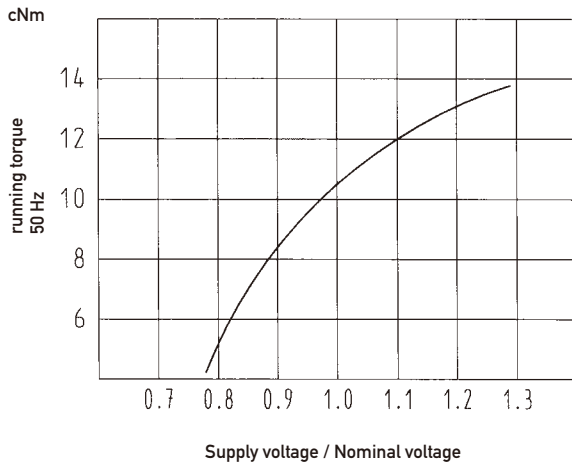
UPM1 (SM 6443 R-250/1)



UPU1 (SM 6443 R-375/1)



UPU1 (SM 6443 R-375/2)



UPU1 (SM 6443 R-375/S2/1)

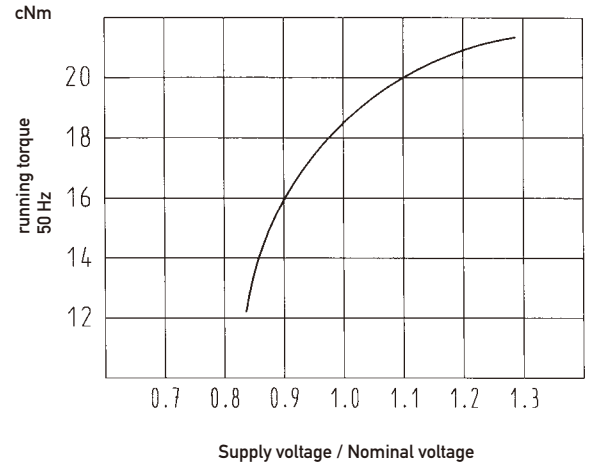
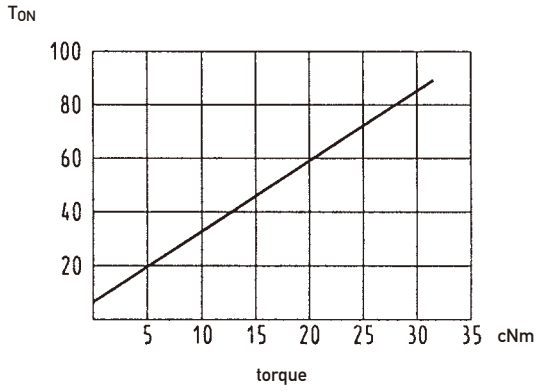


Chart: Possible duty cycle versus torque

UPU5 (SM 6444 R-375/S2/1)



UPU5 (SM 6444 R-375/S2/2)

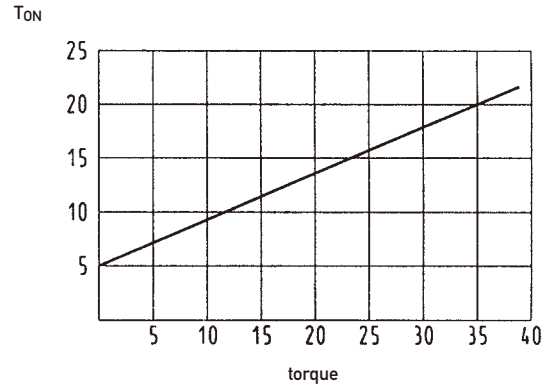
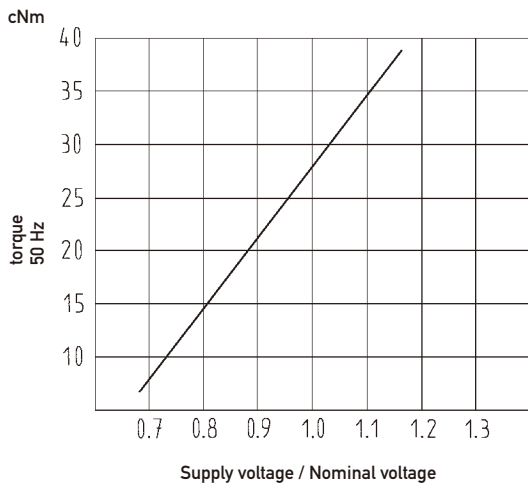
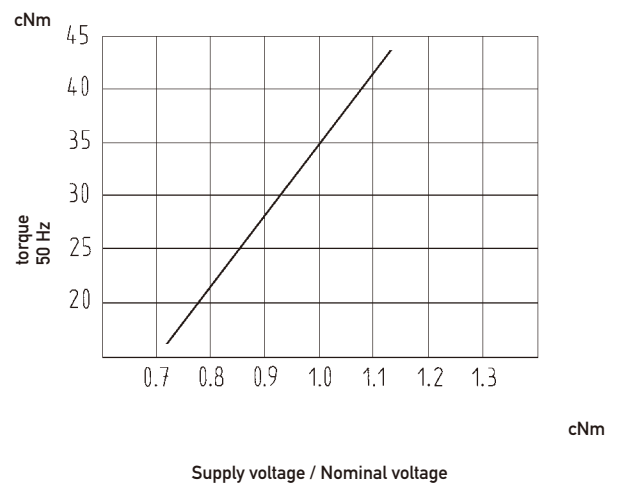


Chart: Torque versus voltage

UPU5 (SM 6444 R-375/S2/1)



UPU5 (SM 6444 R-375/S2/2)



UNU0 (SM 3532 RG)

Dimensions (mm)	∅ 35 x 32
Voltage (V)	24–230
Speed (rpm) 50 Hz	375
60 Hz	450
Pole number	16
Stalled limited torque (cNm)	
50 Hz	0,6
60 Hz	0,6
Power output (W)	
50 Hz	0,25
60 Hz	0,3
Gear combination	O, P, R



Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15 ... +40
Ambient temperature storage	°C -20 ... +100
Thermal class	B according to DIN EN 60085
Approval	standard
Mounting	any position
Electrical connection	cable
Protection	IP 30 according to DIN EN 60529
Weight	100 g
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	Sintered bronze, self- lubricating

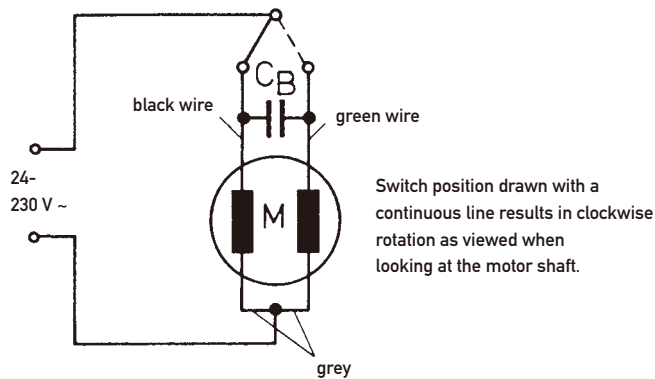
Order Reference

Type	Synchronous Motor	SM 3532 RG 375	24 V	50 Hz
Voltage	24 V 110 V 230 V			
Frequency	50 Hz 60 Hz			

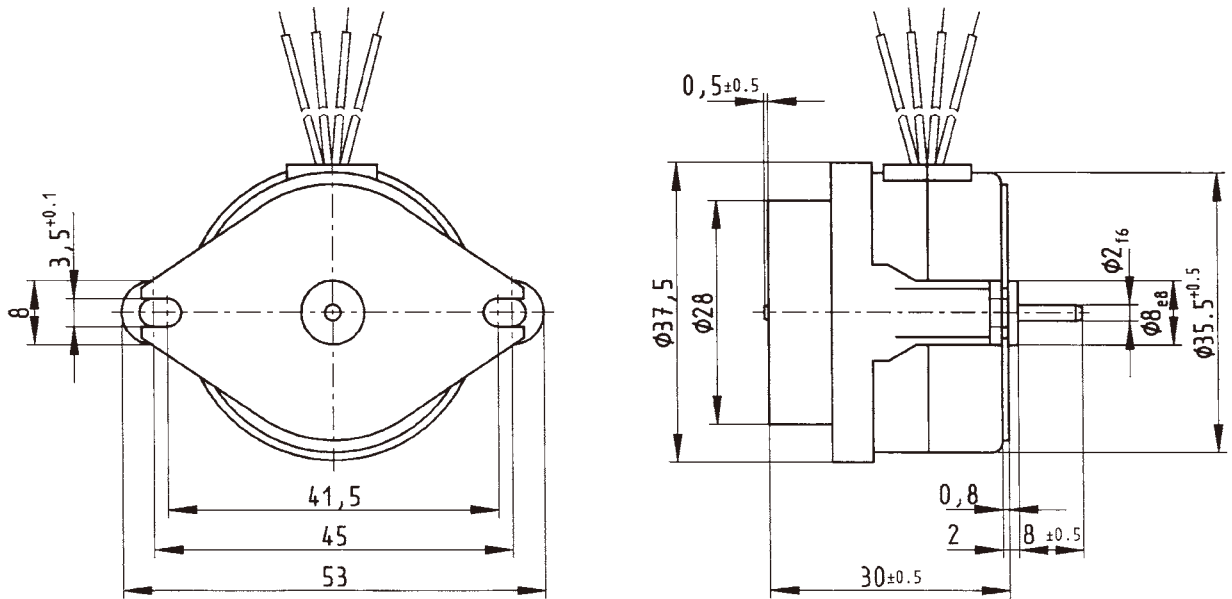
Technical Data

Rated frequency	Hz	50	60
Speed of rotation	rpm	375	450
Stalled limited torque	cNm	0,6 +/-15%	0,6 +/-15% (see chart next page)
Power output	W	0,25	0,3
Power consumption	VA	2,65	2,75
Nominal current at 230 V	mA	11,5	12
Detent torque M_s	cNm	0,1	0,1
Winding temperature increase	K	45	50
Capacitors			
at U_N : 24 V	$\mu F/V\sim$	4,7/63	4,7/63
at U_N : 110 V	$\mu F/V\sim$	0,22/250	0,22/250
at U_N : 230 V	$\mu F/V\sim$	0,068/500	0,068/500

Circuit diagram Parallel circuit



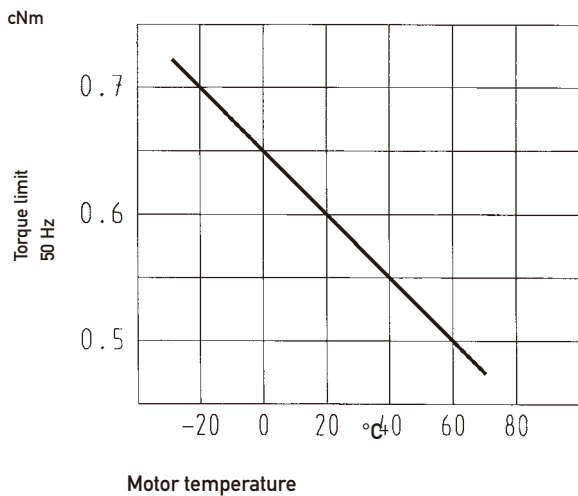
Dimensions



Standard - wire length: 100 mm / 6 mm stripped
 General tolerances acc. to DIN ISO 2768-mk

Chart: Torque limit versus motor temperature

UNU0 (SM 3532 RG-375)



UOU0 (SM 5032 RG)

Dimensions (mm) \varnothing 50 x 32

Voltage (V) 24-230

Speed (rpm) 50 Hz 375
60 Hz 450

Pole number 16

Stalled limited torque (cNm)
50 Hz 2
60 Hz 2

Power output (W)
50 Hz 0,8
60 Hz 0,95

Gear combination O, P, R



Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15 ... +40
Ambient temperature storage	°C -20 ... +100
Thermal class	B according to DIN EN 60085
Approval	standard
Mounting	any position
Electrical connection	cable
Protection	IP 30 according to DIN EN 60529
Weight	190 g
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	Sintered bronze, self-lubricating

Order Reference

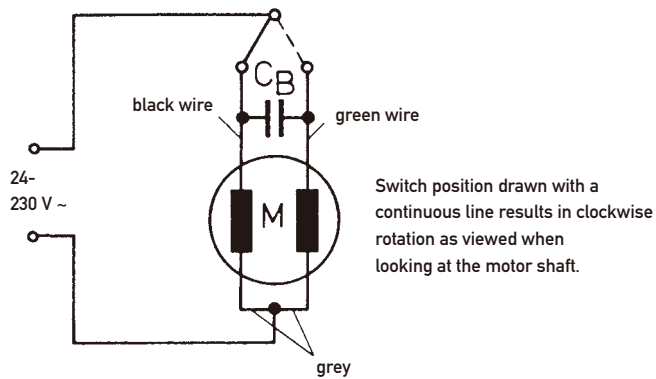
Type	Synchronous Motor	SM 5032 RG 375	24 V	50 Hz
Voltage	24 V 110 V 230 V			
Frequency	50 Hz 60 Hz			

Technical Data

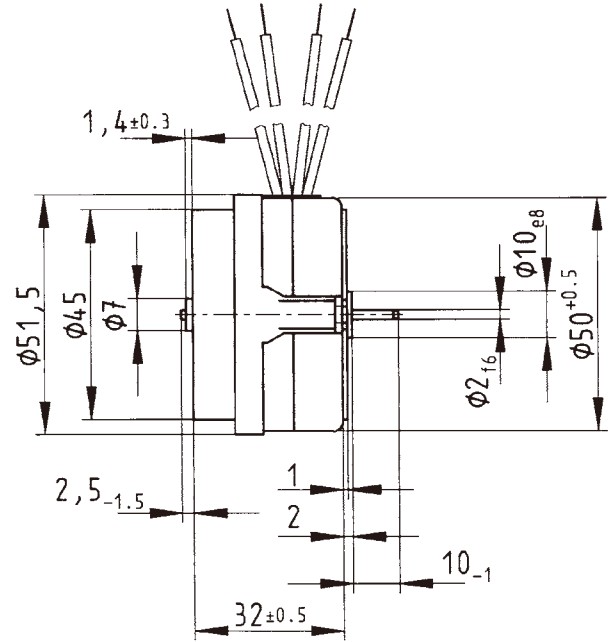
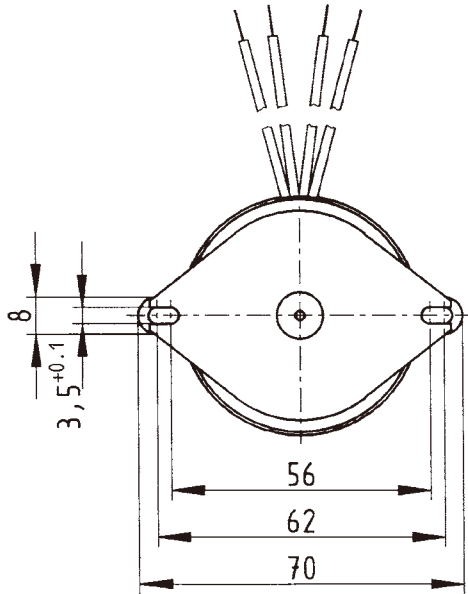
Rated frequency	Hz	50	60
Speed of rotation	rpm	375	450
Stalled limited torque	cNm	2 +10/-15%	2 +10/-15% (see chart next page)
Power output	W	0.8	0.95
Power consumption	VA	4.1	5.3
Nominal current at 230 V	mA	18	23
Detent torque M_s	cNm	0.3	0.3
Winding temperature increase	K	55	70

Capacitors	at U_N : 24 V	$\mu\text{F}/\text{V}\sim$	10/63	10/63
	at U_N : 110 V	$\mu\text{F}/\text{V}\sim$	0,47/250	0,47/250
	at U_N : 230 V	$\mu\text{F}/\text{V}\sim$	0,12/500	0,12/500

Circuit diagram Parallel circuit



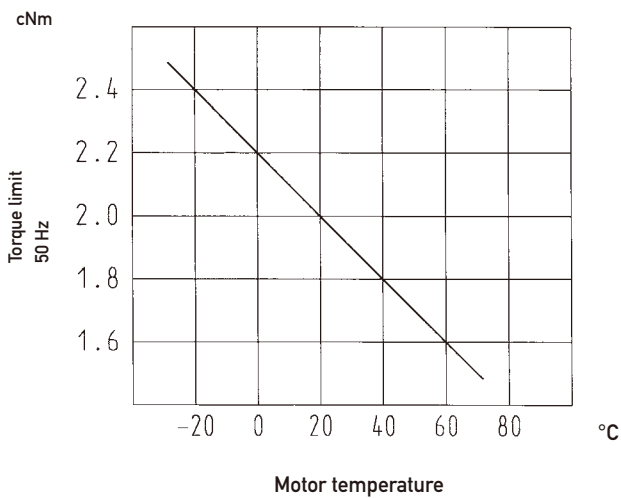
Dimensions



Standard - wire length: 200 mm / 4 mm stripped
 General tolerances acc. to DIN ISO 2768-mk

Chart: Torque limit versus motor temperature

UOU0 (SM 5032 RG-375)



UPU0 (SM6469RG)

Dimensions (mm) \varnothing 64 x 69

Voltage (V) 24–230

Speed (rpm) 50 Hz 375
60 Hz 450

Pole number 16

Stalled limited torque (cNm)
50 Hz 7
60 Hz 7

Power output (W)
50 Hz 2.75
60 Hz 3.3

Gear combination O, P, R



Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15 ... +40
Ambient temperature storage	°C -20 ... +100
Thermal class	B according to DIN EN 60085
Approval	standard
Mounting	any position
Electrical connection	cable
Protection	IP 30 according to DIN EN 60529
Weight	600 g
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	Sintered bronze, self-lubricating

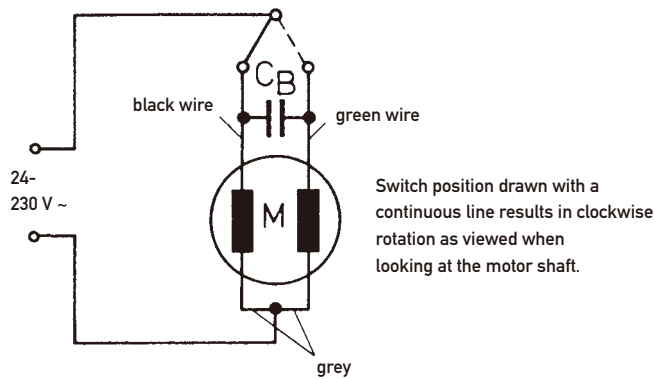
Order Reference

Type	Synchronous Motor	SM6469RG 375	24 V	50 Hz
Voltage	24 V 110 V 230 V			
Frequency	50 Hz 60 Hz			

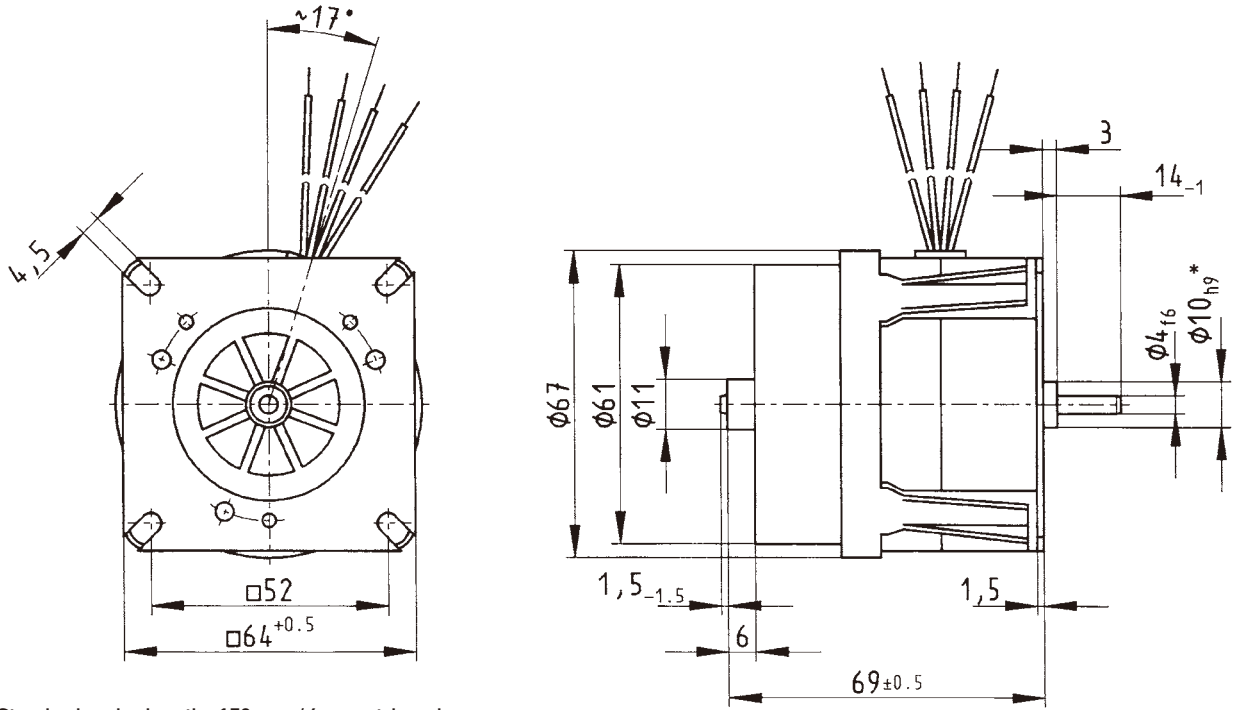
Technical Data

Rated frequency	Hz	50	60
Speed of rotation	rpm	375	450
Stalled limited torque	cNm	7 +/-10%	7 +/-10% (see chart next page)
Power output	W	2,75	3,3
Power consumption	VA	10,5	13,5
Nominal current at 230 V	mA	46	59
Detent torque M_s	cNm	3	3
Winding temperature increase	K	70	90
Capacitors	at U_N : 24 V	$\mu F/V\sim$	30/63
	at U_N : 110 V	$\mu F/V\sim$	1,3/250
	at U_N : 230 V	$\mu F/V\sim$	0,33/500

Circuit diagram Parallel circuit



Dimensions



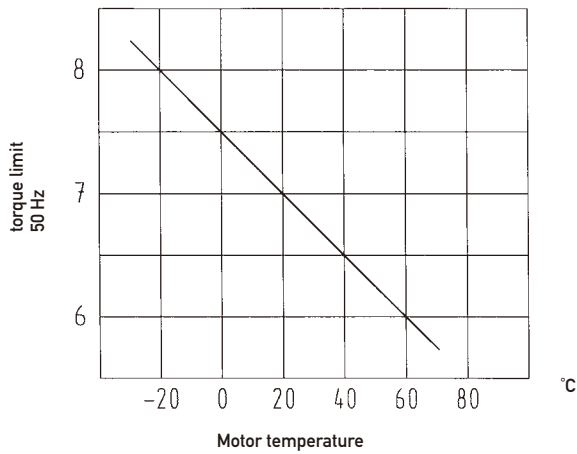
Standard - wire length: 150 mm / 6 mm stripped
General tolerances according to DIN ISO 2768-mk

* on request 14h9

Chart: Torque limit versus motor temperature

UPU0 (SM 6469 RG-375)

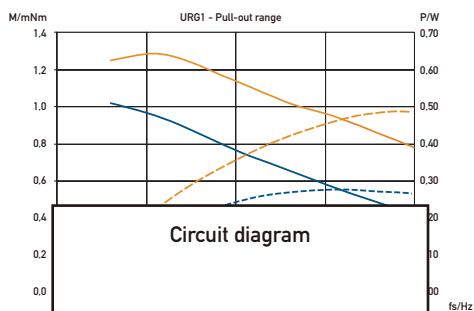
cNm



Stepper Motors



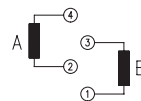
Performance Chart



Circuit diagram

	0	I	II	III	IV
1	+	-	-	+	+
2	+	+	-	-	+
3	-	+	+	-	-
4	-	-	+	+	-

→ CW
← CCW



URG



Dimensions (mm)	∅ 13 x 11
Step angle (°)	18
Holding torque* (mNm)	2.0
Detent torque (mNm)	0.3
Winding	bipolar
Gear combination	—

* winding for duty cycle 30 %, standard magnet

Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15 ... +60
Ambient temperature storage	°C -20 ... +100
Thermal resistance at f=0 R _{therm}	83 K/W
Thermal class	B according to DIN EN 60085
Approval	standard
Mounting	any position
Electrical connection	Pin, optional flex print
Protection	IP 40 according to DIN EN 60529
Weight	7 g
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	integrated high temperature plastic bearing

Order Reference

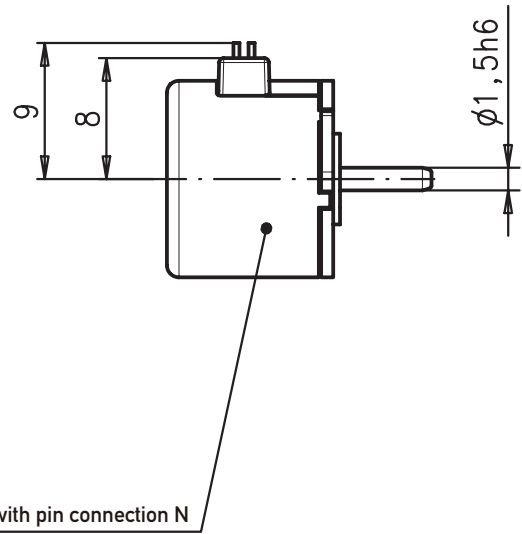
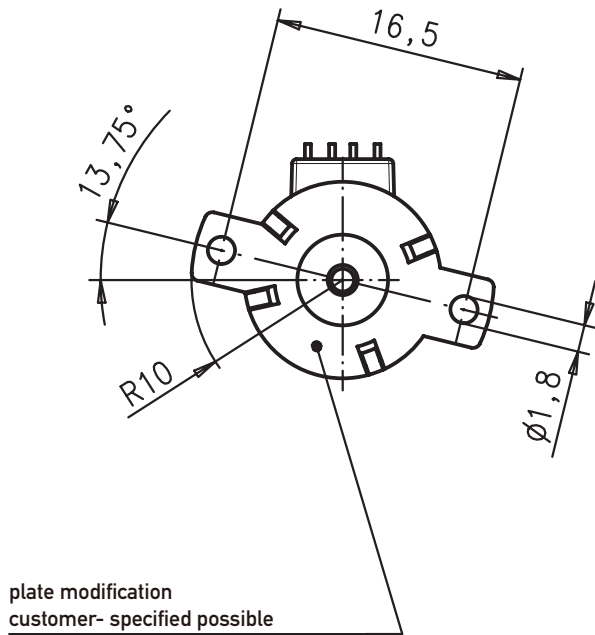
Type	Stepper Motor	URG	1E	N	6Ω	R	C
Configuration	1E	bipolar, standard magnet					
Approval	N						
Resistance	see next page						
Direction	R	reversible					
Connector	N	Pin					
	C	flex print					

This motor type doesn't fulfil basis insulation requirements of EN 60555-1: 2004
Customer application must realize a suitable protection class.

Technical Data

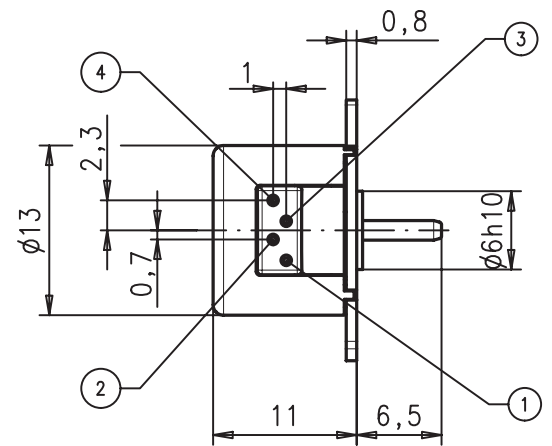
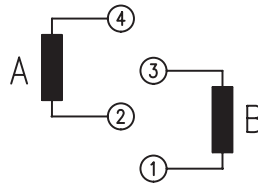
bipolar	Rated voltage U_N	V	3	6	12
	Resistance per winding R_{20}	Ω	6	26	102
	Holding torque M_H	mNm	2.5		
	Detent torque M_S	mNm	0.3		
	Rotor inertia J_R	gcm ²	0.033		
	Steps per revolution		20		
	Duty cycle		30 %		
	Direction of rotation		reversible		

Dimensions



	0	I	II	III	IV
1	+	-	-	+	+
2	+	+	-	-	+
3	-	+	+	-	-
4	-	-	+	+	-

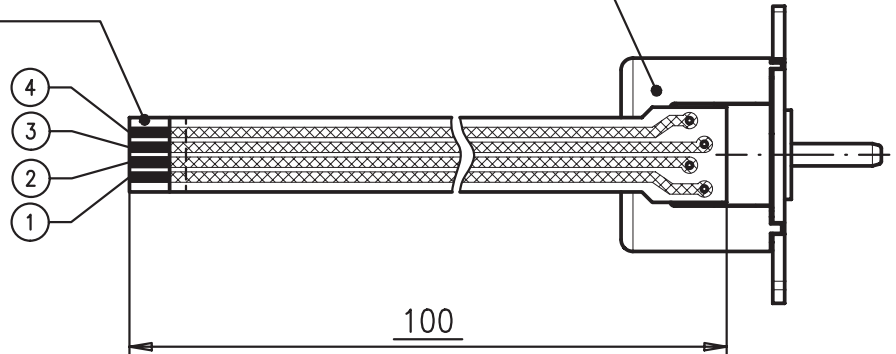
clockwise rotation
 counter clockwise rotation



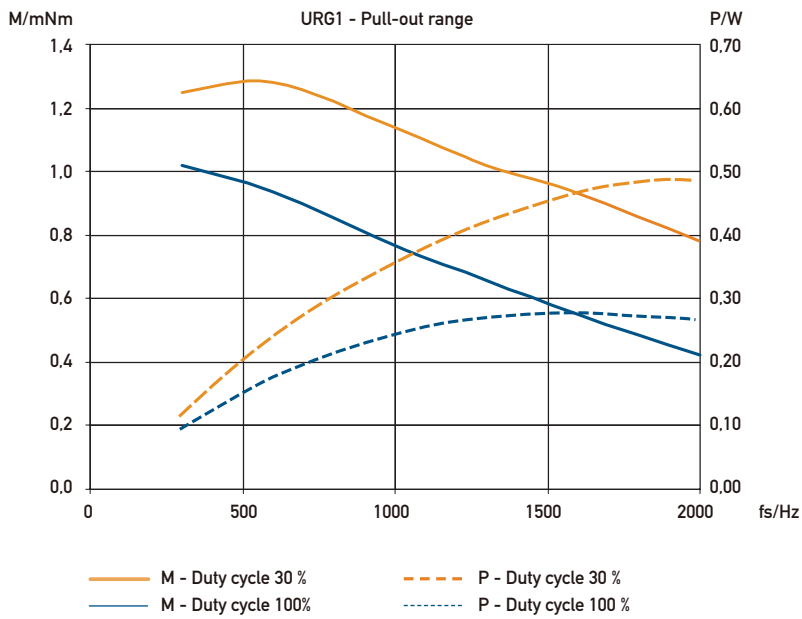
Dimensions

recommended FPC layout for flex print connector 1 mm

version with flex print circuit C



Performance Chart



UAG1/2

UAG1/2

Dimensions (mm) $\varnothing 20 \times 17,2$

Step angle (°) 18

Holding torque
(cNm) 0,7 / 0,5

Detent torque
(cNm) 0,14

Winding bipolar/unipolar

Gear combination on request



Rotational

Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -40...+60
Ambient temperature storage	°C -40...+100
Thermal resistance at f=0 R _{therm}	50 K/W
Thermal class	B according to DIN EN 60085
Approval	standard
Mounting	any position
Electrical connection	insulation displacement connection, pins, lead wires
Protection	IP 40 according to DIN EN 60529
Weight	25 g
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	sintered bronze, self-lubricating

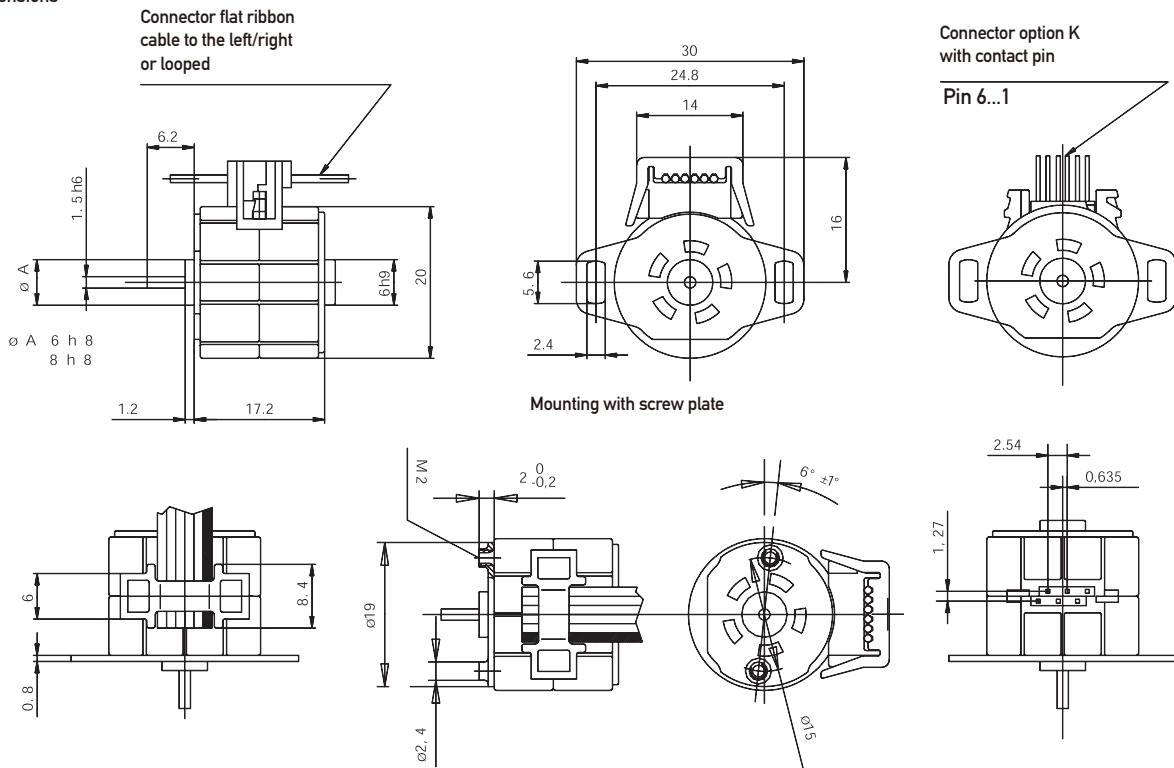
Order Reference

Type	Stepper Motor	UAG	1	0	N	27 (Ω)	R	E
Configuration	1 bipolar 2 unipolar							
Rotor shaft, mounting	0 centring 8 mm, mounting plate with screw M2 3 centring 8 mm, mounting plate with long holes A centring 6 mm, mounting plate with screw M2 E centring 6 mm, mounting plate with long holes							
Approval	N Approval Standard							
Resistance	See next page Resistance per winding for bipolar or unipolar.							
Direction	reversible							
Cable	E Lead wires 150 mm with plug AMP MicroMatch 0-215083-6 (other on request)							

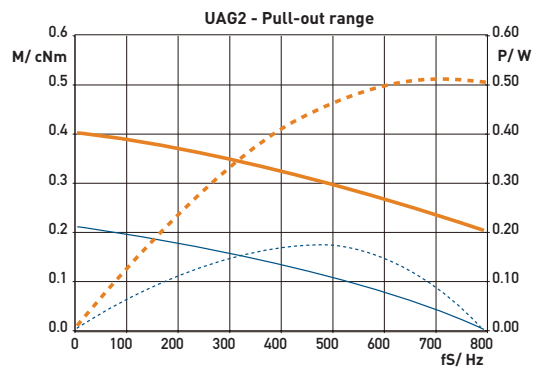
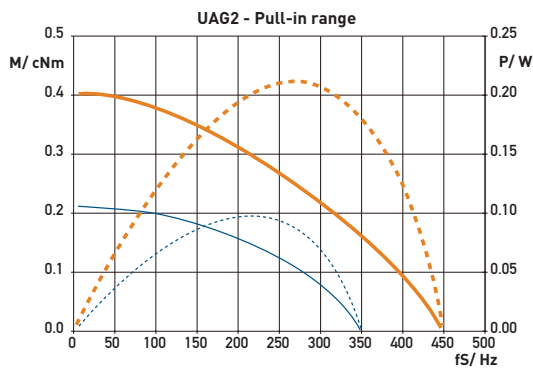
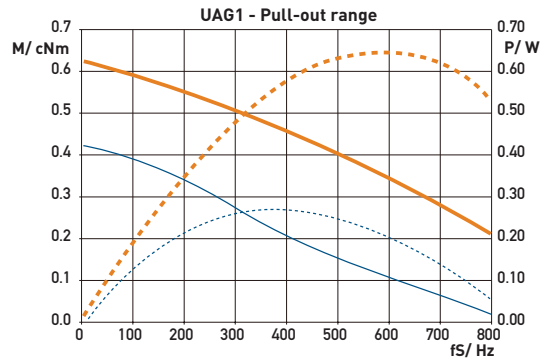
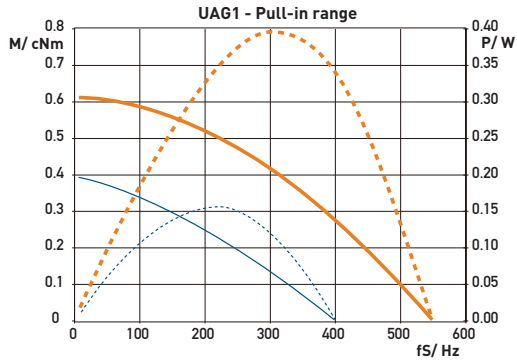
Technical Data

UAG1/2		bipolar (UAG1)	Rated voltage U_N	V	6	12	24
		Resistance per winding		R_{20}	27	150	675
		unipolar (UAG2)	Rated voltage U_N	V	6	12	24
Resistance per winding R_{20}				Ω		35	170
Steps per revolution	20						
Duty cycle	100%						
Winding temperature T_{max}	130° C						
Rotor inertia J_R	0.31 gcm ²						
Holding torque M_H	0.7 cNm (UAG1) 0.5 cNm (UAG2)						
Detent torque M_D	0.14 cNm						
Direction of rotation	reversible						

Dimensions



Performance Chart



— M - Duty cycle 30 %
 — M - Duty cycle 100%

- - - P - Duty cycle 30 %
 - - - P - Duty cycle 100 %

UAG3/4

UAG3/4

Dimensions (mm) \varnothing 20 x 17

Step angle (°) 18

Holding torque (mNm) 5,6 / 4,2

Detent torque (mNm) > 0,6

Winding bipoar/unipolar

Gear combination on request



Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -20...+60
Ambient temperature storage	°C -40...+100
Thermal resistance at f=0 R _{therm}	47 K/W
Thermal class	B according to DIN EN 60085
Approval	standard
Mounting	any position
Electrical connection	cable
Protection	IP 40 according to DIN EN 60529
Weight	22 g
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	sintered bronze, self-lubricating

Order Reference

Type	Stepper Motor	UAG	3	3	N	150 (Ω)	Ω	R	E
Configuration	3 bipolar 4 unipolar								
Rotor shaft, mounting	3 centring 8 mm, mounting plate with long holes 5 centring 8 mm, mounting plate (for clipping) E centring 6 mm, mounting plate with long holes G centring 6 mm, mounting plate (for clipping)								
Approval	N Approval Standard								
Resistance	See next page Resistance per winding for bipolar or unipolar.								
Direction	reversible								
Cable	E cable 150 mm with Tyco connector CT 173977-4 1-6 (other on request)								

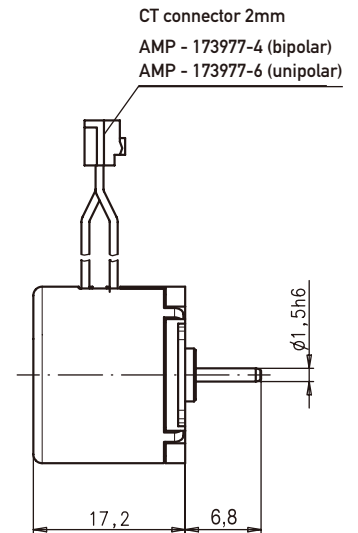
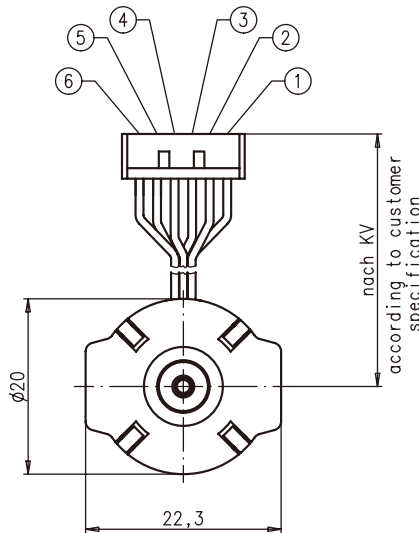
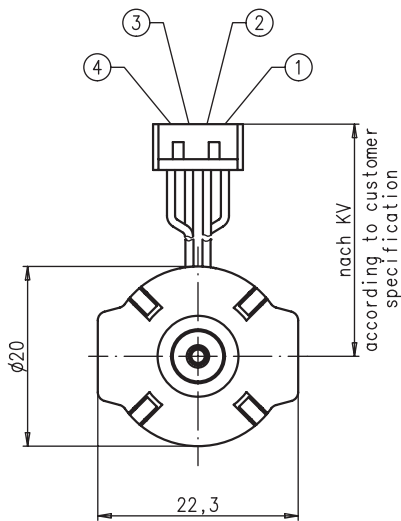
Technical Data

bipolar (UAG3)	Rated voltage U_N	V	12
	Resistance per winding R_{20}	Ω	150
unipolar (UAG4)	Rated voltage U_N	V	12
	Resistance per winding R_{20}	Ω	150
Steps per revolution			20
Duty cycle			100%
Winding temperature T_{max}			130° C
Rotor inertia J_R			0.26 gcm ²
Holding torque M_H			0.56 cNm (UAG3) 0.42 cNm (UAG4)
Detent torque M_{Hd}			> 0.6 mNm
Direction of rotation			reversible

Dimensions

motortype	$\varnothing D$
UAG33	$\varnothing 8\ 0$ -0.05
UAG3E	$\varnothing 6\ 0$ -0.05

motortype	$\varnothing D$
UAG43	$\varnothing 8\ 0$ -0.05
UAG4E	$\varnothing 6\ 0$ -0.05



bipolar

	0	I	II	III	IV
1	+	+	-	-	+
2	+	-	-	+	+
3	-	-	+	+	-
4	-	+	+	-	-

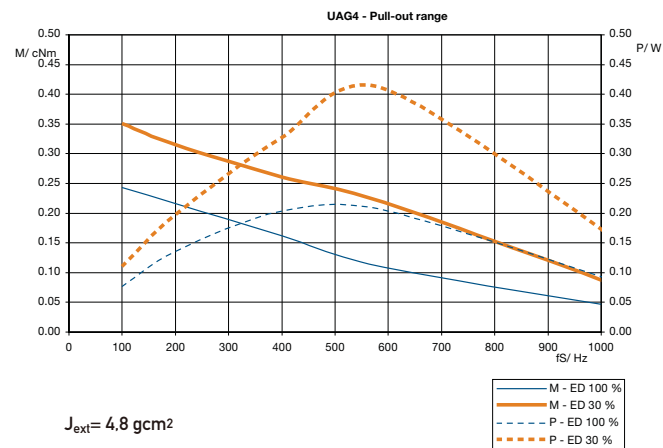
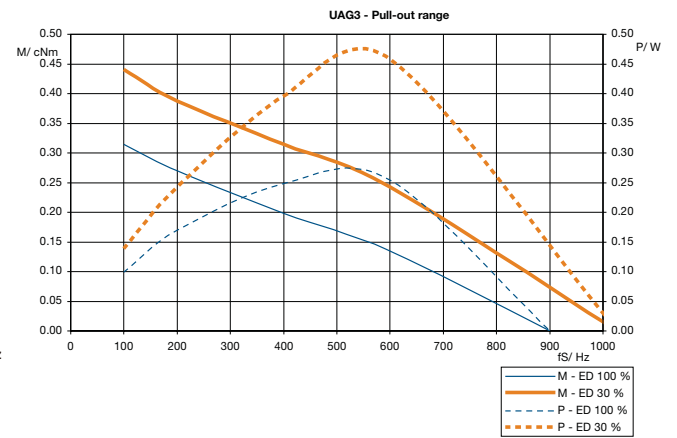
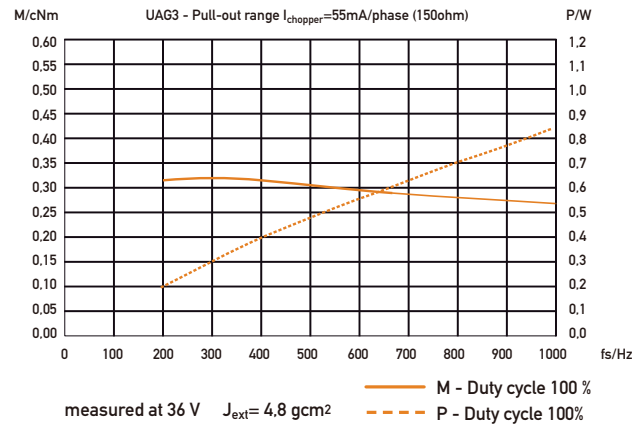
→ clockwise rotation
← counter clockwise rotation

unipolar

	0	I	II	III	IV
1	-	-	+	+	-
2	-	+	+	-	-
3	+	+	+	+	+
4	+	+	+	+	+
5			-	-	
6		-	-		

→ clockwise rotation
← counter clockwise rotation

Performance Chart



UCD1/7; UCD2/8

Dimensions (mm) $\varnothing 28 \times 24$

Step angle (°) 7,5

Holding torque*
(cNm) 1,6–2,7

Detent torque
(cNm) 0,26–0,42

Winding bipolar/unipolar

Gear combination on request



* values for lead wire version (connection N) / connector versions up to 15 % higher

Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15 ... +60
Ambient temperature storage	°C -20 ... +100
Thermal resistance at f=0 R _{therm}	29 K/W
Thermal class	B according to DIN EN 60085
Approval	standard
Mounting	any position
Electrical connection	connector type D or N
Protection	IP 30 according to DIN EN 60529
Weight	54 g
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	Sintered bronze, self-lubricating

Order Reference

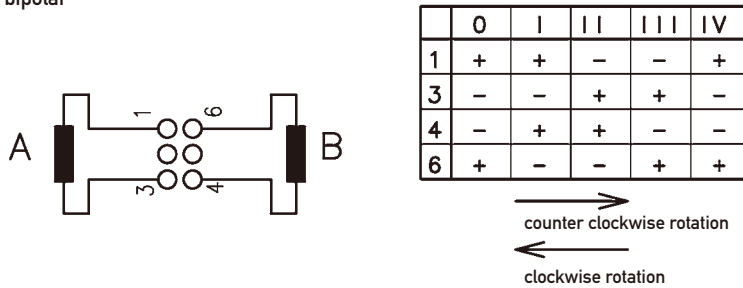
Type	Stepper Motor		UCD	1	0	N	24 Ω	R	B
Configuration	1	bipolar, standard magnet	7	bipolar, stronger magnet					
	2	unipolar, standard magnet	8	unipolar, stronger magnet					
Rotor shaft, mounting	3	centring 8 mm, shaft 2,0 mm, screw plate	E	centring 10 mm, shaft 2,0 mm, screw plate					
	4	centring 8 mm, shaft 1,5 mm, screw plate	K	centring 10 mm, shaft 1,5 mm, screw plate					
	0	centring 8 mm, shaft 2,0 mm, clip	A	centring 10 mm, shaft 2,0 mm, clip					
	1	centring 8 mm, shaft 1,5 mm, clip	C	centring 10 mm, shaft 1,5 mm, clip					
Approval	N	Approval Standard							
Resistance	see next pages: Resistance per winding for bipolar or unipolar								
Direction	R	reversible							
Connection	D	see next pages „Connection Types“							
	N								

Technical Data

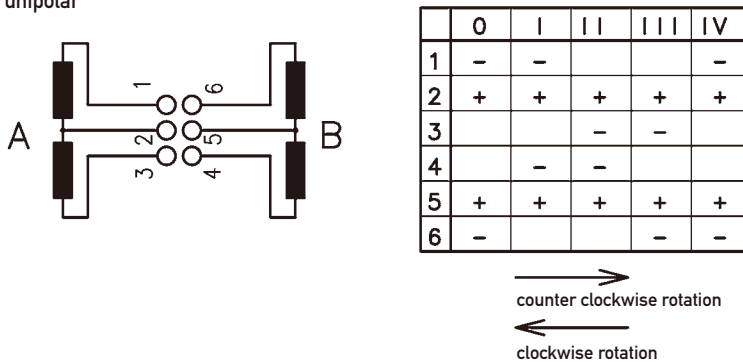
bipolar		UCD1		UCD5	
Holding torque M_H *	cNm	2		2.7	
Detent torque M_S	cNm	0,26		0,42	
Rotor inertia J_R	gcm ²	2.2		2.4	
Rated voltage U_N	V	6	12	24	
Resistance per winding R_{20}	Ω	24	90	380	
Steps per revolution		48			
Duty cycle		100%			
Direction of rotation	V	reversible			
unipolar		UCD2		UCD6	
Holding torque M_H	cNm	1,6		2,3	
Detent torque M_S	cNm	0,26		0,42	
Rotor inertia J_R	gcm ²	2.2		2,4	
Rated voltage U_N	V	3	6	24	
Resistance per winding R_{20}	Ω	24	90	380	
Steps per revolution		48			
Duty cycle		100%			
Direction of rotation	V	reversible			

* values for lead wire version (connection N) / connector versions up to 15 % higher

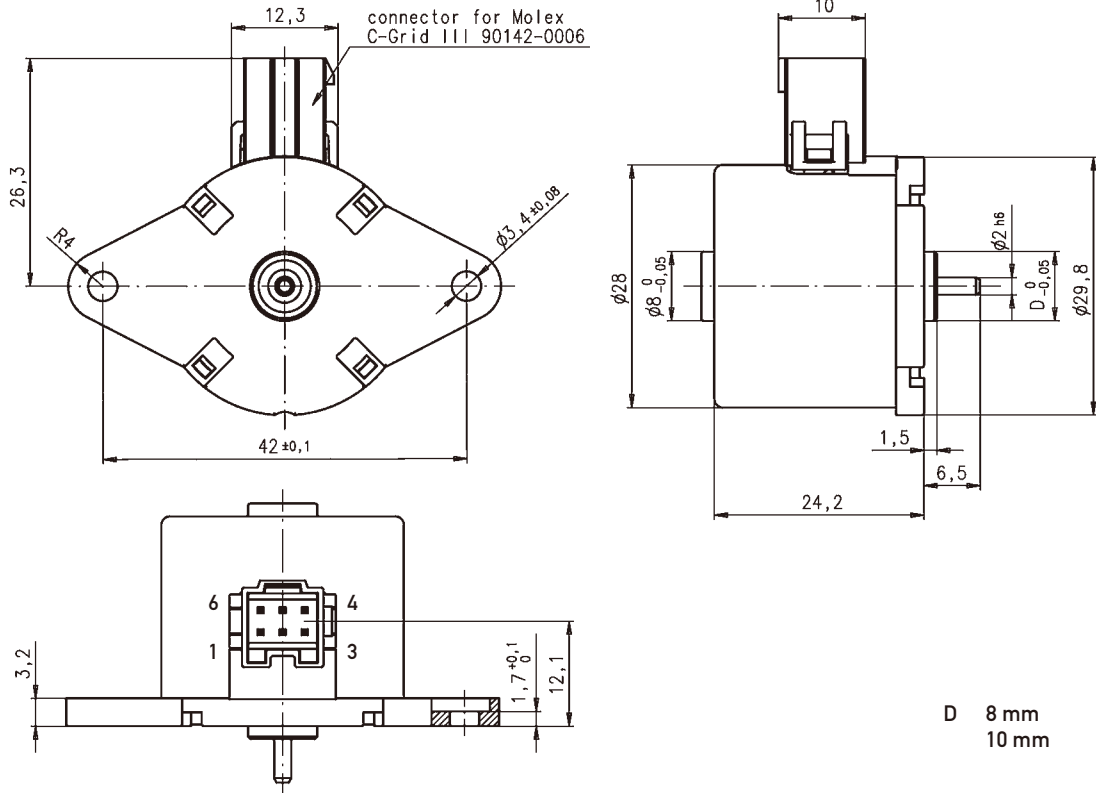
Circuit diagram bipolar



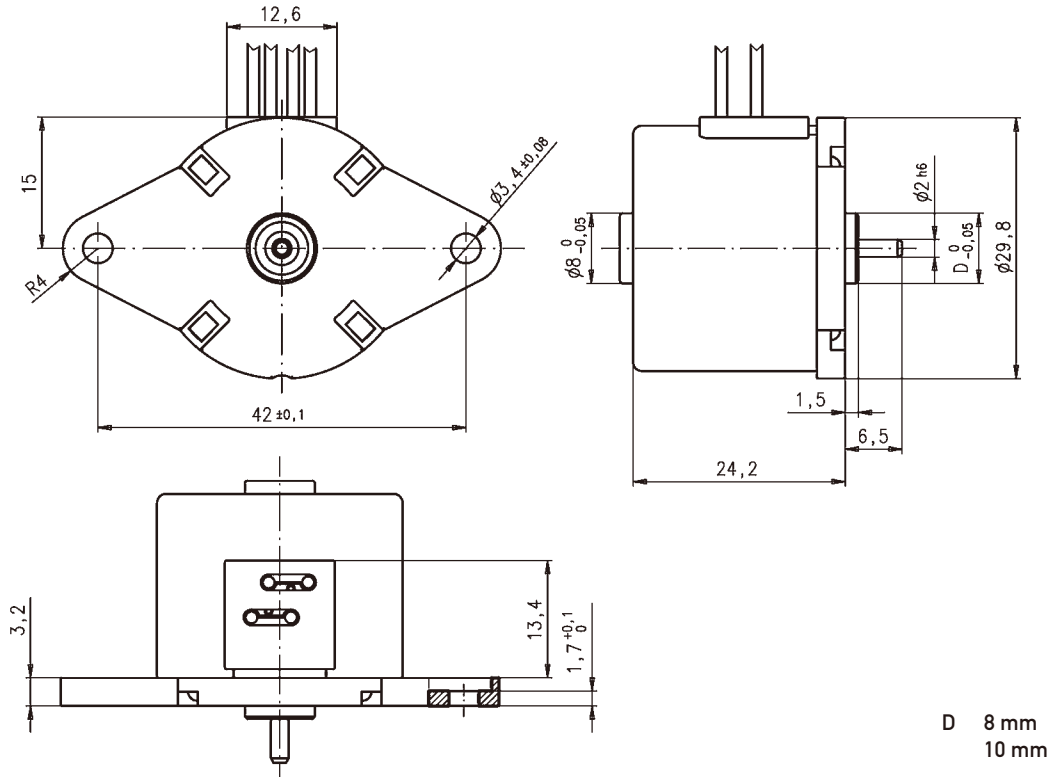
Circuit diagram unipolar



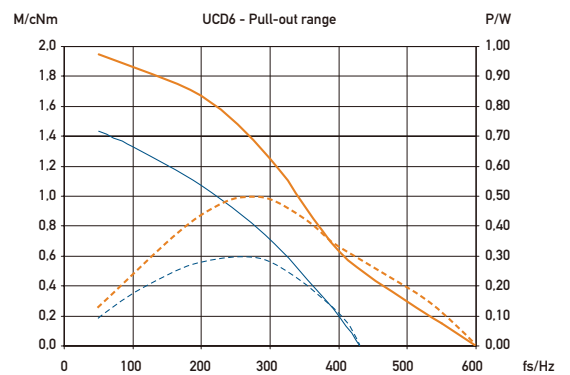
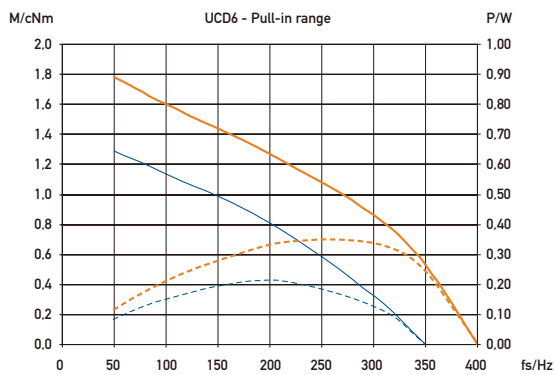
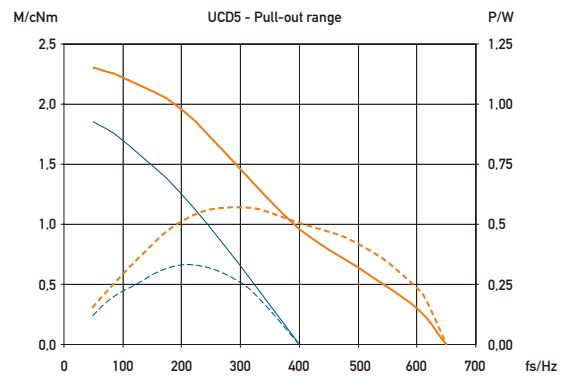
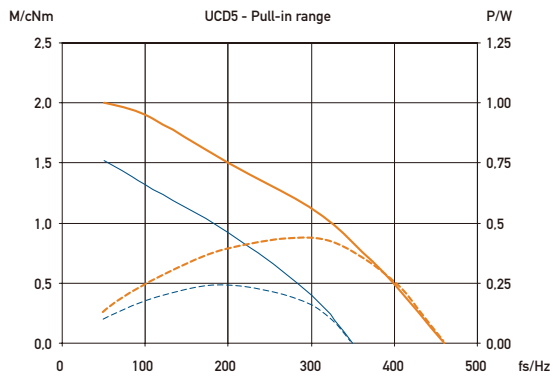
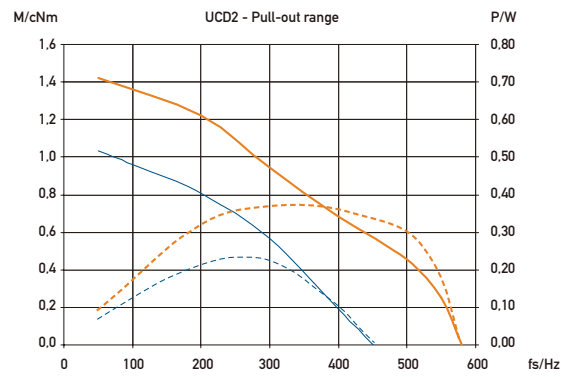
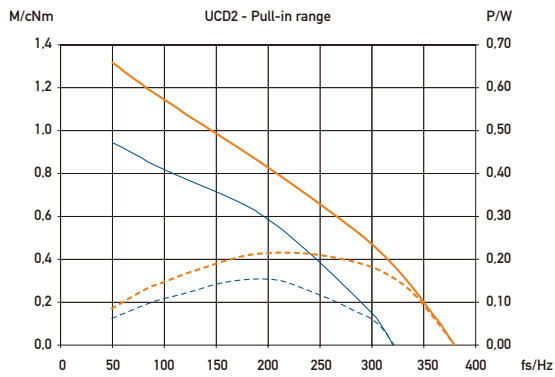
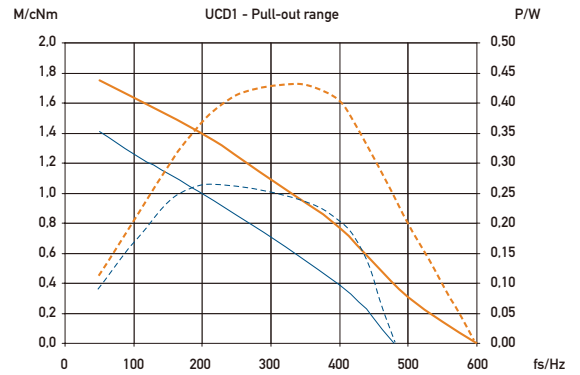
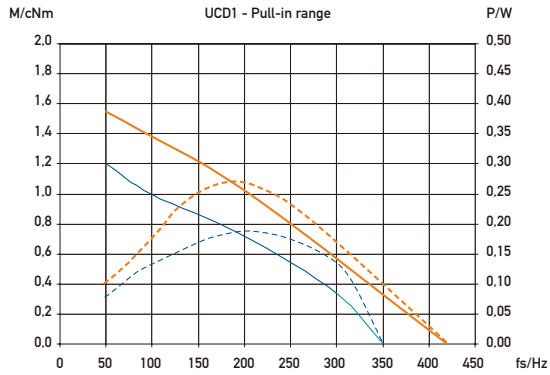
Dimensions Version with Connector D



Version with Connector N



Performance Chart



— M - Duty cycle 30 %
— M - Duty cycle 100%

- - - P - Duty cycle 30 %
- - - P - Duty cycle 100 %

UCB1/7; UCB2/8

Dimensions (mm) $\varnothing 28 \times 24$

Step angle (°) 15

Holding torque*
(cNm) 1,3–2,3

Detent torque
(cNm) 0,29

Winding bipolar/unipolar

Gear combination on request



* values for lead wire version (connection N) / connector versions up to 15 % higher

Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15 ... +60
Ambient temperature storage	°C -20 ... +100
Thermal resistance at f=0 R _{therm}	29 K/W
Thermal class	B according to DIN EN 60085
Approval	standard
Mounting	any position
Electrical connection	connector type D or N
Protection	IP 30 according to DIN EN 60529
Weight	54 g
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	Sintered bronze, self-lubricating

Order Reference

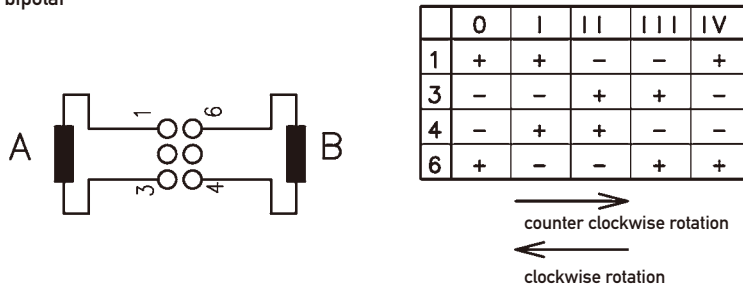
Type	Stepper Motor		UCB	1	0	N	24 Ω	R	B
Configuration	1	bipolar, standard magnet	7	bipolar, stronger magnet					
	2	unipolar, standard magnet	8	unipolar, stronger magnet					
Rotor shaft, mounting	3	centring 8 mm, shaft 2,0 mm, screw plate	E	centring 10 mm, shaft 2,0 mm, screw plate					
	4	centring 8 mm, shaft 1,5 mm, screw plate	K	centring 10 mm, shaft 1,5 mm, screw plate					
	0	centring 8 mm, shaft 2,0 mm, clip	A	centring 10 mm, shaft 2,0 mm, clip					
	1	centring 8 mm, shaft 1,5 mm, clip	C	centring 10 mm, shaft 1,5 mm, clip					
Approval	N	Approval Standard							
Resistance	see next pages: Resistance per winding for bipolar or unipolar								
Direction	R	reversible							
Connection	D	see next pages „Connection Types“							
	N								

Technical Data

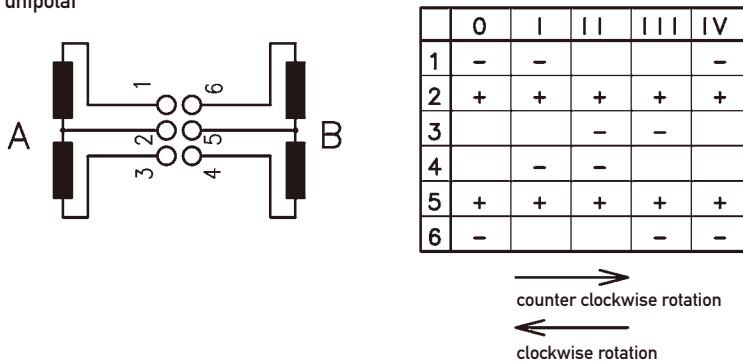
bipolar		UCB1		UCB5	
Holding torque M_H *	cNm	1,7		2,3	
Detent torque M_S	cNm	0,29		0,46	
Rotor inertia J_R	gcm ²	2,1		2,4	
Rated voltage U_N	V	6	12	24	
Resistance per winding R_{20}	Ω	24	90	380	
Steps per revolution		24			
Duty cycle		100%			
Direction of rotation	V	reversible			
unipolar		UCB2		UCB6	
Holding torque M_H *	mNm	1,3		1,8	
Detent torque M_S	mNm	0,29		0,46	
Rotor inertia J_R	gcm ²	2,1		2,4	
Rated voltage U_N	V	6	12	24	
Resistance per winding R_{20}	Ω	24	90	380	
Steps per revolution		24			
Duty cycle		100%			
Direction of rotation	V	reversible			

* values for lead wire version (connection N) / connector versions up to 15 % higher

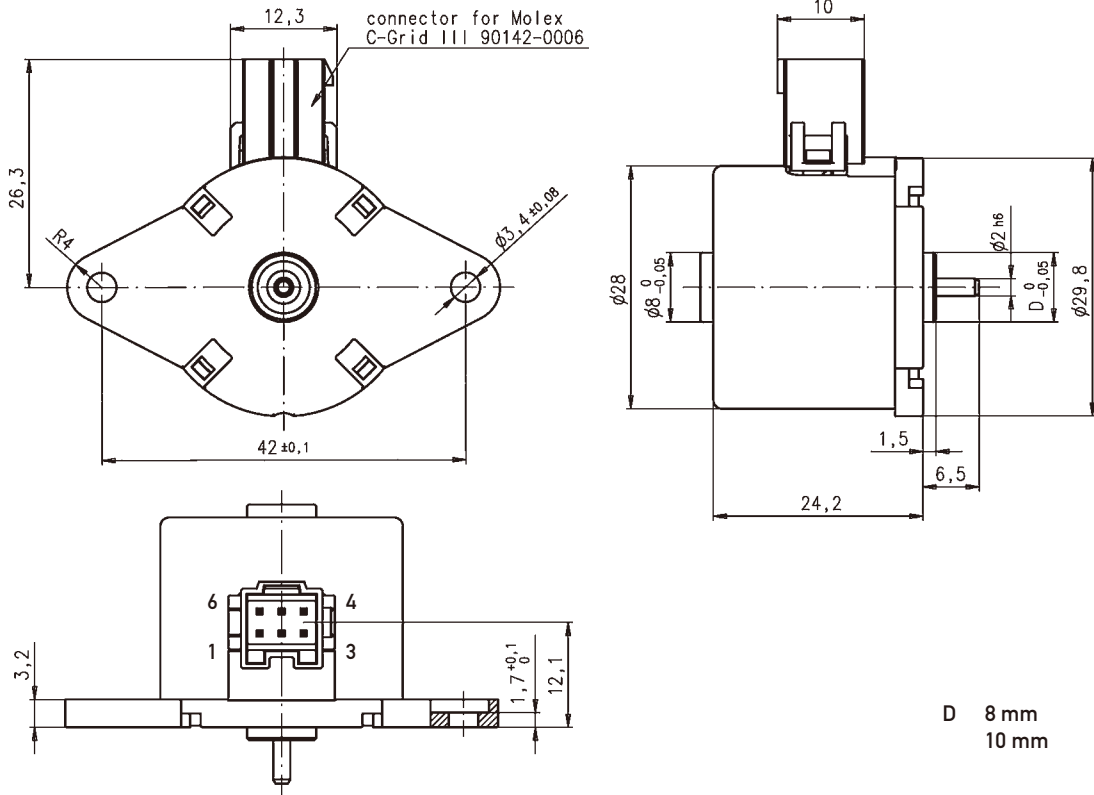
Circuit diagram bipolar



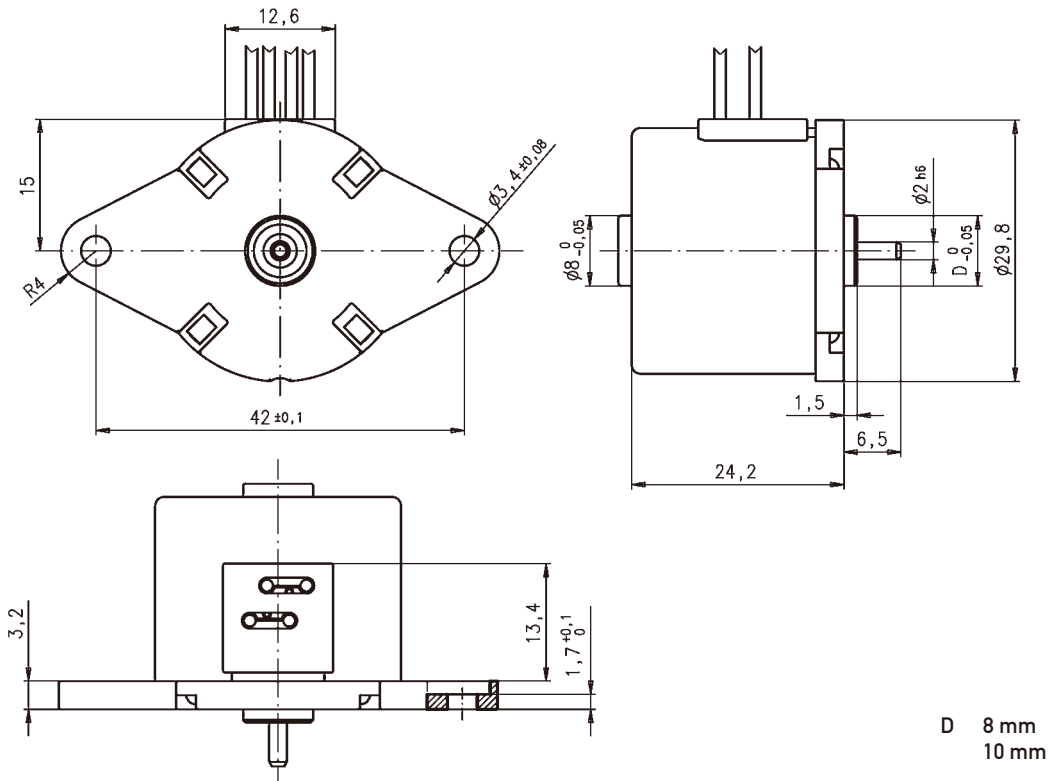
Circuit diagram unipolar



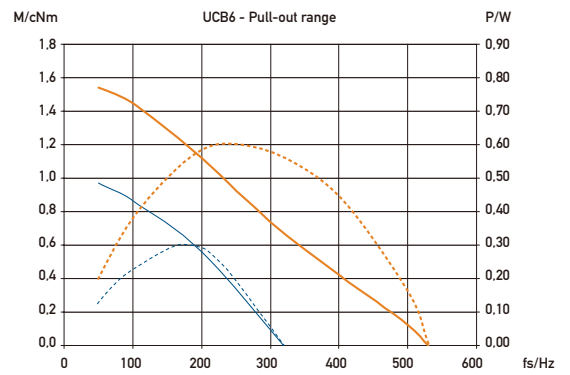
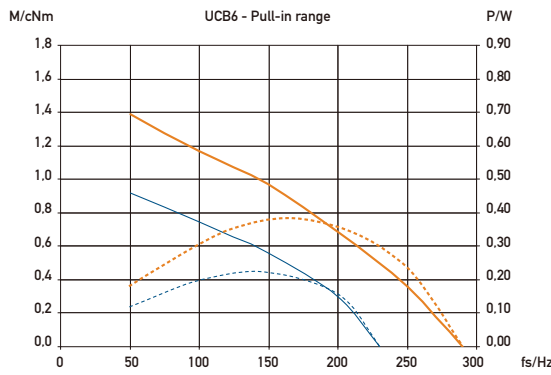
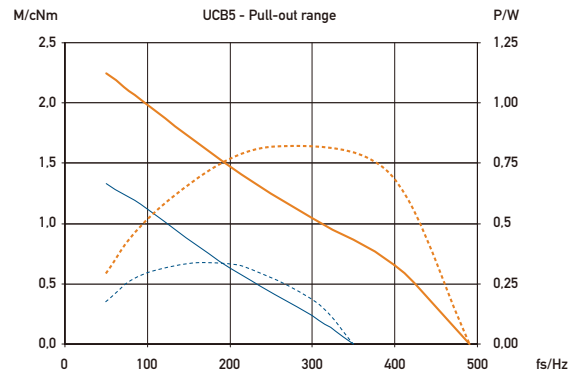
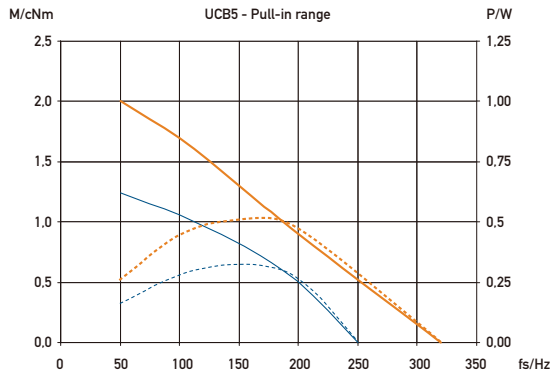
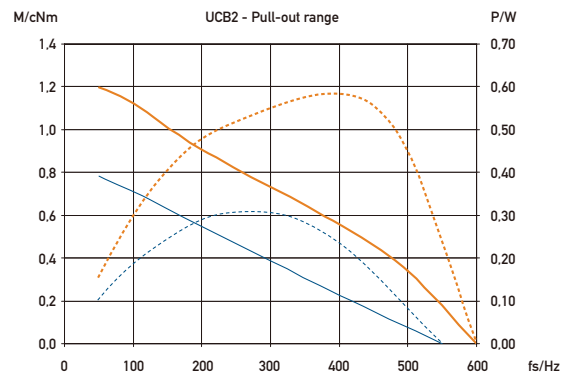
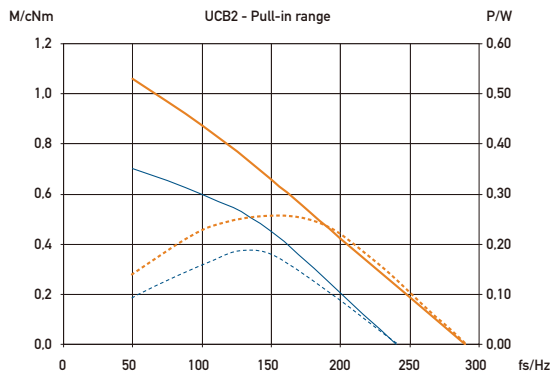
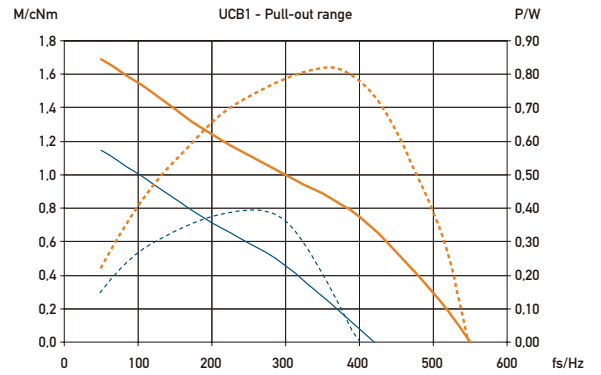
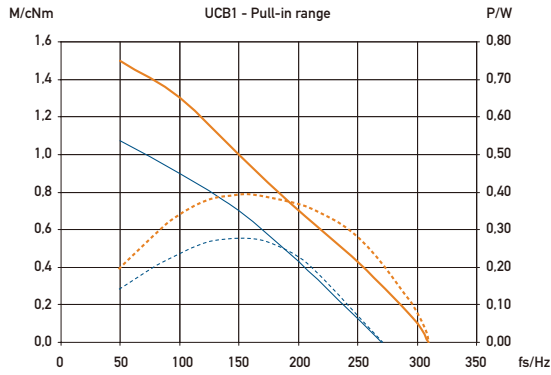
Dimensions Version with Connector D



Version with Connector N



Performance Chart



— M - Duty cycle 30 %
— M - Duty cycle 100%

- - - P - Duty cycle 30 %
- - - P - Duty cycle 100%

UBD1/2/5/6

Dimensions (mm) $\varnothing 36 \times 21$

Step angle (°) 7.5

Holding torque (cNm) 1.3–1.9

Detent torque (cNm) 0.22/0.27

Winding bipolar/unipolar

Gear combination A, D, M, B, F, V



Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15...+55
Ambient temperature storage	°C -20...+100
Thermal resistance at f=0 R _{therm}	27 K/W
Thermal class	A according to DIN EN 60085
Approval	standard (UL/CSA on request)
Mounting	any position
Electrical connection	cable
Protection	IP 40 according to DIN EN 60529
Weight	60 g
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	sintered bronze, self-lubricating
Electric strength	according to DIN EN 60034-1/DIN EN 60335-1

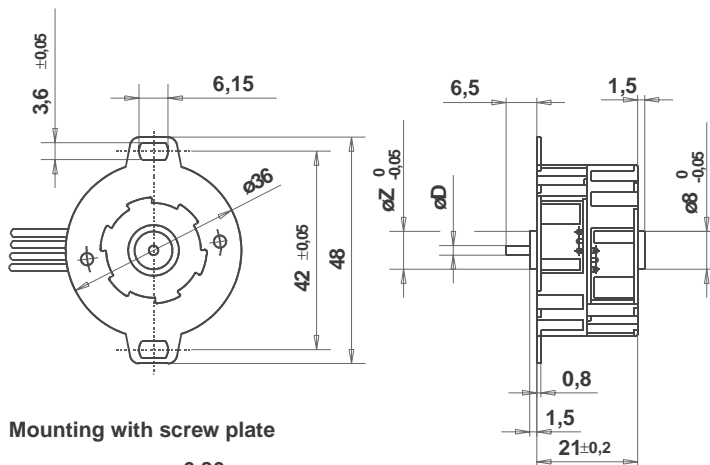
Order Reference

Type	Stepper Motor		UBD	1	0	N	18.5	R	E
Configuration	1	bipolar, standard magnet	5	bipolar, stronger magnet					
	2	unipolar, standard magnet	6	unipolar, stronger magnet					
Rotor shaft, mounting	0	centring 8 mm, shaft 2.0 mm, clip	A	centring 10 mm, shaft 2.0 mm, clip					
	1	centring 8 mm, shaft 1.5 mm, clip	C	centring 10 mm, shaft 1.5 mm, clip					
	3	centring 8 mm, shaft 2.0 mm, screw plate	E	centring 10 mm, shaft 2.0 mm, screw plate					
	4	centring 8 mm, shaft 1.5 mm, screw plate	K	centring 10 mm, shaft 1.5 mm, screw plate					
Approval	N	Approval Standard							
Resistance	See next page Resistance per winding for bipolar or unipolar.								
Direction	reversible								
Cable	E	cable 150 mm (other on request)							

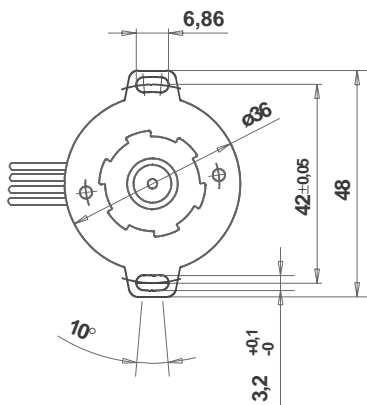
Technical Data

bipolar (UBD1/5)	Rated voltage U_N	V	3	6	12	24
	Resistance per winding R_{20}	Ω	11,5	18,5	100	460
	Holding torque M_H	cNm	1,8 (UBD1); 1,9 (UBD5)			
	Detent torque M_S	cNm	0,22 (UBD1); 0,27 (UBD5)			
	Rotor inertia J_R	gcm^2	2,8 (UBD 1), 2,9 (UBD 5)			
unipolar (UBD2/6)	Rated voltage U_N	V	3	6	12	24
	Resistance per winding R_{20}	Ω	12	28	120	500
	Holding torque M_H	cNm	1,3 (UBD2); 1,6 (UBD6)			
	Detent torque M_S	cNm	0,22 (UBD2); 0,27 (UBD6)			
	Rotor inertia J_R	gcm^2	2,8 (UBD2); 2,9 (UBD6)			
	Steps per revolution	48				
	Winding temperature T_{max}	105° C				
	Duty cycle	100%				
	Direction of rotation	reversible				

Dimensions **Mounting with screw plate**



Mounting with screw plate



Mounting with snap on clip

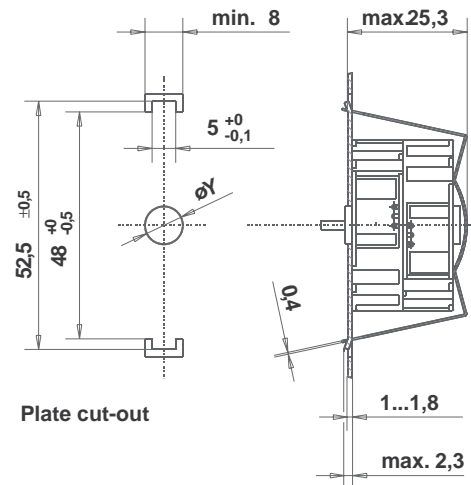


Plate cut-out

$\varnothing D$ Rotor shaft

$\varnothing 2 h6$

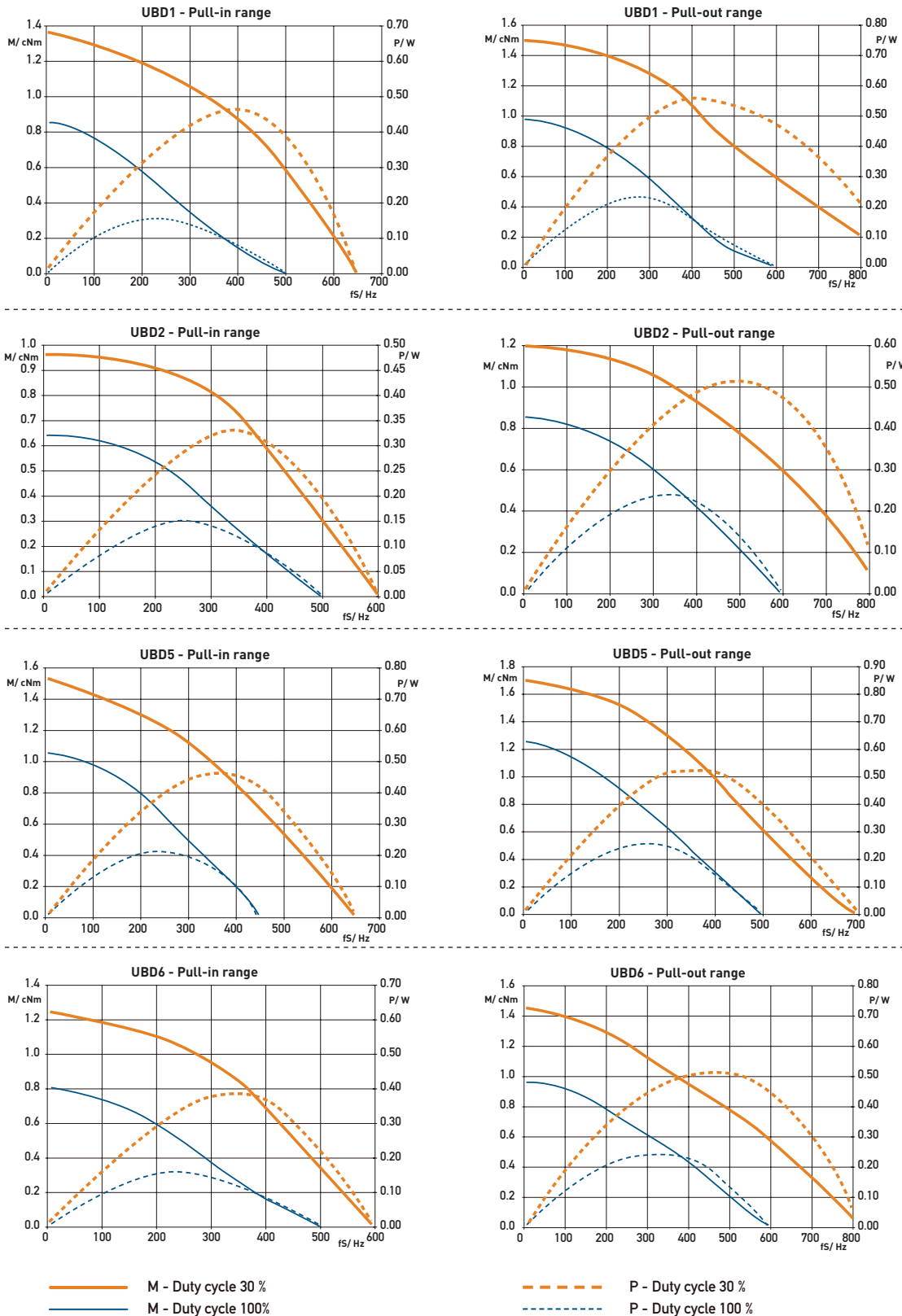
$\varnothing 1.5 js8$

$\varnothing Z$ $\varnothing Y$

8 8F8

10 10F8

Performance Chart



UBB1/2/5/6

Dimensions (mm)	∅ 36 x 21
Step angle (°)	15
Holding torque (cNm)	1.0–1.9
Detent torque (cNm)	0.25/0.36
Winding	bipolar/unipolar
Gear combination	A, D, M, B, F, V



Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15...+55
Ambient temperature storage	°C -20...+100
Thermal resistance at f=0 R _{therm}	27 K/W
Thermal class	A according to DIN EN 60085
Approval	standard (UL/CSA on request)
Mounting	any position
Electrical connection	cable
Protection	IP 40 according to DIN EN 60529
Weight	60 g
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	sintered bronze, self-lubricating
Electric strength	according to DIN EN 60034-1/DIN EN 60335-1

Order Reference

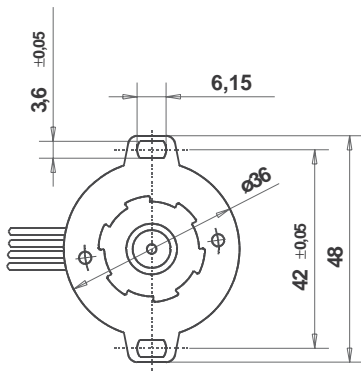
Type	Stepper Motor		UBB	1	0	N	18,5	R	E
Configuration	1	bipolar, standard magnet	5	bipolar, stronger magnet					
	2	unipolar, standard magnet	6	unipolar, stronger magnet					
Rotor shaft, mounting	0	centring 8 mm, shaft 2,0 mm, clip	A	centring 10 mm, shaft 2,0 mm, clip					
	1	centring 8 mm, shaft 1,5 mm, clip	C	centring 10 mm, shaft 1,5 mm, clip					
	3	centring 8 mm, shaft 2,0 mm, screw plate	E	centring 10 mm, shaft 2,0 mm, screw plate					
	4	centring 8 mm, shaft 1,5 mm, screw plate	K	centring 10 mm, shaft 1,5 mm, screw plate					
Approval	N	Approval Standard							
Resistance	See next page Resistance per winding for bipolar or unipolar.								
Direction	reversible								
Cable	E	cable 150 mm (other on request)							

Technical Data

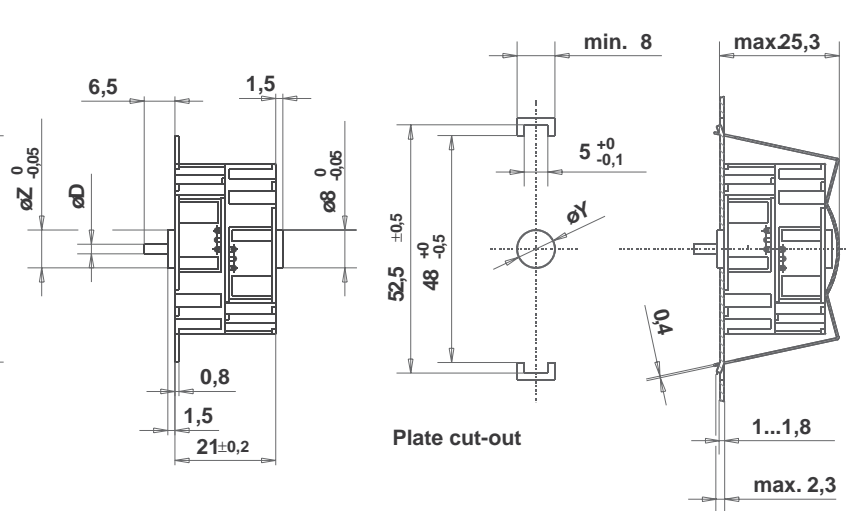
bipolar (UBB1/5)	Rated voltage U_N	V	3	6	12	24
	Resistance per winding R_{20}	Ω	11,5	18,5	100	460
	Holding torque M_H	cNm	1,5 (UBB1); 1,9 (UBB5)			
	Detent torque M_S	cNm	0,25 (UBB1); 0,36 (UBB5)			
	Rotor inertia J_R	gcm^2	2,8 (UBB1); 2,9 (UBB5)			
unipolar (UBB2/6)	Rated voltage U_N	V	3	6	12	24
	Resistance per winding R_{20}	Ω	12	28	120	500
	Holding torque M_H	cNm	1,0 (UBB2); 1,4 (UBB6)			
	Detent torque M_S	cNm	0,25 (UBB2); 0,36 (UBB6)			
	Rotor inertia J_R	gcm^2	2,8 (UBB2); 2,9 (UBB6)			
	Steps per revolution		24			
	Winding temperature T_{max}		105°C			
	Duty cycle		100%			
	Direction of rotation		reversible			

Dimensions

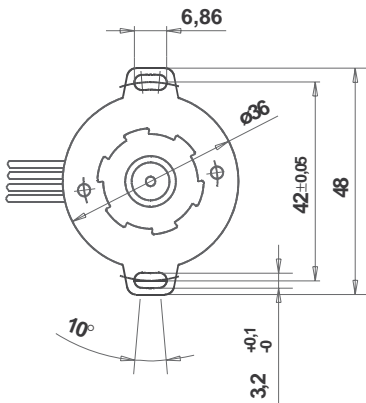
Mounting with screw plate



Mounting with snap on clip



Mounting with screw plate



$\varnothing D$ Rotor shaft

$\varnothing 2$ h6

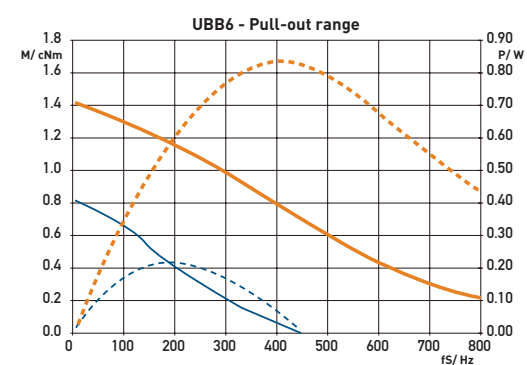
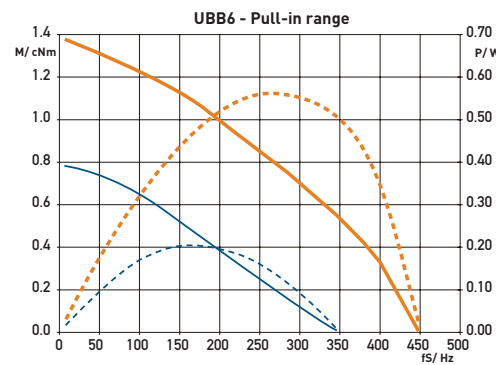
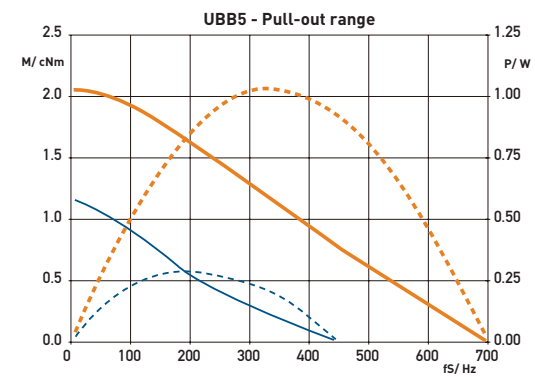
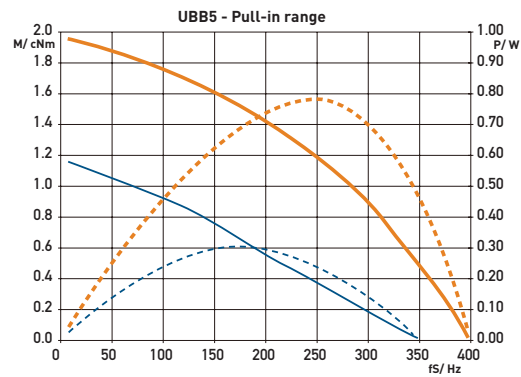
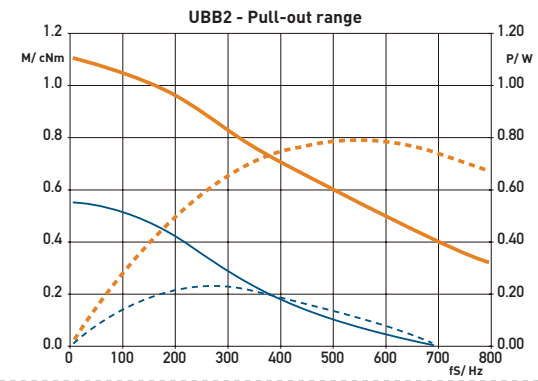
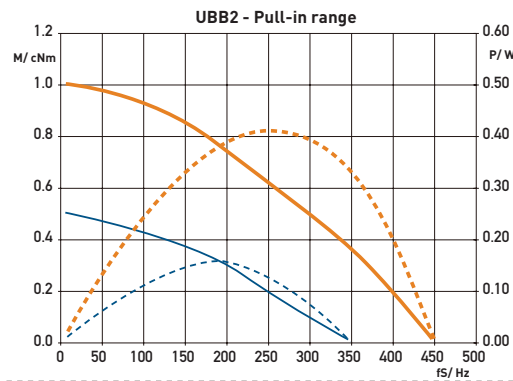
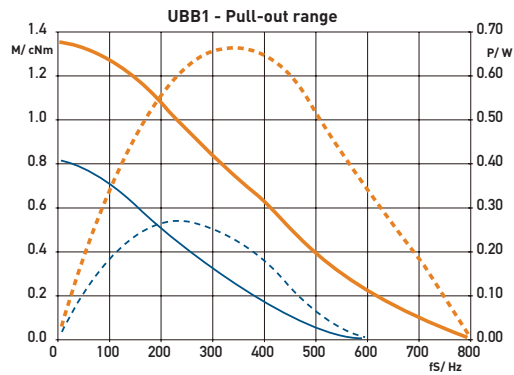
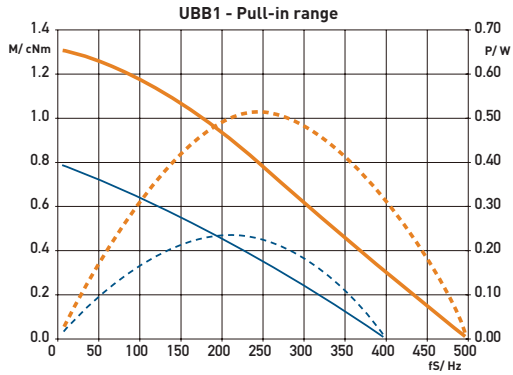
$\varnothing 1.5$ js8

$\varnothing Z$ $\varnothing Y$

8 8F8

10 10F8

Performance Chart



— M - Duty cycle 30 %
— M - Duty cycle 100 %

- - - P - Duty cycle 30 %
- - - P - Duty cycle 100 %

UDB1/2

Dimensions (mm)	∅ 48 x 24
Step angle (°)	15
Holding torque (cNm)	2.7/2.2
Detent torque (cNm)	0.35
Winding	bipolar/unipolar
Gear combination	A, D, M, B, F, V, J



Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15...+60
Ambient temperature storage	°C -20...+100
Thermal resistance at f=0 R _{therm}	18 K/W
Thermal class	A according to DIN EN 60085
Approval	standard
Mounting	any position
Electrical connection	cable
Protection	IP 40 according to DIN EN 60529
Weight	132 g
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	sintered bronze, self-lubricating
Electric strength	according to DIN EN 60034-1/DIN EN 60335-1

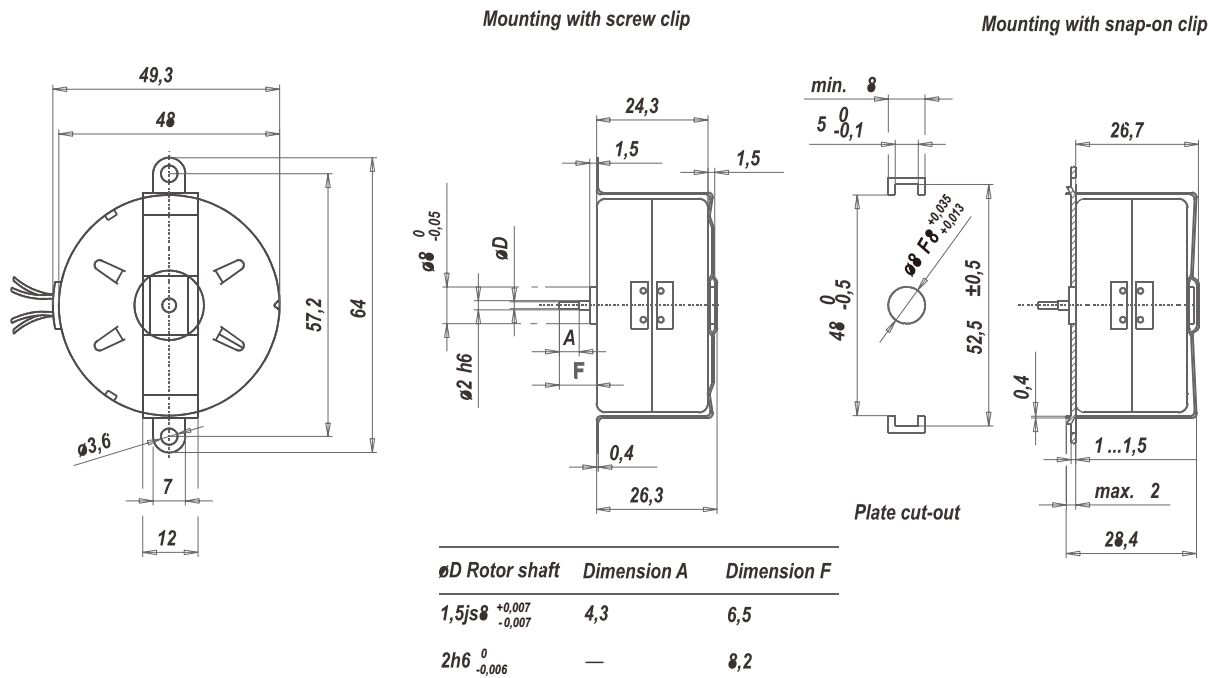
Order Reference

Type	Stepper Motor	UDB	1	0	N	78	R	N
Configuration	1 bipolar 2 unipolar							
Rotor shaft. mounting	0 centring 8 mm, shaft 1,5 mm, clip 1 centring 8 mm, shaft 2,0 mm, clip							
Approval	N Approval Standard							
Resistance	See next page Resistance per winding for bipolar or unipolar.							
Direction	reversible							
Cable	N cable 150 mm (other on request)							

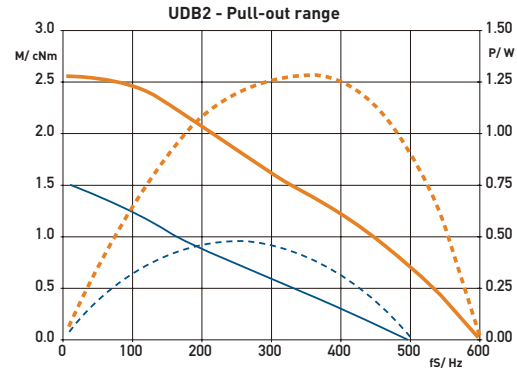
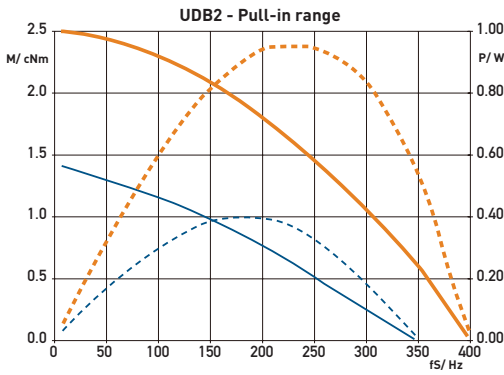
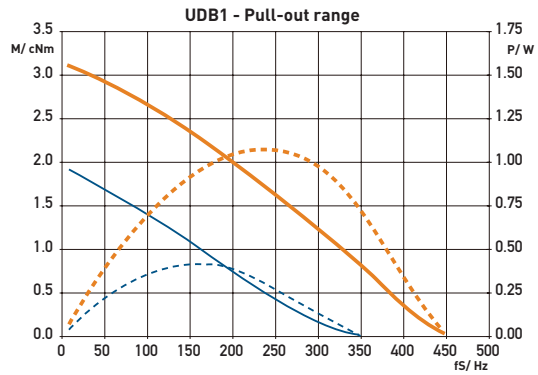
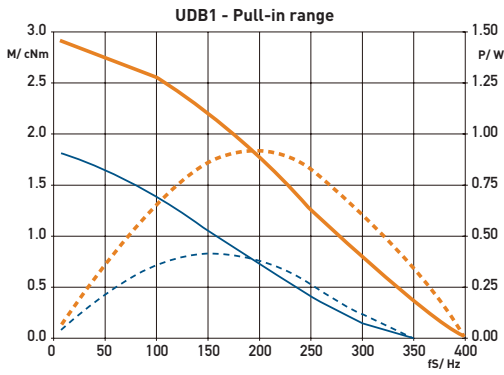
Technical Data

bipolar (UDB1)	Rated voltage U_N	V	6	12	24
	Resistance per winding R_{20}	Ω	15	78	350
	Holding torque M_H	cNm	2.7		
	Detent torque M_S	cNm	0.35		
	Rotor inertia J_R	gcm ²	6.3		
unipolar (UDB2)	Rated voltage U_N	V	6	12	24
	Resistance per winding R_{20}	Ω	19	75	300
	Holding torque M_H	cNm	2.2		
	Detent torque M_S	cNm	0.35		
	Rotor inertia J_R	gcm ²	6.3		
	Steps per revolution		24		
	Winding temperature T_{max}		105° C		
	Duty cycle		100%		
	Direction of rotation		reversible		

Dimensions



Performance Chart



— M - Duty cycle 30 %
 — M - Duty cycle 100%

- - - P - Duty cycle 30 %
 - - - P - Duty cycle 100 %

U0 (ST5021; ST5022)

Dimensions (mm)	∅ 50 x 21
Step angle (°)	7,5/11,25
Holding torque (cNm)	3,7–4 (ST5021); 4 (ST5022)
Detent torque (cNm)	0,25 (ST5021); 1 (ST5022)
Winding	bipolar
Gear combination	O, P, R



Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15 ... +40
Ambient temperature storage	°C -20 ... +100
Thermal class	B (ST5021); A (ST5022) according to DIN EN 60085
Approval	standard
Mounting	any position
Electrical connection	cable
Protection	IP 30 according to DIN EN 60529
Weight	180 g (ST5021); 195 g (ST5022)
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	Sintered bronze, self- lubricating

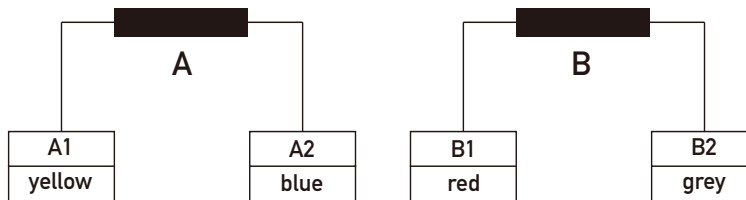
Order Reference

Type	Stepper Motor	ST5021 / ST5022	7,5°	7 Ω
Step angle	7,5° 11,25°			
Resistance	7 Ω			

Technical Data

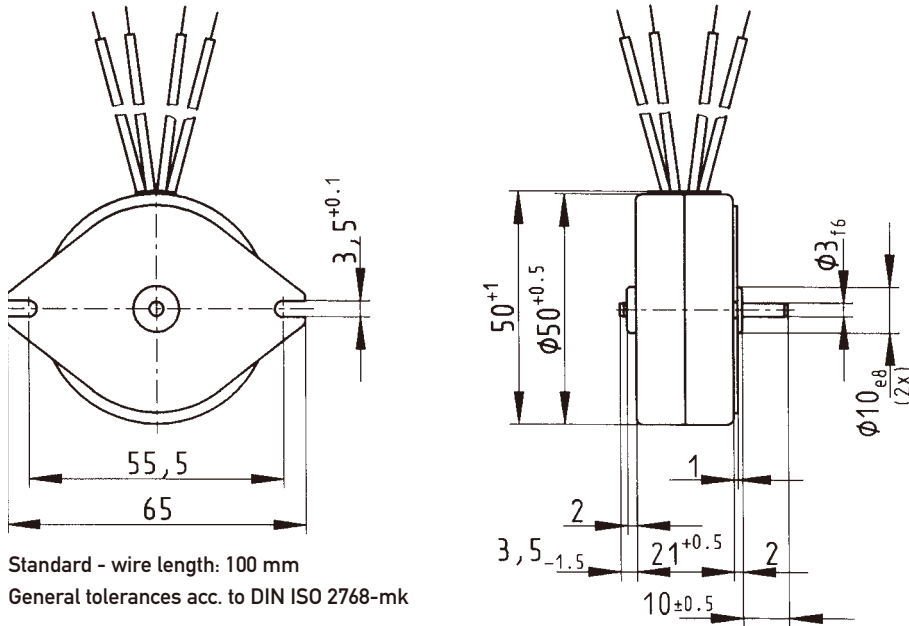
ST5021	Step angle	°	7,5	11,25
	Rated voltage U_N	V	4	4
	Holding torque M_H	cNm	4	3,7
	Detent torque M_s	cNm	0,25	
	Rotor inertia J_R	gcm ²	14,5	
	Winding temperature increase	K	65	
	Current per winding	A	0,53	
	Resistance per winding R_{20}	Ω	7	
	Inductance per winding	mH	12,5	11,5
	Power consumption	W	4	
	Driver mode		Chopper drive	
ST5022	Step angle	°	7,5/11,25	
	Rated voltage U_N	V	4	
	Holding torque M_H	cNm	7,5	
	Detent torque M_s	cNm	1	
	Rotor inertia J_R	gcm ²	25	
	Winding temperature increase	K	65	
	Current per winding	A	0,53	
	Resistance per winding R_{20}	Ω	7	
	Inductance per winding	mH	11	
	Power consumption	W	4	
	Driver mode		Chopper drive	

Circuit diagram Motor connections - bipolar



		clockwise rotation				
A	$\frac{A1}{A2}$	↓	↑	↑	↓	↓
B	$\frac{B1}{B2}$	↑	↑	↓	↓	↑

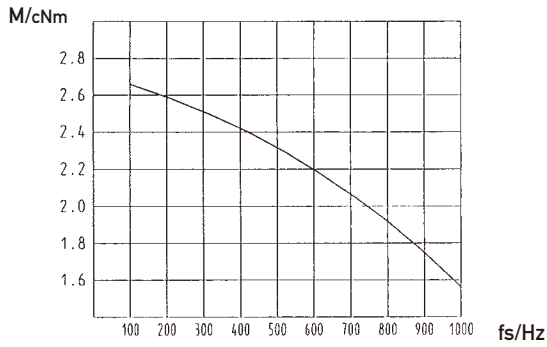
Dimensions



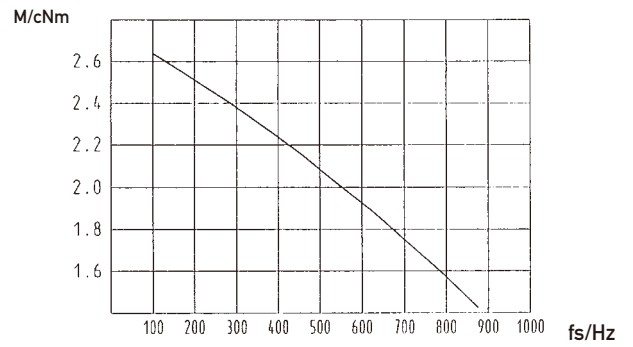
Standard - wire length: 100 mm
General tolerances acc. to DIN ISO 2768-mk

Performance Chart (chopper driver)

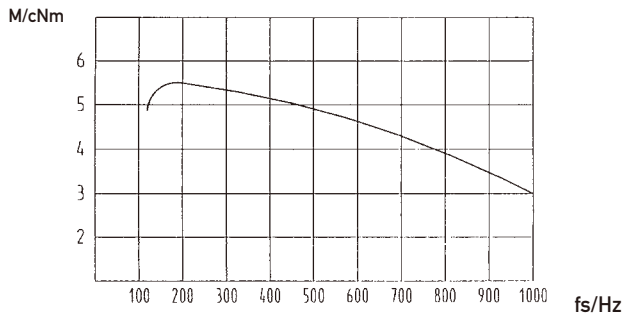
ST5021 UOD1 (ST 5021/7.5/1)



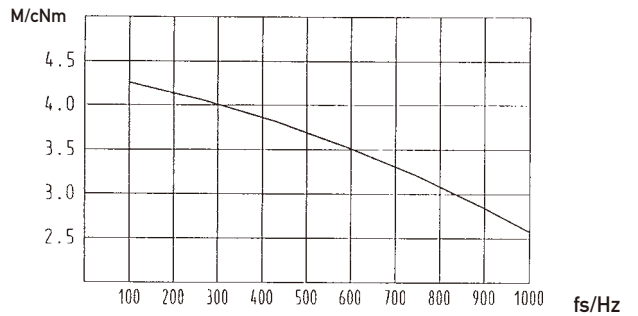
UOJ1 (ST 5021/11.25/1)



ST5022 UOD5 (ST 5022/7.5/1)



UOJ5 (ST 5022/11.25/1)



UFD1/2

Dimensions (mm)	∅ 52 x 28
Step angle (°)	7,5
Holding torque (cNm)	6,4/6,4
Detent torque (cNm)	0,45
Winding	bipolar/unipolar
Gear combination	A, D, M, B, F, V, J, O



Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15...+55
Ambient temperature storage	°C -20...+100
Thermal resistance at f=0 R _{therm}	13 K/W
Thermal class	A according to DIN EN 60085
Approval	standard (UL/CSA on request)
Mounting	any position
Electrical connection	cable
Protection	IP 30 according to DIN EN 60529
Weight	180 g
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	sintered bronze, self-lubricating
Electric strength	according to DIN EN 60034-1/DIN EN 60335-1

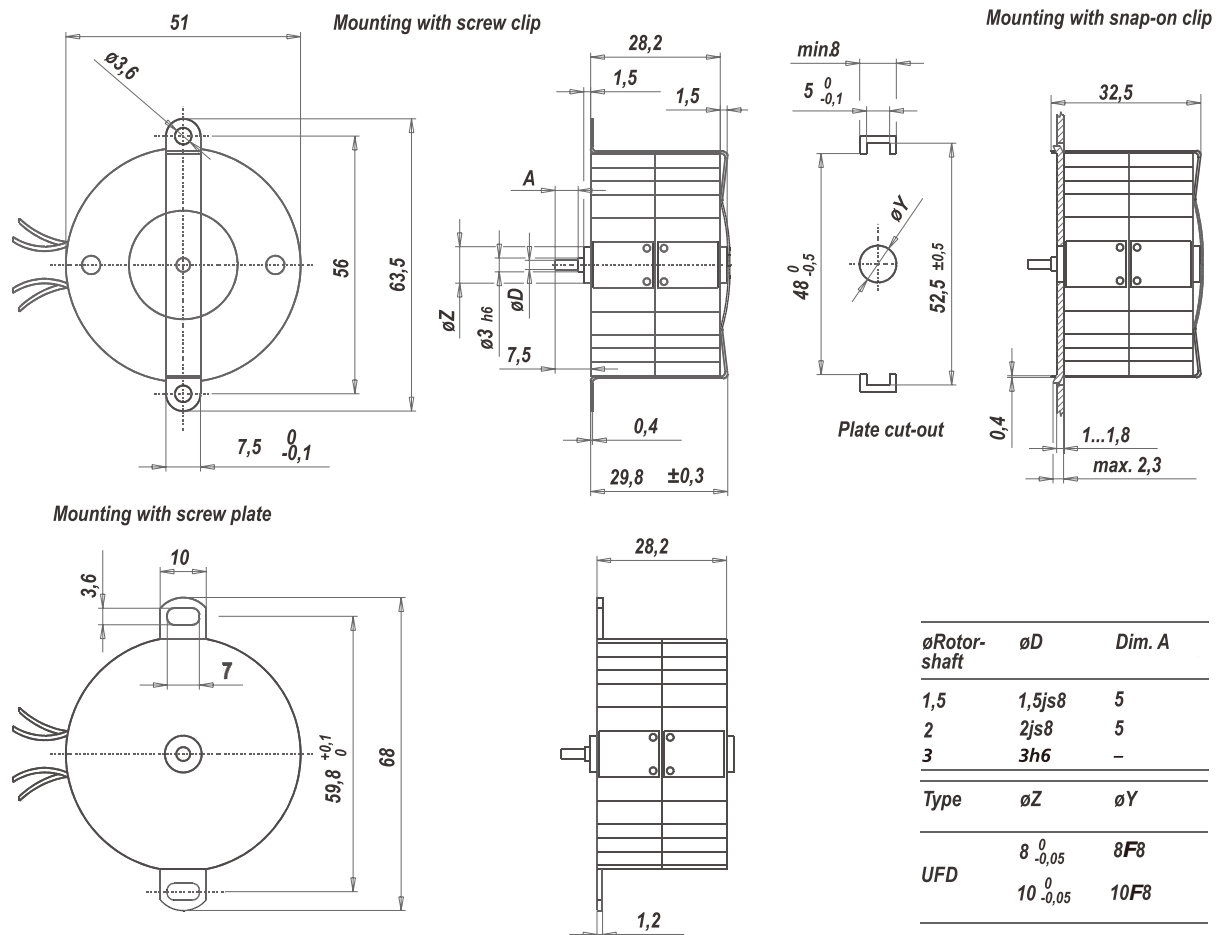
Order Reference

Type	Stepper Motor						UFD	1	0	N	52	R	N
Configuration	1	bipolar, two coils											
	2	unipolar, two coils											
Rotor shaft, mounting	0	centring 8 mm, shaft 3,0 mm, clip			E	centring 10 mm, shaft 3,0 mm, screw plate							
	1	centring 8 mm, shaft 2,0 mm, clip			K	centring 10 mm, shaft 2,0 mm, screw plate							
	2	centring 8 mm, shaft 1,5 mm, clip			M	centring 10 mm, shaft 1,5 mm, screw plate							
	3	centring 8 mm, shaft 3,0 mm, screw plate											
	4	centring 8 mm, shaft 2,0 mm, screw plate											
	5	centring 8 mm, shaft 1,5 mm, screw plate											
Approval	N	Approval Standard											
Resistance	See next page Resistance per winding for bipolar or unipolar.												
Direction	reversible												
Cable	E	cable 150 mm (other on request)											

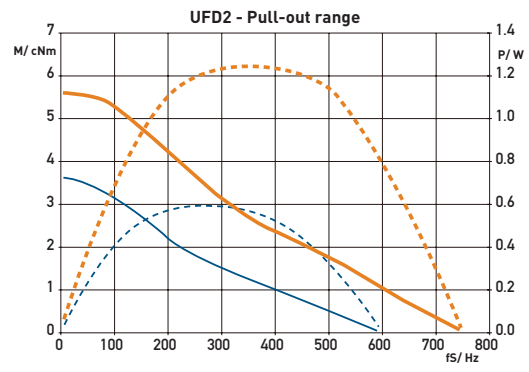
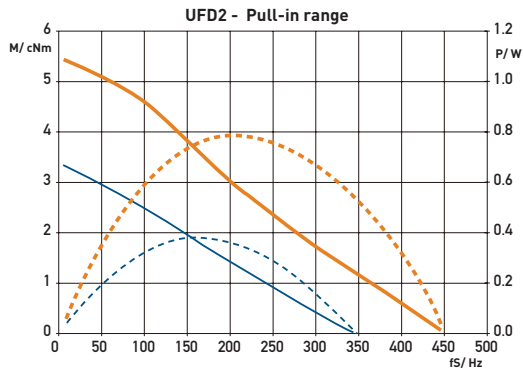
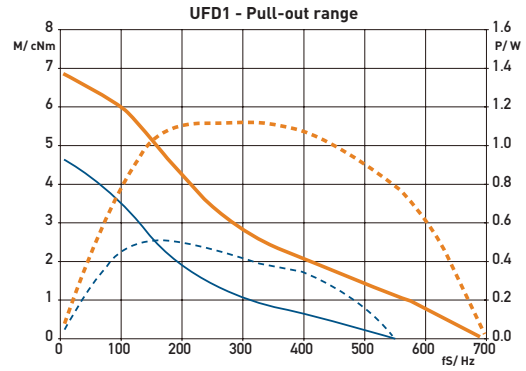
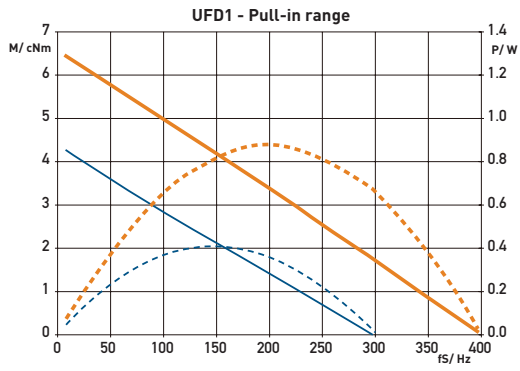
Technical Data

bipolar (UFD1)	Rated voltage U_N	V	6	12	24
	Resistance per winding R_{20}	Ω	9,5	52	250
	Holding torque M_H	cNm	6,4		
	Detent torque M_S	cNm	0,45		
	Rotor inertia J_R	gcm ²	14,4		
unipolar (UFD2)	Rated voltage U_N	V	6	12	24
	Resistance per winding R_{20}	Ω	15	61	251
	Holding torque M_H	cNm	4,6		
	Detent torque M_S	cNm	0,45		
	Rotor inertia J_R	gcm ²	14,4		
	Steps per revolution		48		
	Winding temperature T_{max}		105° C		
	Duty cycle		100%		
	Direction of rotation		reversible		
	Rotor shaft		3, $\varnothing D = 3h6$, Dim. A = „-“		

Dimensions



Performance Chart



— M - Duty cycle 30 %
— M - Duty cycle 100%

- - - P - Duty cycle 30 %
- - - P - Duty cycle 100 %

UFB1/2; UFB3/4

Dimensions (mm)	∅ 52 x 28 / ∅ 52 x 56
Step angle (°)	15
Holding torque (cNm)	45,3–10,4 (UFB1/2); 7,6–10,4 (UFB3/4)
Detent torque (cNm)	0,45 (UFB1/2); 0,8 (UFB3/4)
Winding	bipolar/unipolar
Gear combination	A, D, M, B, F, V, J, O



Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15...+55
Ambient temperature storage	°C -20...+100
Thermal resistance at f=0 R _{therm}	11 K/W (UFB1/2), 7 K/W (UFB3/4)
Thermal class	A according to DIN EN 60085
Approval	standard (UL/CSA on request)
Mounting	any position
Electrical connection	cable
Protection	IP 30 according to DIN EN 60529
Weight	180 g (UFB1/2), 350 g (UFB3/4)
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	sintered bronze, self-lubricating
Electric strength	according to DIN EN 60034-1/DIN EN 60335-1

Order Reference

Type	Stepper Motor		UFB	1	0	N	52 Ω	R	N
Configuration	1	bipolar, two coils	3	bipolar, four coils					
	2	unipolar, two coils	4	unipolar, four coils					
Rotor shaft, mounting	0	centring 8 mm, shaft 3,0 mm, clip	E	centring 10 mm, shaft 3,0 mm, screw plate *					
	1	centring 8 mm, shaft 2,0 mm, clip	K	centring 10 mm, shaft 2,0 mm, screw plate *					
	2	centring 8 mm, shaft 1,5 mm, clip	M	centring 10 mm, shaft 1,5 mm, screw plate *					
	3	centring 8 mm, shaft 3,0 mm, screw plate *	A	centring 12 mm, shaft 3,0 mm, clip					
	4	centring 8 mm, shaft 2,0 mm, screw plate *							
	5	centring 8 mm, shaft 1,5 mm, screw plate *							
Approval	N	Approval Standard							
Resistance	See next page	Resistance per winding for bipolar or unipolar.							
Direction		reversible							
Cable	N	cable 150 mm (other on request)							

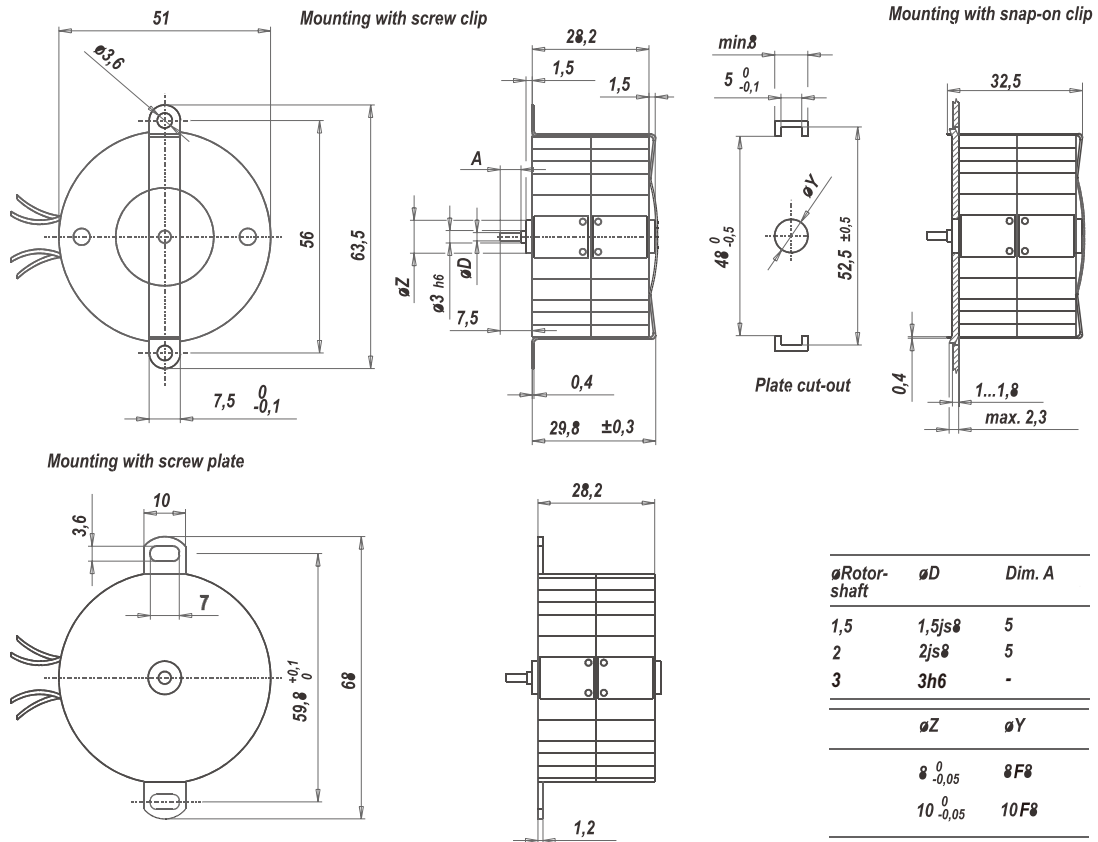
* screw plate not for UFB3 and UFB4

Technical Data

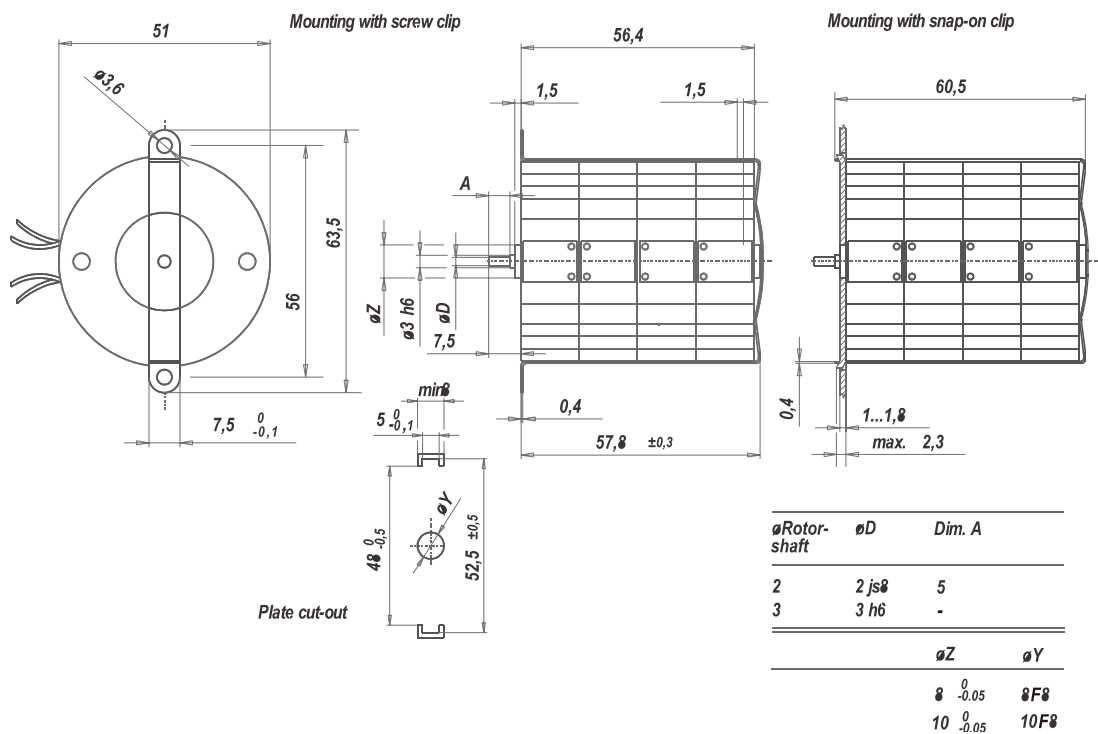
bipolar (UFB1/3)	Rated voltage U_N	V	6	12	24
	Resistance per winding R_{20} (UFB1)	Ω	9,5	52	250
	Resistance per winding R_{20} (UFB3)	Ω	5	25,5	125
	Holding torque M_H	cNm	5,5 (UFB1); 10,4 (UFB3)		
	Detent torque M_S	cNm	0,46 (UFB1); 0,8 (UFB3)		
	Rotor inertia J_R	gcm ²	14,2 (UFB1); 24,2 (UFB3)		
unipolar (UFB2/4)	Rated voltage U_N	V	6	12	24
	Resistance per winding R_{20} (UFB2)	Ω	15	61	251
	Resistance per winding R_{20} (UFB4)	Ω	7,5	30,5	125
	Holding torque M_H	cNm	4,3 (UFB2); 7,6 (UFB4)		
	Detent torque M_S	cNm	0,46 (UFB2); 0,8 (UFB4)		
	Rotor inertia J_R	gcm ²	14,2 (UFB2); 24,2 (UFB4)		
	Steps per revolution		24		
	Duty cycle		100%		
	Winding temperature T_{max}		105° C		
	Direction of rotation		reversible		

Dimensions

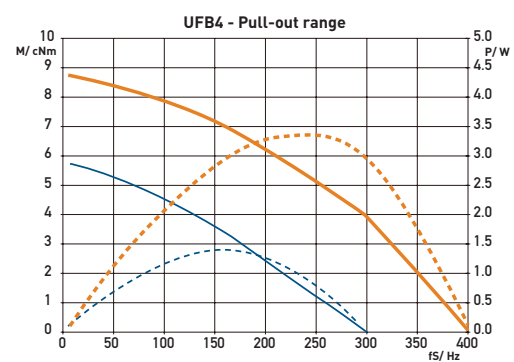
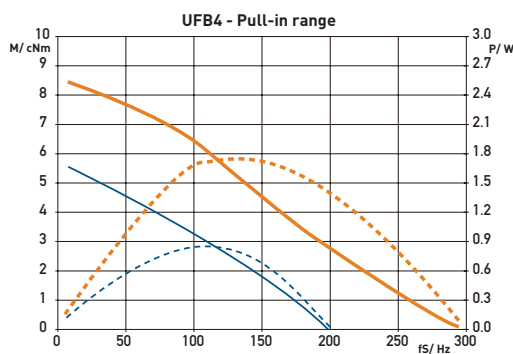
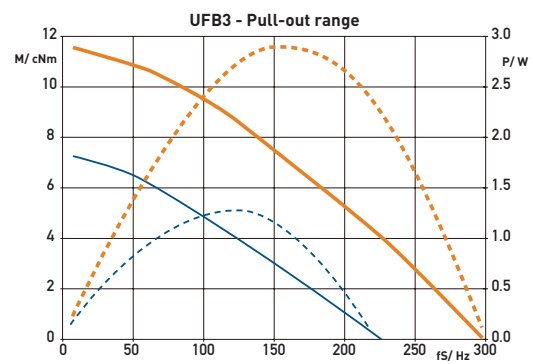
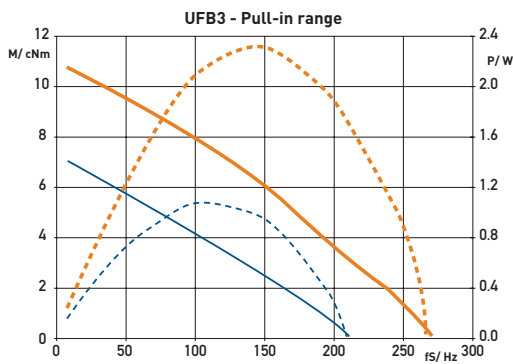
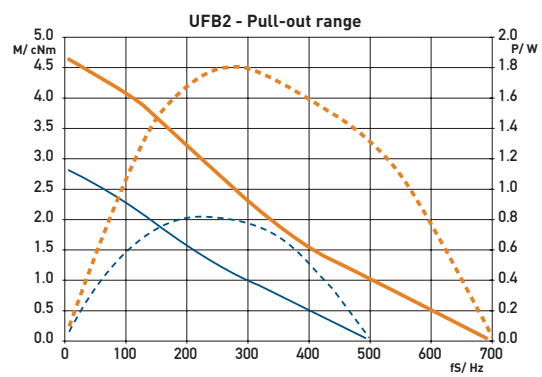
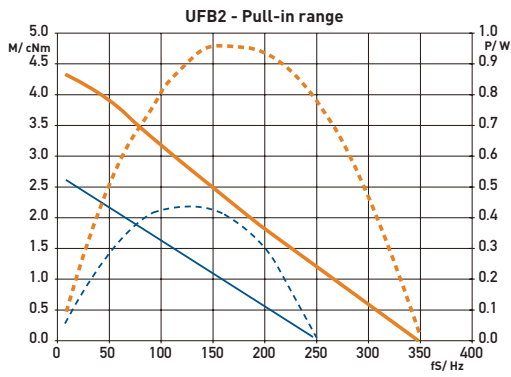
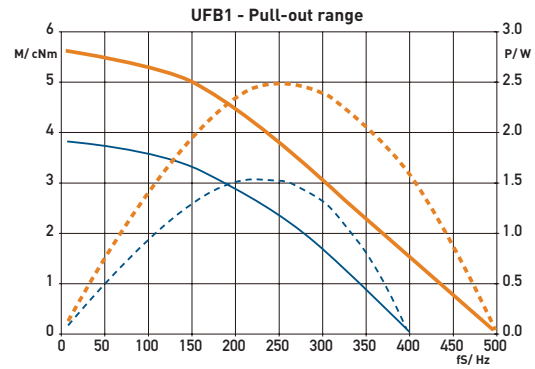
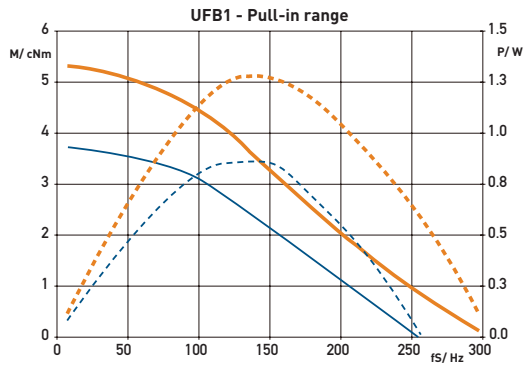
UFB1/2



UFB3/4



Performance Chart



— M - Duty cycle 30 %
— M - Duty cycle 100%

- - - P - Duty cycle 30 %
- - - P - Duty cycle 100%

UHD1/2/5/6; UHD3/4/7/8

Dimensions (mm)	∅ 59 x 35 / ∅ 59 x 70
Step angle (°)	7.5
Holding torque (cNm)	13–24 (UHD1/2/5/6); 27.5–45.5 (UHD3/4/7/8)
Detent torque (cNm)	1.3–2.1 (UHD1/2/5/6); 3.4–5.3 (UHD3/4/7/8)
Winding	bipolar/unipolar
Gear combination	J



Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	-15 ... +55° C
Ambient temperature storage	-20 ... +100° C
Thermal resistance at f=0 (R _{therm})	9 K/W (UHD 1/2/5/6); 6.7 K/W (UHD 3/4/7/8)
Thermal class	A according to DIN EN 60085 (B on request)
Approval	standard (UL/CSA on request)
Mounting	any position
Electrical connection	cable
Protection	IP 30 according to DIN EN 60529
Weight (g)	300 (UHD 1/2/5/6), 580 (UHD 3/4/7/8)
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	sintered bronze, self-lubricating
Electric strength	according to DIN EN 60034-1/DIN EN 60335-1

Order Reference

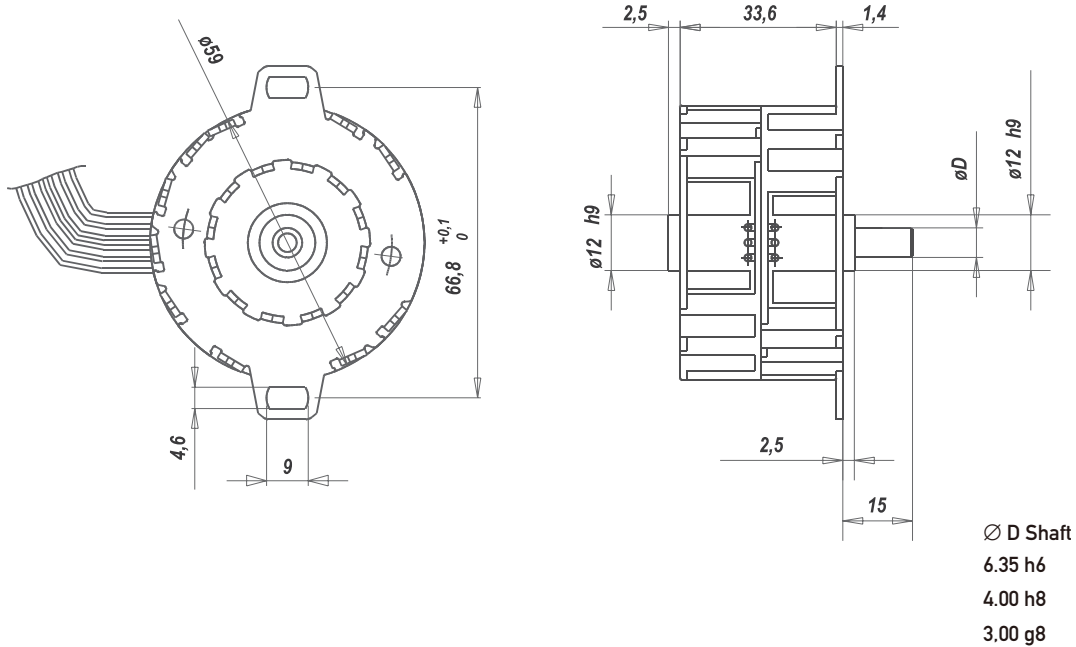
Type	Stepper Motor		UHD	1	0	N	36	R	N	
Configuration	1	bipolar, two coils, standard magnet	3	bipolar, four coils, standard magnet	4	unipolar, two coils, standard magnet	7	bipolar, four coils, stronger magnet	8	unipolar, four coils, stronger magnet
Rotor shaft, mounting	0	centring 12 mm, shaft 6.35 mm, clip **	3	centring 12 mm, shaft 6.35 mm, screw plate*	1	centring 12 mm, shaft 4.0 mm, clip **	4	centring 12 mm, shaft 4.0 mm, screw plate*	2	centring 12 mm, shaft 3.0 mm, clip **
Approval	N	Standard								
Resistance	see next pages Resistance per winding for bipolar or unipolar.									
Direction	reversible									
Cable	N	cable 150 mm (other on request)								

* not for UHD3/4/7/8
 ** not for UHD1/2/5/6

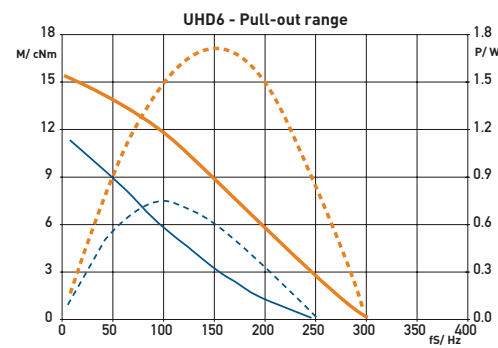
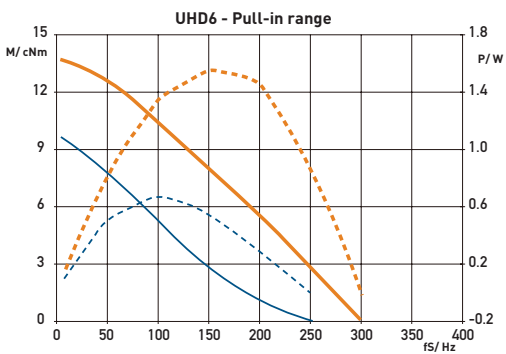
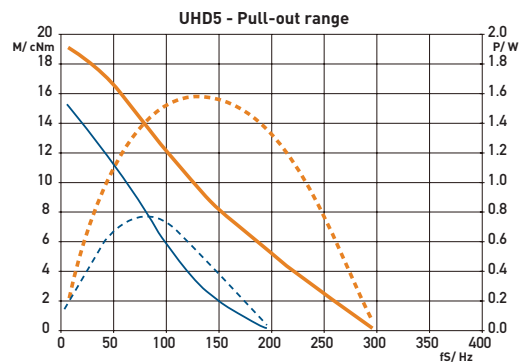
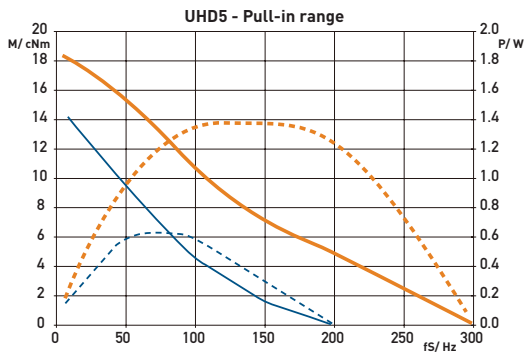
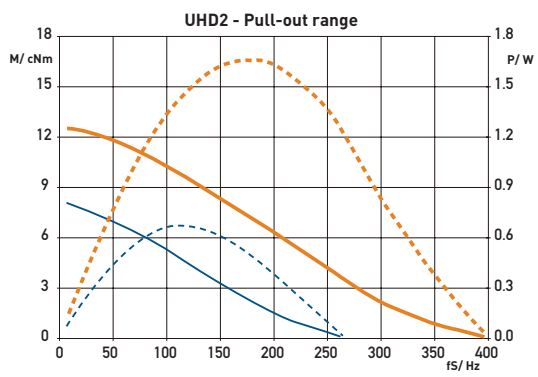
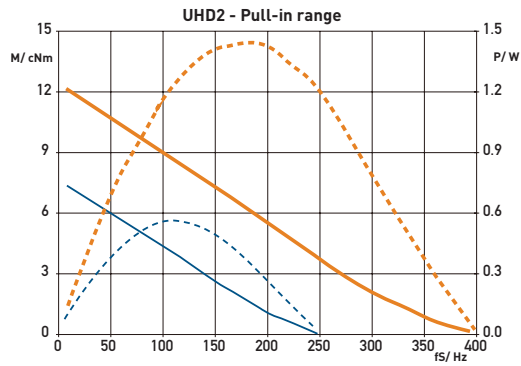
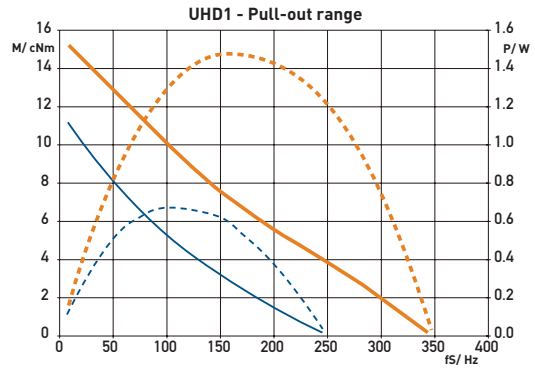
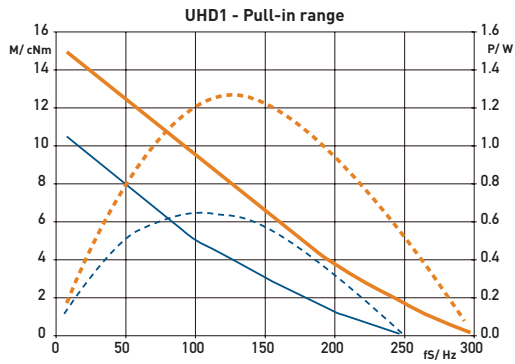
Technical Data UHD1/2/5/6

bipolar (UHD1/5)	Rated voltage U_N	V	6	12	24
	Resistance per winding R_{20}	Ω	6,8	36	168
	Holding torque	cNm	17,1 (UHD1); 24 (UHD5)		
	Detent torque M_S	cNm	1.3 (UHD1/2); 2.1 (UHD5/6)		
	Rotor inertia J_R	gcm^2	49 (UHD1/2); 56 (UHD5/6)		
unipolar (UHD2/6)	Rated voltage U_N	V	6	12	24
	Resistance per winding R_{20}	Ω	10	45	190
	Holding torque	cNm	13 (UHD2); 17.3 (UHD6)		
	Detent torque M_S	cNm	1.3 (UHD1/2); 2.1 (UHD5/6)		
	Rotor inertia J_R	gcm^2	49 (UHD1/2); 56 (UHD5/6)		
	Steps per revolution		48		
	Duty cycle		100%		
	Winding temperature T_{max}		130° C		
	Direction of rotation		reversible		

Dimensions



Performance Chart



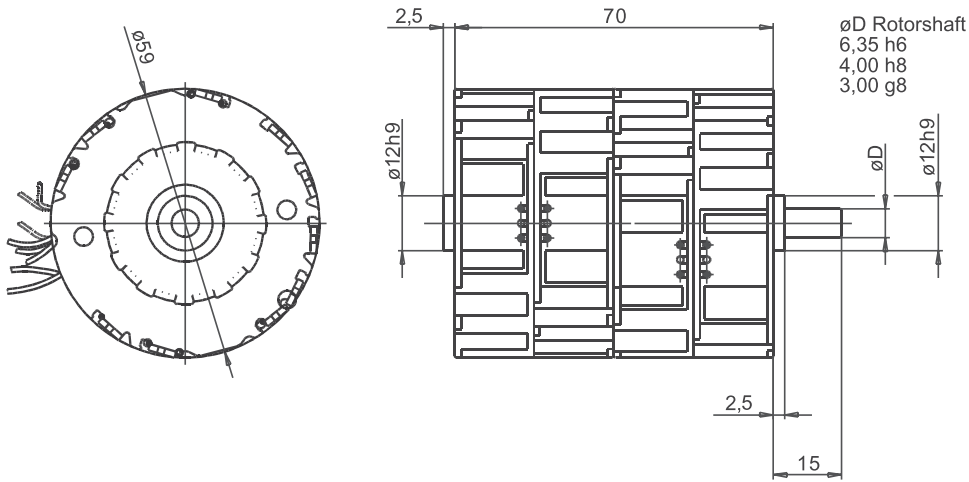
— M - Duty cycle 30 %
— M - Duty cycle 100 %

- - - P - Duty cycle 30 %
- - - P - Duty cycle 100 %

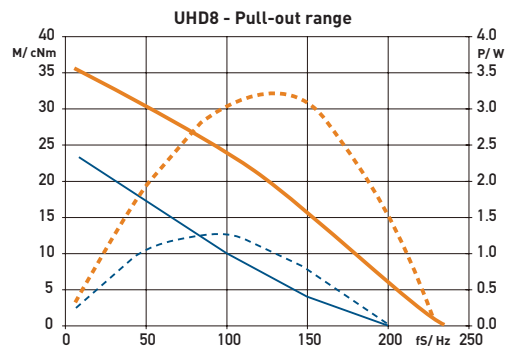
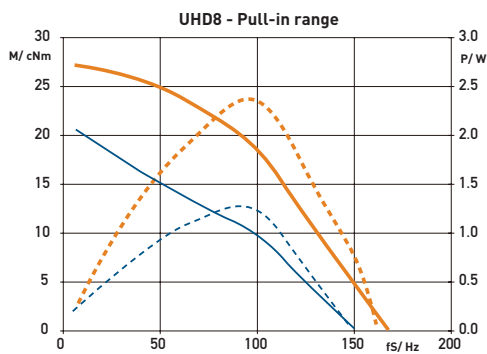
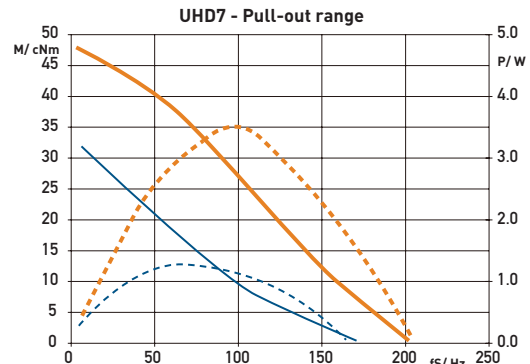
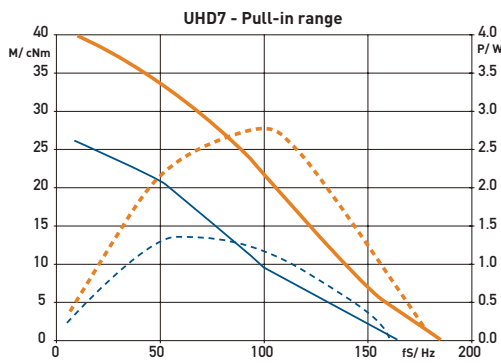
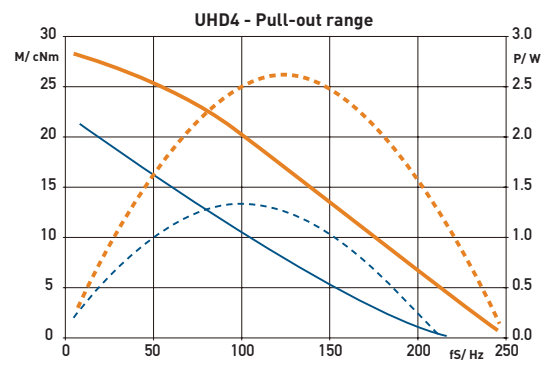
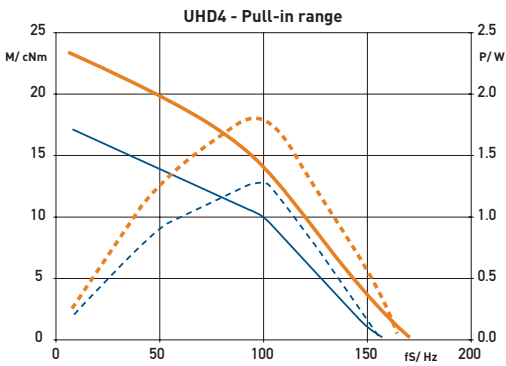
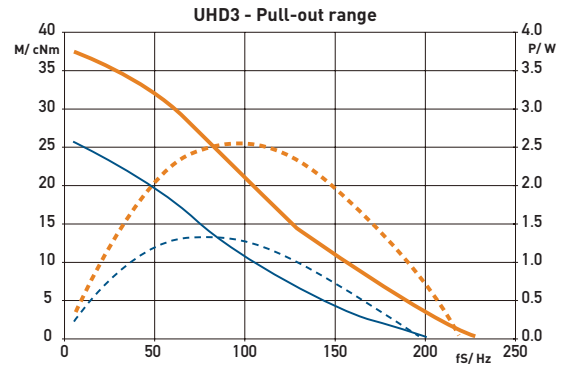
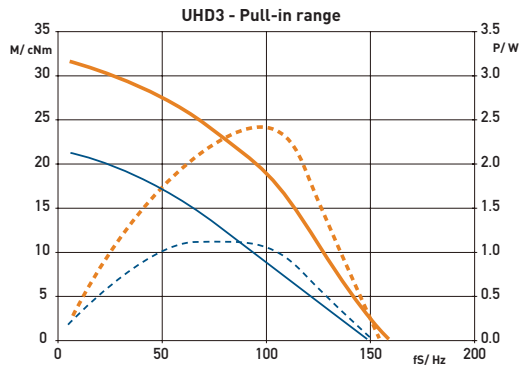
Technical Data UHD3/4/7/8

bipolar (UHD3/7)	Rated voltage U_N	V	12	24	48
	Resistance per winding R_{20}	Ω	20	108	460
	Holding torque	cNm	37,5 (UHD3); 45,5 (UHD7)		
	Detent torque M_s	cNm	3,4 (UHD3/4); 5,3 (UHD7/8)		
	Rotor inertia J_R	gcm^2	135 (UHD3/4); 141 (UHD7/8)		
unipolar (UHD4/8)	Rated voltage U_N	V	6	12	24
	Resistance per winding R_{20}	Ω	6,75	28,5	120
	Holding torque	cNm	27,5 (UHD4); 33,5 (UHD8)		
	Detent torque M_s	cNm	3,4 (UHD3/4); 5,3 (UHD7/8)		
	Rotor inertia J_R	gcm^2	135 (UHD3/4); 141 (UHD7/8)		
Steps per revolution			48		
Duty cycle			100%		
Winding temperature T_{max}			130° C		
Direction of rotation			reversible		

Dimensions



Performance Chart



— M - Duty cycle 30 %
— M - Duty cycle 100 %

- - - P - Duty cycle 30 %
- - - P - Duty cycle 100 %

UP (ST6443; ST6444)

Dimensions (mm)	∅ 64 x 43
Step angle (°)	7,5/11,25 (ST6443); 11,25 (ST6444)
Holding torque (cNm)	30–35 (ST6443); 45 (ST6444)
Detent torque (cNm)	2–2,5 (ST6443); 7 (ST6444)
Winding	bipolar
Gear combination	O, P, R



Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15 ... +40
Ambient temperature storage	°C -20 ... +100
Thermal resistance at f=0 R _{therm}	29 K/W
Thermal class	B (ST6443); A (ST6444) according to DIN EN 60085
Approval	standard
Mounting	any position
Electrical connection	cable
Protection	IP 30 according to DIN EN 60529
Weight	500 g (ST6443); 550 g (ST6444)
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	Sintered bronze, self-lubricating

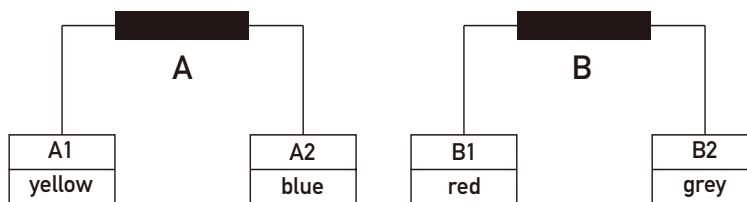
Order Reference

Type	Stepper Motor	ST6443 / ST6444	7,5°	3,7 Ω
Step angle	7,5° (ST6443) 11,25° (ST6443 / ST6444)			
Resistance	3,7 Ω			

Technical Data

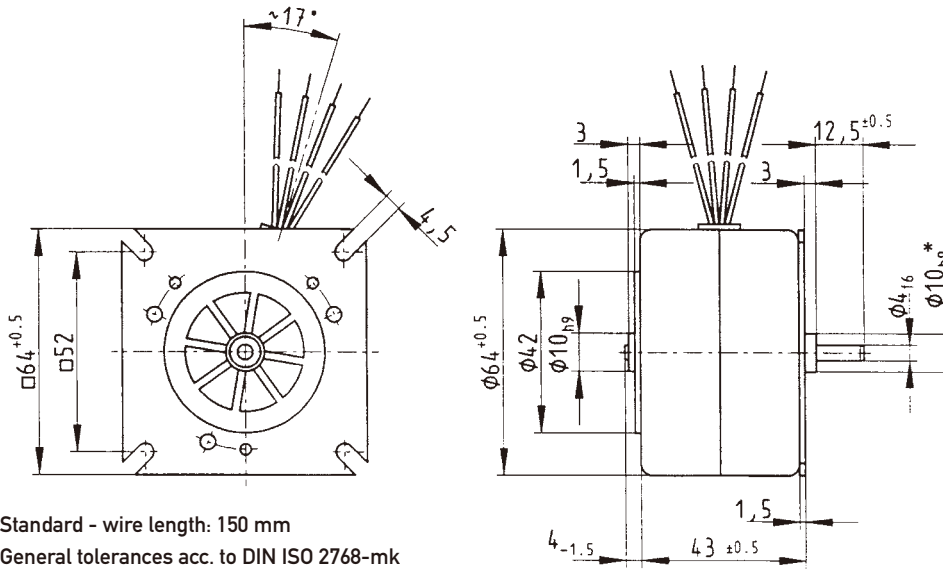
bipolar (ST6443)	Rated voltage U_N	V	4,5	4,5	
	Resistance per winding R_{20}	Ω	3,7		
	Step angle	$^\circ$	7,5	11,25	
	Holding torque M_H	cNm	35	30	
	Detent torque M_S	cNm	2,5	2	
	Rotor inertia J_R	gcm^2	85		
	Steps per revolution			48	32
	Winding temperature increase	K	90		
	Current per winding	A	1,25		
	Inductance per winding	mH	10	9,5	
	Power consumption	W	11,5		
	Driver mode		Chopper drive		
	bipolar (ST6444)	Rated voltage U_N	V	4,5	
Resistance per winding R_{20}		Ω	3,7		
Step angle		$^\circ$	11,25		
Holding torque M_H		cNm	45		
Detent torque M_S		cNm	7		
Rotor inertia J_R		gcm^2	180		
Steps per revolution			32		
Winding temperature increase		K	90		
Current per winding		A	1,25		
Inductance per winding		mH	8		
Power consumption		W	11,5		
Driver mode			Chopper drive		

Circuit diagram Motor connections - bipolar



		clockwise rotation				
A	$\frac{A1}{A2}$	↓	↑	↑	↓	↓
B	$\frac{B1}{B2}$	↑	↑	↓	↓	↑

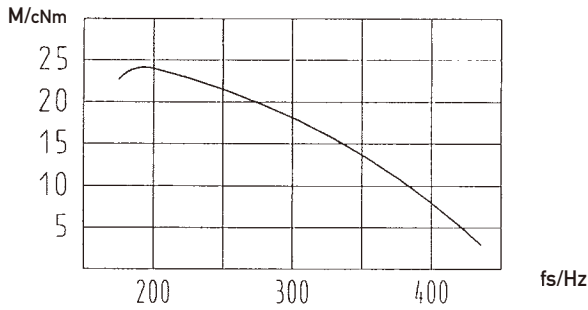
Dimensions



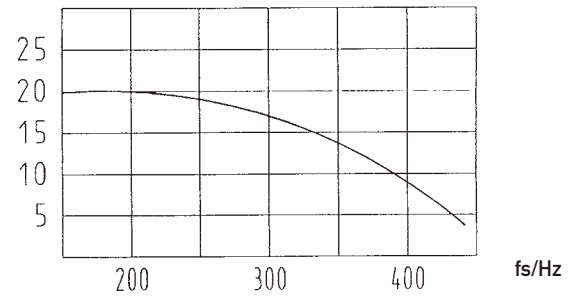
* on request 14h9

Performance Chart (chopper driver)

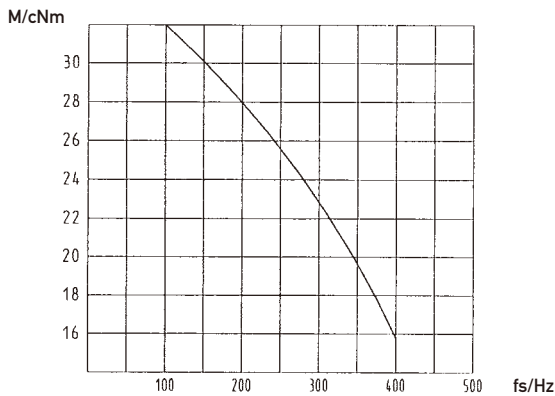
ST6443 UPD1 (ST6443/7.5/1)



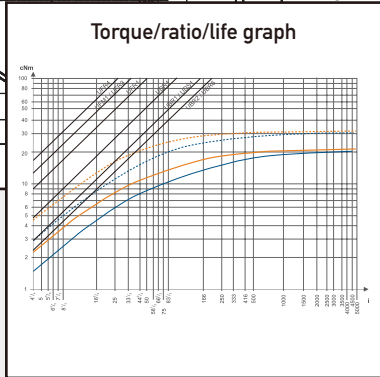
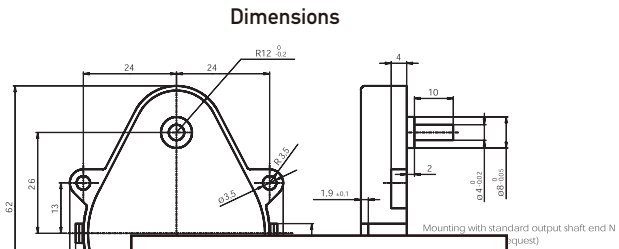
UPJ1 (ST 6443/11.25/1)



ST6444 UPJ5 (ST 6444/11.25)



Gearboxes for Motors



UGA

Dimensions (mm)	55 x 62
Hight (mm)	12
Max. torque (cNm)	32
Ratios	4 1/6 ... 360.000
Internal slipping clutch	optional
Standard shaft (mm)	∅ 4 x 10
Weight (g)	55
Motor combination	Series UB and UD; Series UF without UFR3/4 and UFB3/4



Standard Data

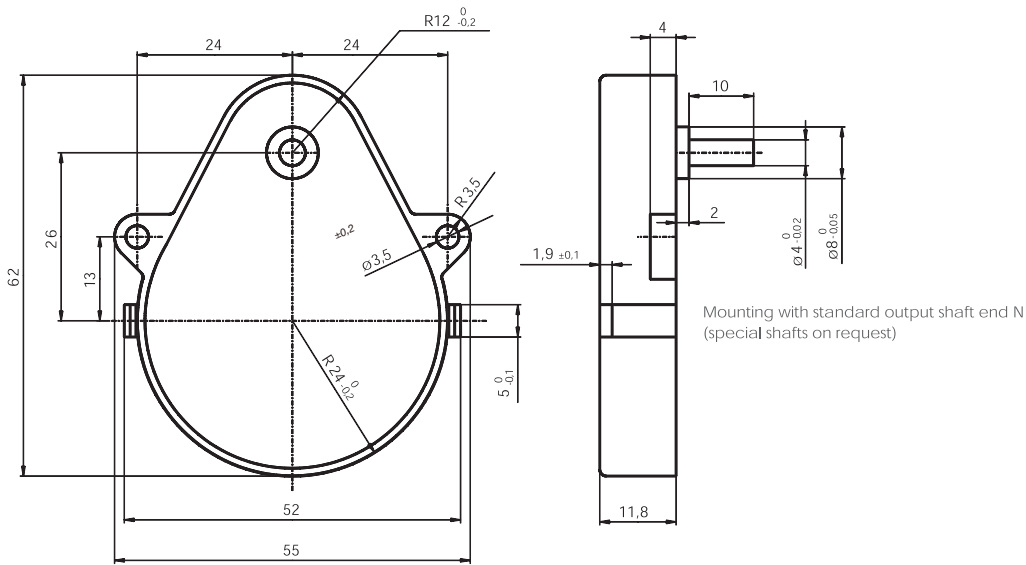
Mounting	any position
Axial thrust F_A	20 N
Lateral force F_R	60 N
Slipping clutches/free wheel	single-way clockwise/counter clockwise function and two way
Slipping-/free wheel torque	0,5 ... 40 cNm
Output shafts	∅ 4 x 10, other on request
Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	-15 ... +55° C
Ambient temperature storage	-40 ... +80° C

Ratios	4 1/6	5	8 1/6	10	12 1/2	15	16 2/3	20 5/6	25	30	31 1/4	33 1/3	37 1/2
	41 2/3	45	50	60	62 1/2	75	83 1/3	100	112 1/2	120	125	135	140 5/8
	150	166 2/3	187 1/2	200	250	277 7/8	300	375	416 2/3	450	500	600	625
	750	900	937 1/2	1000	1125	1200	1250	1500	1800	1875	2250	2500	3000
	3600	3750	4500	5000	5400	7200	7500	9000	11250	12000	12500	15000	18000
	18750	22500	27000	300000	36000	375000	450000	54000	60000	72000	75000	90000	108000
	112500	120000	135000	150000	180000	216000	240000	360000					

Order Reference

Type	Gearbox	UGA	100	N	5cNm	N
Ratio	100					
Slipping clutch	N Without slipping clutch ER One-way slipping clutch, clockwise EL One-way slipping clutch, counter clockwise Z Two-way slipping clutch					
Slipping torque	5 cNm					
Shaft end	N ∅ 4 x 10, other on request					

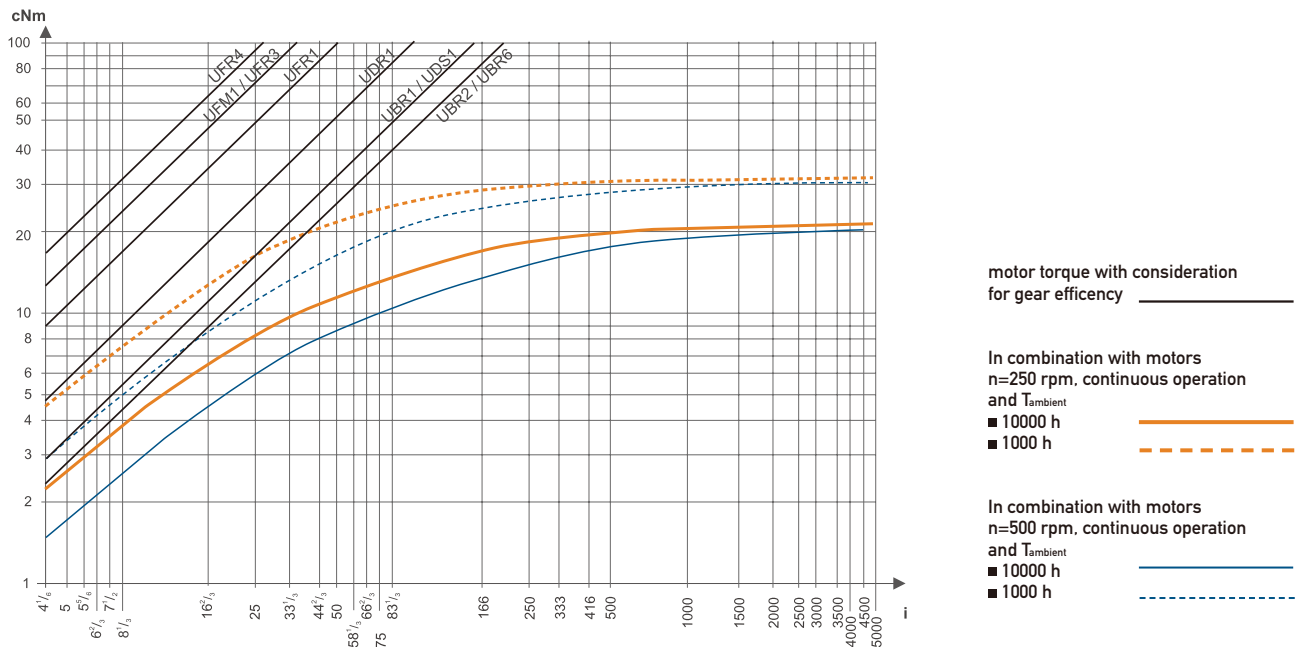
Dimensions



Slipping clutches

	max. torque available at output shaft (cNm)	free wheel- / clutch torque (cNm)
Roller-type free wheel	32	0,5 ... 1
Single-way slipping clutches	32	2 ... 40 (counter clockwise or clockwise direction possible)
Two-way slipping clutches	1,5 ... 10	2 ... 36

Torque / ratio / life graph



UGD

Dimensions (mm)	55 x 65,6
Hight (mm)	13
Max. torque (cNm)	32
Ratios	4 1/6 ... 6.048.000
Internal slipping clutch	optional
Standard shaft (mm)	∅ 4 x 10
Weight (g)	35
Motor combination	Series UB and UD; Series UF without UFR3/4 and UFB3/4



Standard Data

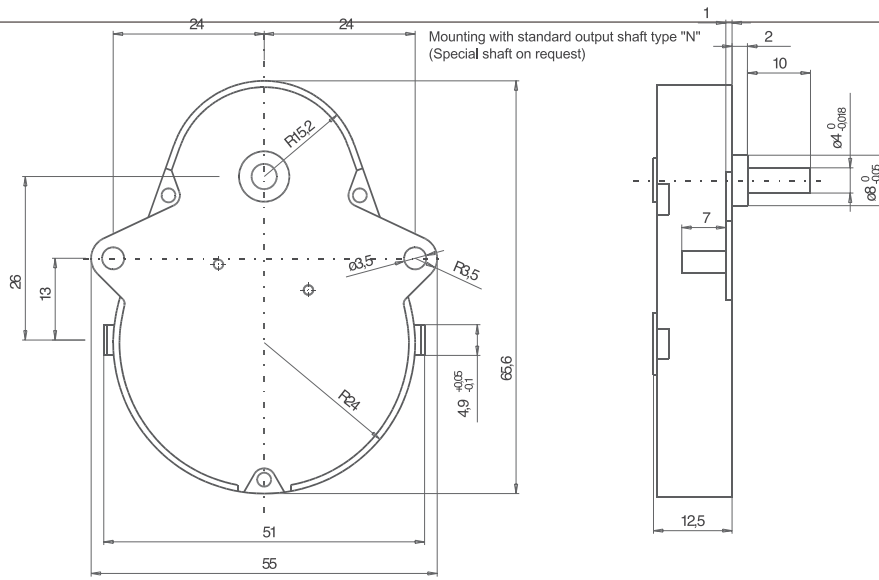
Mounting	any position
Axial thrust F_A	10 N
Lateral force F_R	50 N
Slipping clutches/free wheel	single-way clockwise/counter clockwise function and two way
Slipping-/free wheel torque	1 ... 40 cNm
Output shafts	∅ 4 x 10, other on request
Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15 ... +55
Ambient temperature storage	°C -40 ... +80

Ratios	4 1/6	5	8 1/3	10	12 1/2	15	16 2/3	20 5/6	25	30	33 1/3	40	41 2/3
	45	50	60	62 1/2	83 1/3	100	120	125	150	166 2/3	200	250	300
	375	500	600	625	750	900	1000	1200	1500	1800	2000	2400	2500
	3000	3600	3750	4500	5000	6000	7500	9000	10000	15000	18000	21600	22500
	30000	36000	45000	54000	60000	72000	90000	108000	112500	120000	180000	216000	225000
	270000	300000	360000	432000	450000	720000	864000	1800000	5040000	6048000			

Order Reference

Type	Gearbox	UGD	100	N	5cNm	N
Ratio	100					
Slipping clutch	N Without slipping clutch ER One-way slipping clutch, clockwise EL One-way slipping clutch, counter clockwise Z Two-way slipping clutch					
Slipping torque	5 cNm					
Shaft end	N ∅ 4 x 10, other on request					

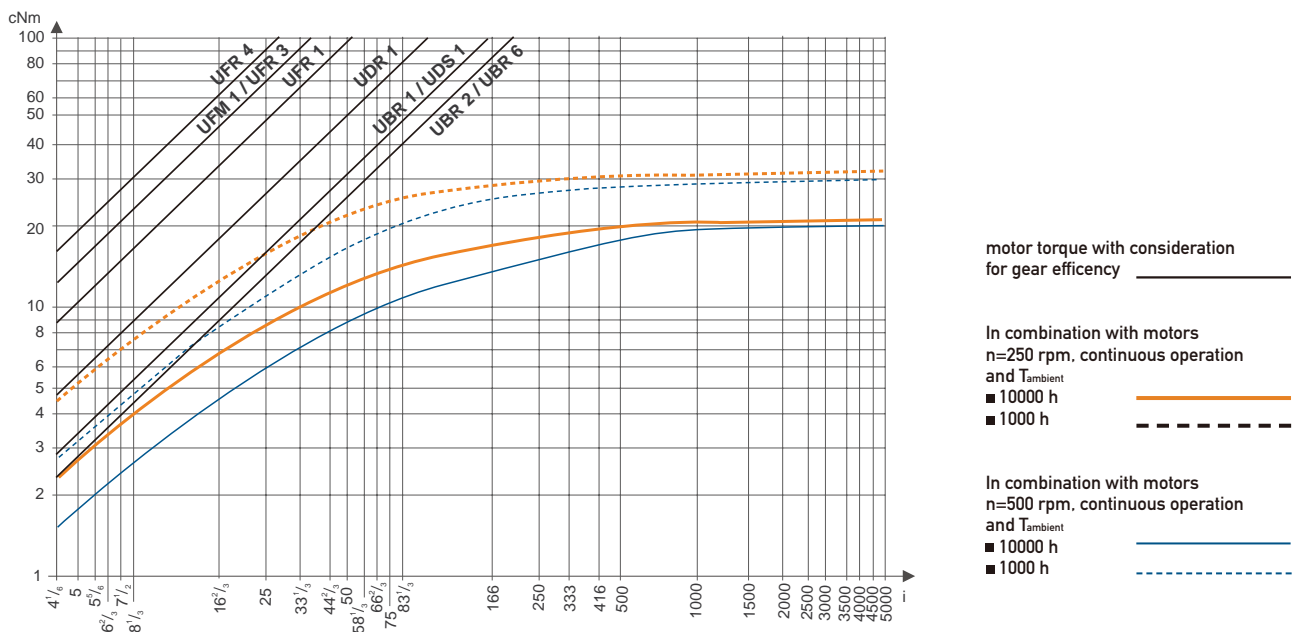
Dimensions



Slipping clutches

	max. torque available at output shaft (cNm)	free wheel-/clutch torque (cNm)
Roller-type free wheel	32	1
Single-way slipping clutches	32	4 ... 25 counter clockwise or clockwise function
Two-way slipping clutches	3 ... 15	4 ... 40

Torque / ratio / life graph



UGM

Dimensions (mm)	51 x 65.2
Hight (mm)	15
Max. torque (cNm)	100
Ratios	12.5 ... 4800
Internal slipping clutch	none
Standard shaft (mm)	∅ 4 x 10
Weight (g)	45
Motor combination	Series UB and UD; Series UF without UFR3/4 and UFB3/4



Standard Data

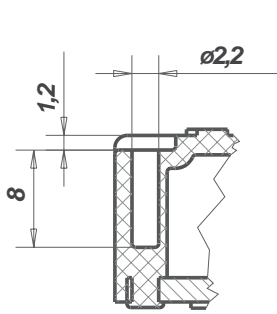
Mounting	any position
Axial thrust F_A	20 N
Lateral force F_R	100 N
Output shafts	∅ 4 x 10, other on request
Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15 ... +60
Ambient temperature storage	°C -40 ... +80

Ratios	12 1/2	16 2/3	25	50	100	120	150	200	240	300	400	500	600
	750	1000	1200	1500	4800								

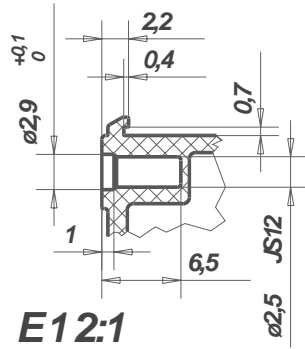
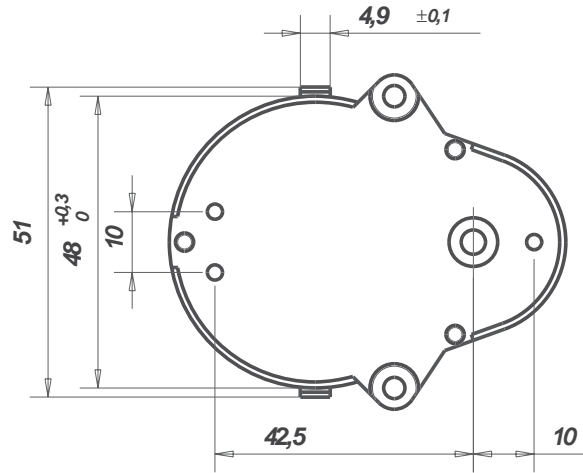
Order Reference

Type	Gearbox	UGM	100	N	N
Ratio	100				
Slipping clutch	N Without slipping clutch				
Shaft end	N ∅ 4 x 10, other on request				

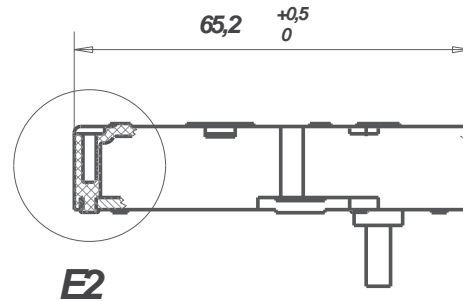
Dimensions



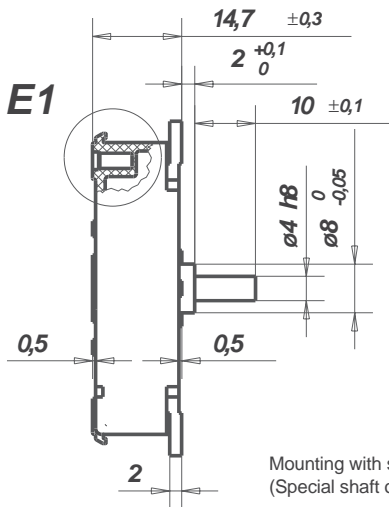
E22:1



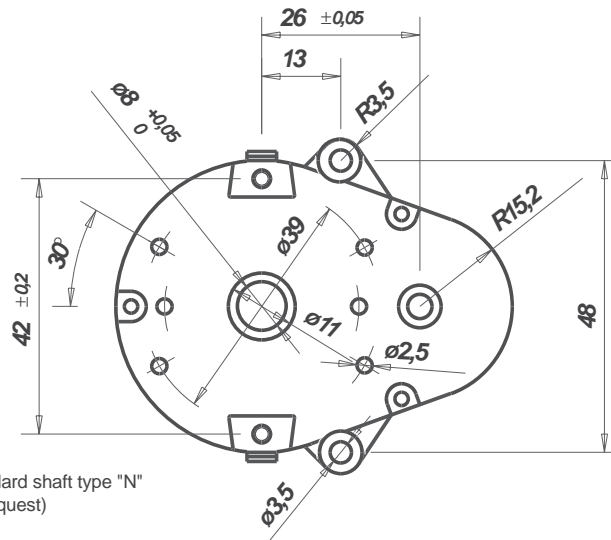
E12:1



E2

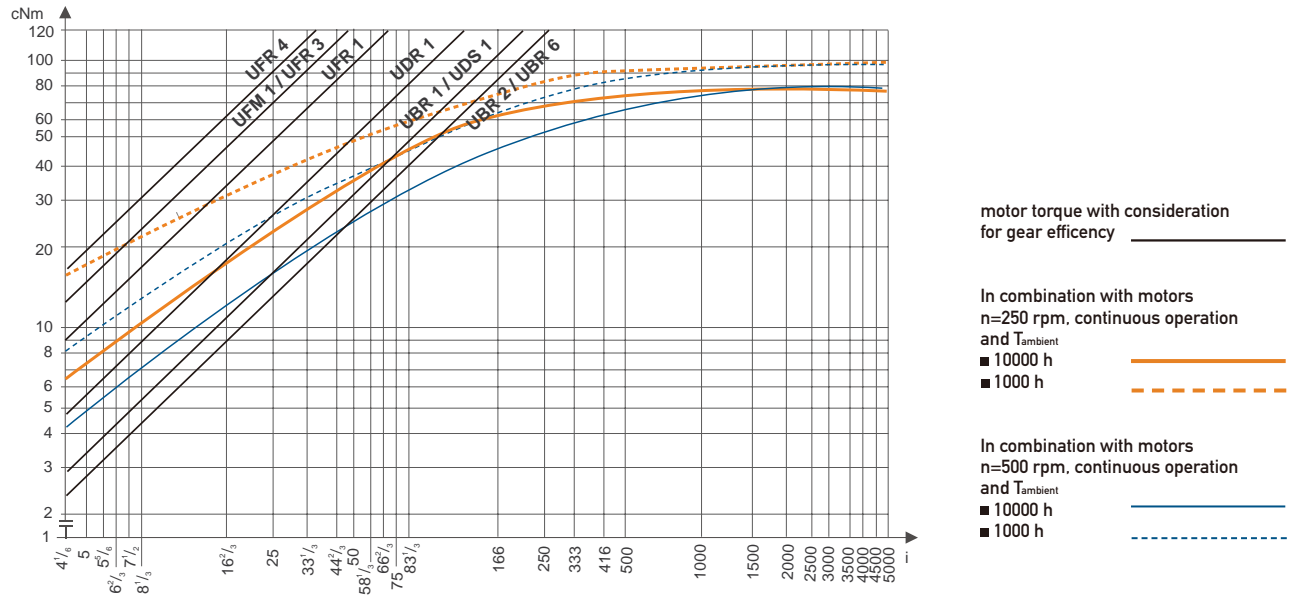


E1



Mounting with standard shaft type "N"
(Special shaft on request)

Torque / ratio / life graph



UGB

Dimensions (mm)	58 x 81
Hight (mm)	17
Max. torque (cNm)	250
Ratios	41 ^{2/3} ... 345.600
Internal slipping clutch	optional
Standard shaft (mm)	∅ 8 x 12
Weight (g)	130
Motor combination	Series UB and UD; Series UF without UFR3/4 and UFB3/4



Standard Data

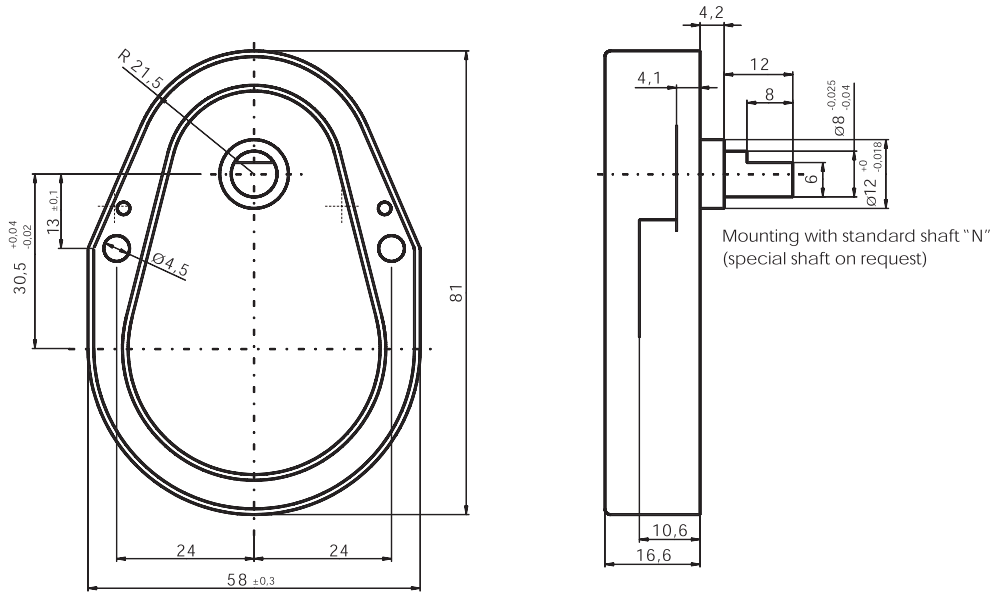
Mounting	any position
Axial thrust F _A	100 N
Lateral force F _R	300 N
Slipping clutches/free wheel	single-way clockwise/counter clockwise function and two way
Slipping-/free wheel torque	4 ... 175 cNm
Output shafts	∅ 8 x 12, other on request
Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15 ... +55
Ambient temperature storage	°C -40 ... +80

Ratios	41 ^{2/3}	83 ^{1/3}	100	125	150	166 ^{2/3}	200	250	300	500	600	750	900
	1000	1200	1500	1800	2000	2500	3000	3750	5000	6000	7500	12000	15000
	18000	30000	36000	60000	120000	266666 ^{2/3}	288000	320000	345600				

Order Reference

Type	Gearbox	UGB	100	N	5cNm	N
Ratio	100					
Slipping clutch	N Without slipping clutch ER One-way slipping clutch, clockwise EL One-way slipping clutch, counter clockwise Z Two-way slipping clutch					
Slipping torque	5 cNm					
Shaft end	N ∅ 8 x 12, other on request					

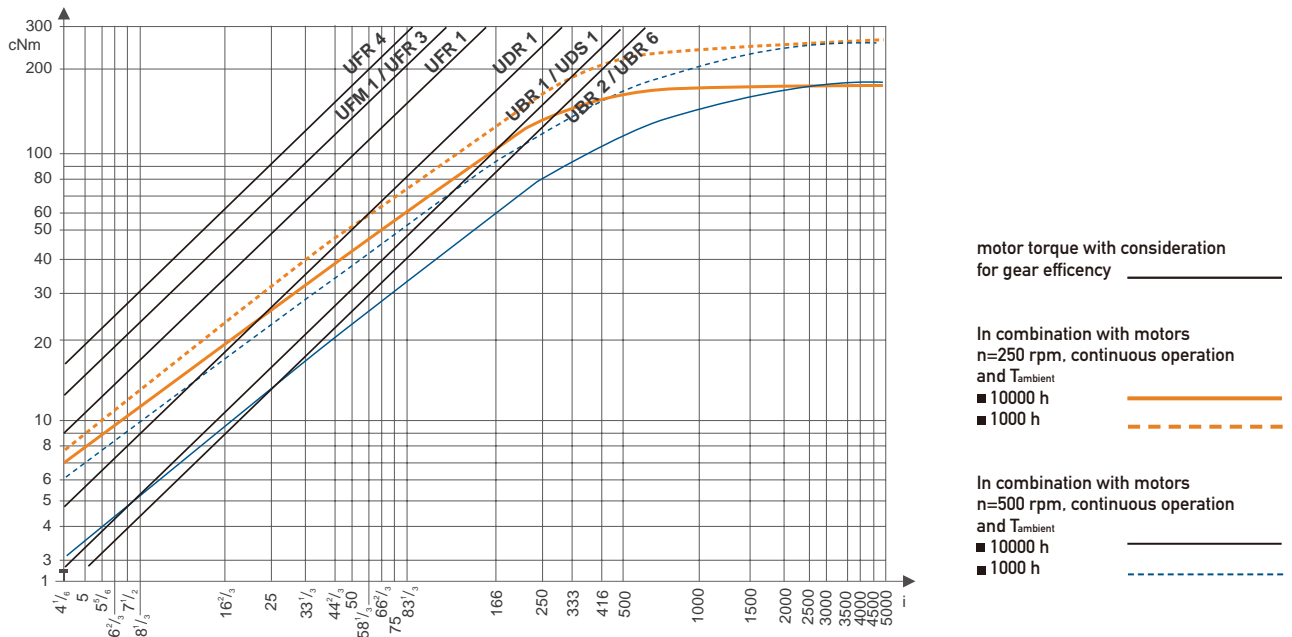
Dimensions



Slipping clutches

	max. torque available at output shaft (cNm)	free wheel-/clutch torque (cNm)
Roller-type free wheel		
Single-way slipping clutches	150	4 ... 50 counter clockwise or clockwise direction possible
Two-way slipping clutches	40 ... 70	60 ... 175

Torque / ratio / life graph



UGF

Dimensions (mm)	58 x 81
Hight (mm)	17
Max. torque (cNm)	500
Ratios	4 ¹ / ₆ ... 5000
Internal slipping clutch	none
Standard shaft (mm)	∅ 8 x 12
Weight (g)	130
Motor combination	Series UB, UD, UF



Standard Data

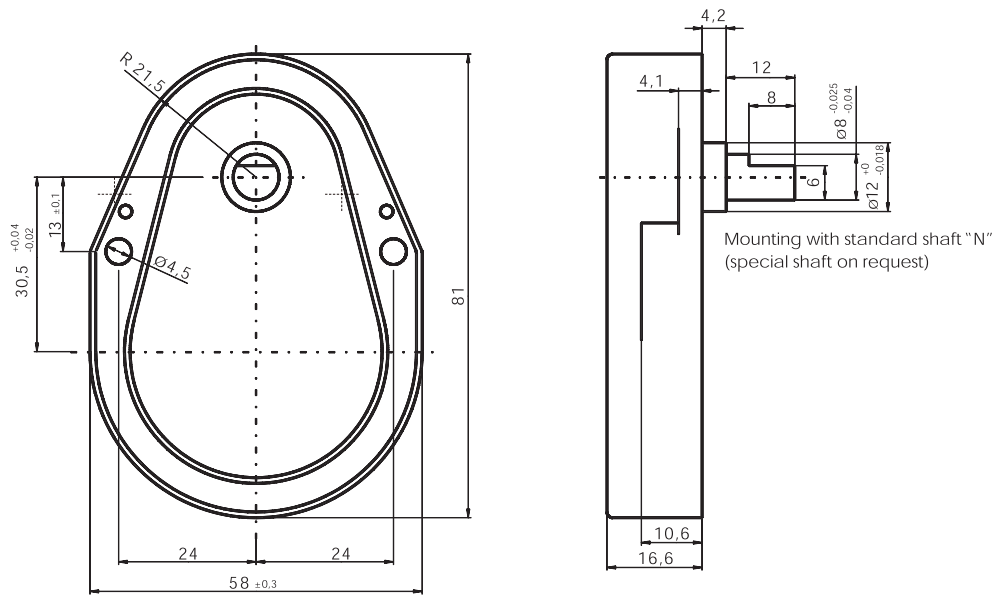
Mounting	any position
Axial thrust F _A	100 N
Lateral force F _R	400 N
Slipping clutches/free wheel	none
Slipping-/free wheel torque	cNm
Output shafts	∅ 8 x 12, other on request
Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15 ... +55
Ambient temperature storage	°C -40 ... +80

Ratios	4 ¹ / ₆	8 ¹ / ₃	16 ² / ₃	20 ⁵ / ₆	25	30	41 ² / ₃	50	62 ¹ / ₂	83 ¹ / ₃	100	125	166 ² / ₃
	250	333 ¹ / ₃	500	600	750	1000	1200	1500	4000	5000			

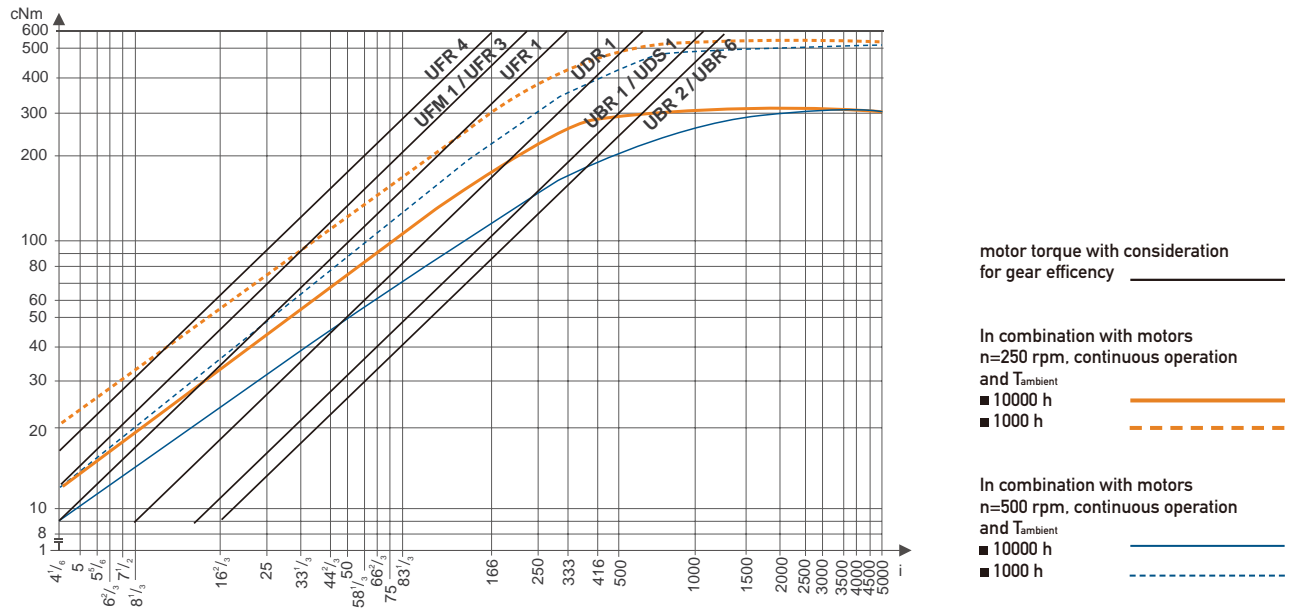
Order Reference

Type	Gearbox	UGF	100	N	N
Ratio	100				
Slipping clutch	N	Without slipping clutch			
Shaft end	N	∅ 8 x 12, other on request			

Dimensions



Torque / ratio / life graph



UGV

Dimensions (mm)	70 x 70
Height (mm)	17
Max. torque (cNm)	500
Ratios	8 ¹ / ₃ ... 2000
Internal slipping clutch	none
Standard shaft (mm)	∅ 8 x 12
Weight (g)	130
Motor combination	Series UB, UD, UF



Standard Data

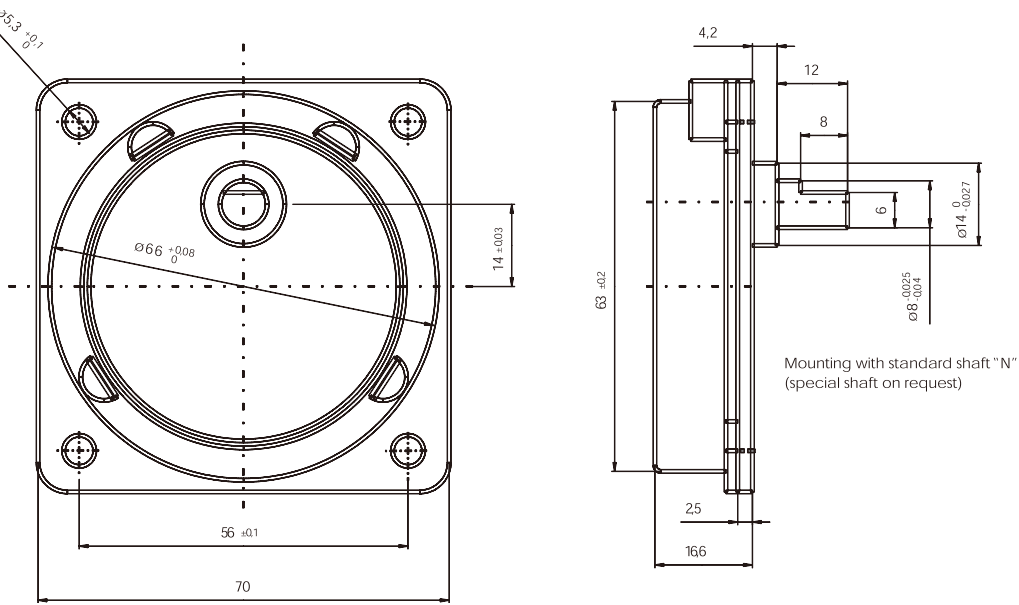
Mounting	any position
Axial thrust F _A	100 N
Lateral force F _R	400 N
Output shafts	∅ 8 x 12, other on request
Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15 ... +55
Ambient temperature storage	°C -40 ... +80

Ratios 8¹/₃ 16²/₃ 25 41²/₃ 83¹/₃ 100 125 250 500 2000

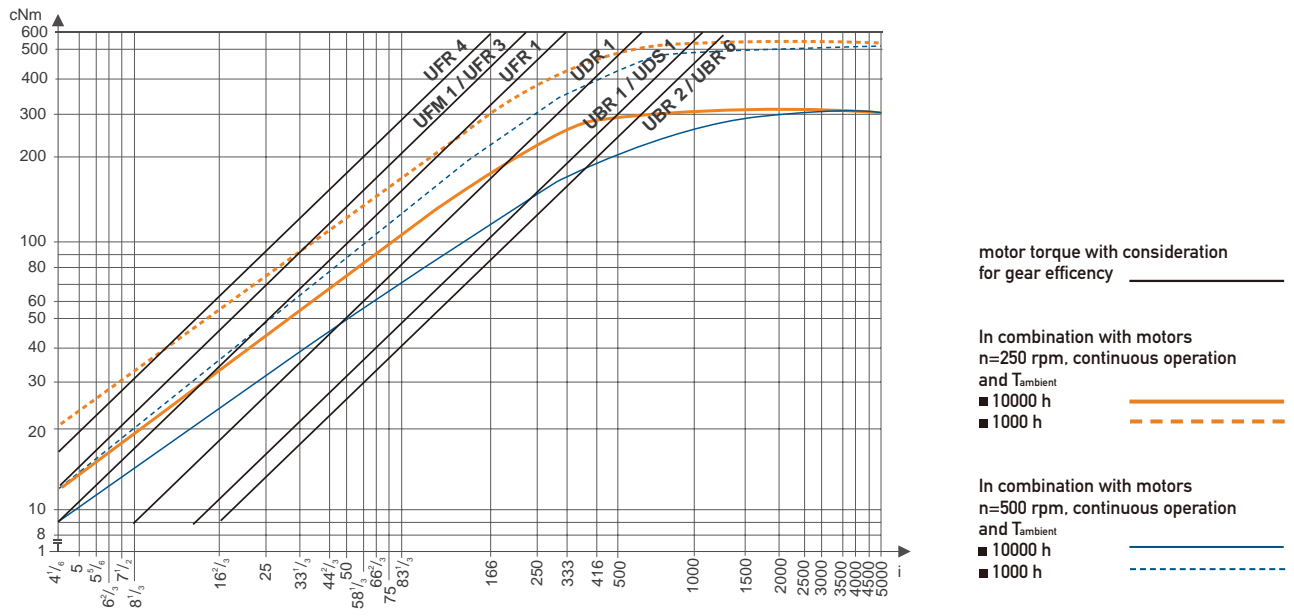
Order Reference

Type	Gearbox	UGV	100	N	N
Ratio	100				
Slipping clutch	N Without slipping clutch				
Shaft end	N ∅ 8 x 12, other on request				

Dimensions



Torque / ratio / life graph



UGO/UGP (STG60/61)

Dimensions (mm)	65 x 65/68 x 68
Hight (mm)	29,8–38
Max. torque (cNm)	600
Ratios	6 1/4 ... 5400
Internal slipping clutch	none
Standard shaft (mm)	∅ 8 x 22
Weight (g)	230–330
Motor combination	5021–, 5022–, 5032RG–, 6443–, 6444– series U0, UP and UF



UGO (STG 60)

UGP (STG 61)

Standard Data

Mounting	any position
Max. input speed*	3000 min ⁻¹
Max. output torque*	600 cNm
Max. input -and output power	please refer to table in Technical Data
Average back lash	unloaded 1,5 degree 2–4 stages with 6 Nm 3 degree 5–6 stages with 6 Nm 4 degree
Max. axial force F _A	30 N
Max. lateral force F _R , 12 mm from lange	80 N
Max. axial play	0.3 mm
Max. radial play	20 μm
Working temperature	0 ... +50 °C
Ambient temperature storage	–40 ... +100 °C

Ratio	6 1/4	12 1/2	18 3/4	37 1/2	46 7/8	62 1/2	93 3/4	125	150	187 1/2	375	750
	1500	2000	3750	5400								

* Depends on ratio, see next page

Order Reference

Type	Gearbox	STG60 UGO	6 1/4	1	1
Ratio	6 1/4				
shaft end	1	see next pages	drawings	Dimension	shaft end types
	2				
	3				
	4				
fixing	1	through holes			
	2	threaded holes (only STG61)			
optional	motor pinion: see next pages		Motor Pinion Data		
	adaptor plate: see next pages		for adaptor plate		

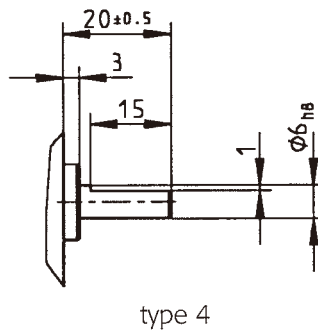
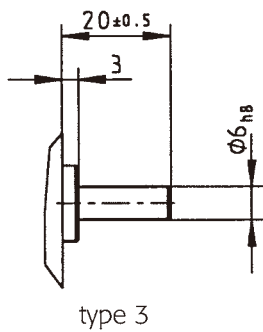
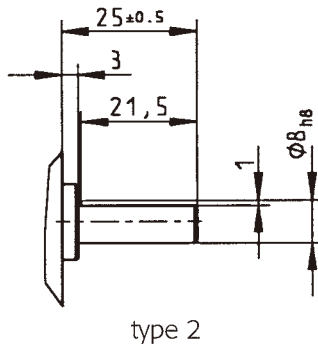
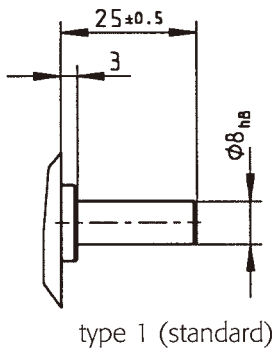
Technical Data

Ratio	Stages *	η	pinion type	Weight	Max. torque (Nm)	Max. input speed (rpm)
6 1/4	2	0,77	1	190	1,0	750
12 1/2	3	0,68	2	220	1,8	750
18 3/4	3	0,68	3	220	2,7	750
37 1/2	3	0,68	4	220	5,4	750
46 7/8	4	0,60	3	250	6	750
62 1/2	4	0,60	2	250	6	1000
93 3/4	4	0,60	3	250	6	1500
125	4	0,60	2	250	6	2000
150	4	0,60	3	250	6	2400
187 1/2	4	0,60	4	250	6	3000
375	5	0,53	3	280	6	3000
750	5	0,53	4	280	6	3000
1500	6	0,46	4	310	6	3000
2000	6	0,46	4	310	6	3000
3750	6	0,46	4	310	6	3000
5400	6	0,46	5	310	6	3000

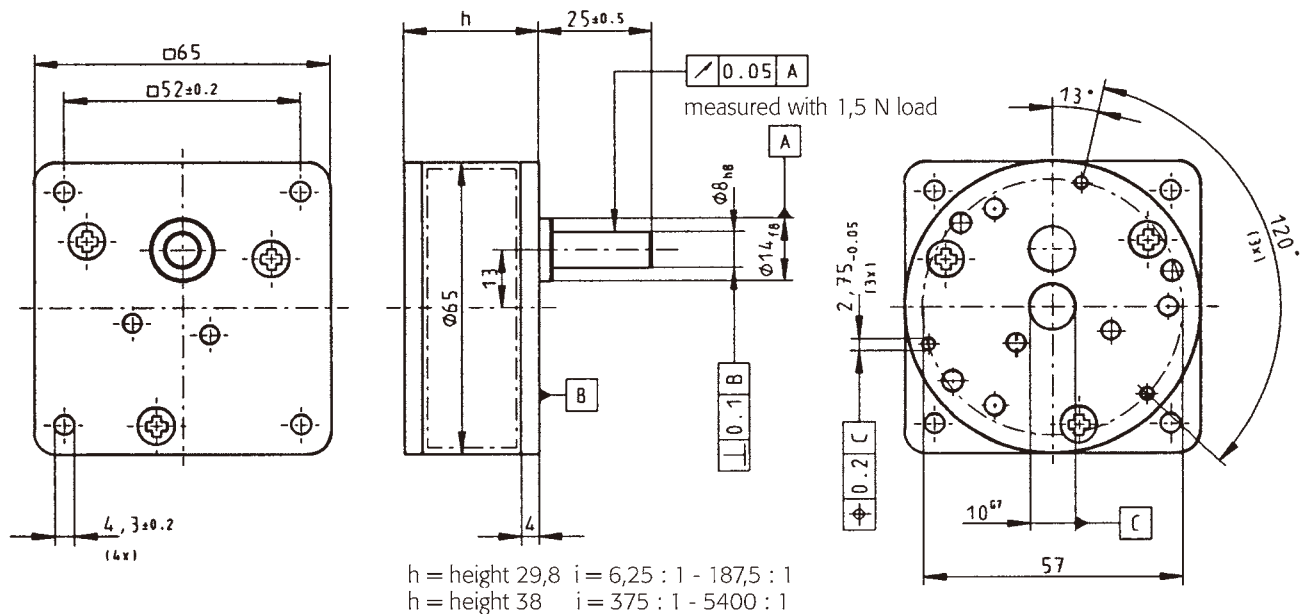
Technical Data valid for a working temperature 0 °C ... +50 °C

* Direction of rotation of output- and motor-shaft at
 2,4 and 6 stages - same
 3 and 5 stages - opposite

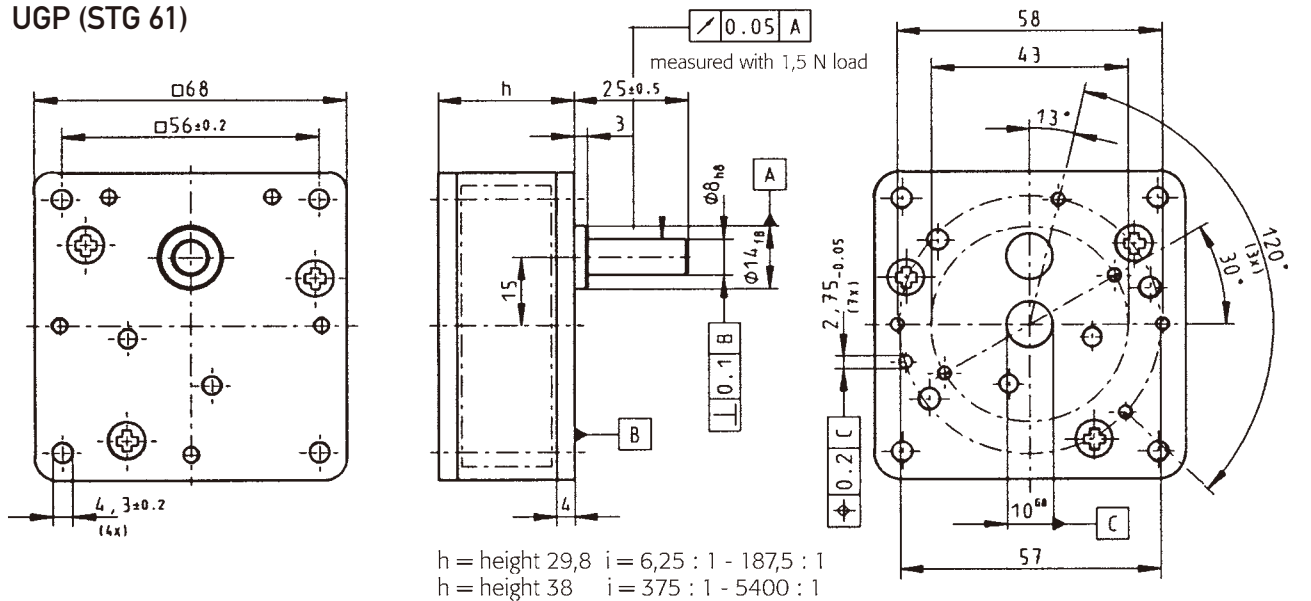
Dimensions shaft end types UGO/P (STG 60/61)



Dimensions UGO (STG 60)



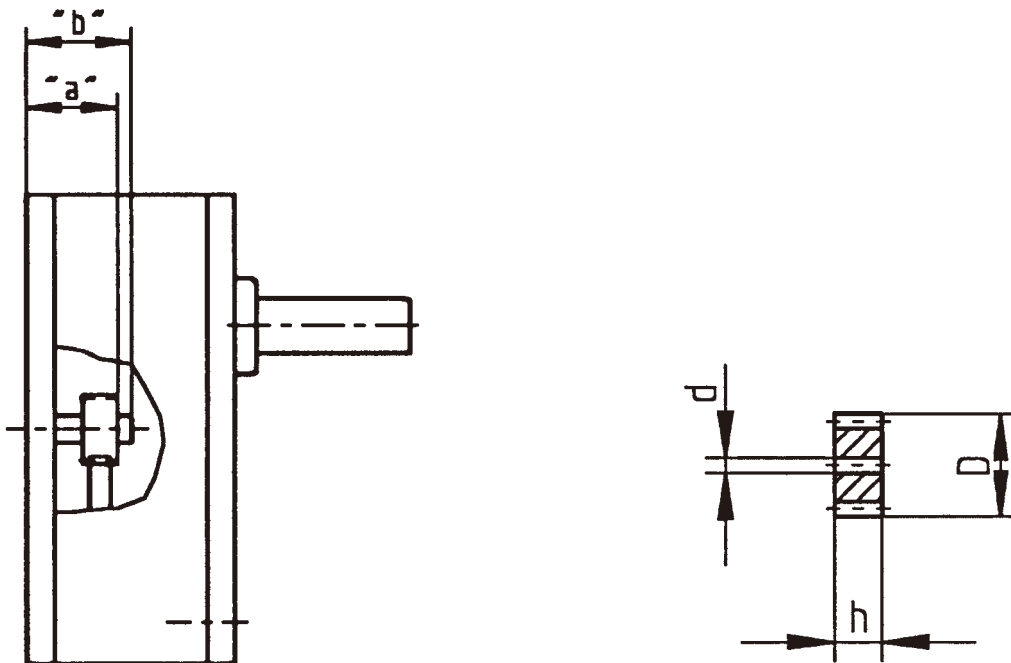
UGP (STG 61)



For fixing version 2 (threaded holes, see page before):
 4 holes $d=4,3$ are threaded holes M4
 (only for UGP possible)

Motor Pinion Data UGO/P (STG 60/61)

pinion type	d	h	D	module	no. of teeth	Order Reference
1	2.5 ^{S7}	6	9.81	0.38	24	022-100-004-010
	3.0 ^{S7}	6	9.81	0.38	24	022-100-004-020
	4.0 ^{X7}	6	9.81	0.38	24	022-100-004-030
	5.0 ^{S7}	6	9.81	0.38	24	022-100-004-040
2	2.5 ^{S7}	4.5	9.81	0.38	24	022-100-004-070
	3.0 ^{S7}	4.5	9.81	0.38	24	022-100-004-080
	4.0 ^{X7}	4.5	9.81	0.38	24	022-100-004-090
	5.0 ^{S7}	4.5	9.81	0.38	24	022-100-004-110
3	2.5 ^{S7}	4.5	9.32	0.5	16	022-100-004-270
	3.0 ^{S7}	4.5	9.32	0.5	16	022-100-004-280
	4.0 ^{X7}	4.5	9.32	0.5	16	022-100-004-290
	5.0 ^{S7}	4.5	9.32	0.5	16	022-100-004-310
4	2.5 ^{S7}	4.5	8.23	0.42	16	022-100-004-580
	3.0 ^{S7}	4.5	8.23	0.42	16	022-100-004-590
	4.0 ^{X7}	4.5	8.23	0.42	16	022-100-004-600
	5.0 ^{S7}	4.5	8.23	0.42	16	022-100-004-610
5	2.0 ^{S7}	4.5	6.34	0.42	12	022-100-004-730
	2.5 ^{S7}	4.5	6.34	0.42	12	022-100-005-150
	3.0 ^{S7}	4.5	6.34	0.42	12	022-100-004-740



pinion position	Dimension	„a“	„b“
2 gear stages		8.9 _{-0.2}	9.6 _{-0.7}
3-6 gear stages		7.6 _{-0.2}	7.6 _{-0.2}

AP 60

AP 60

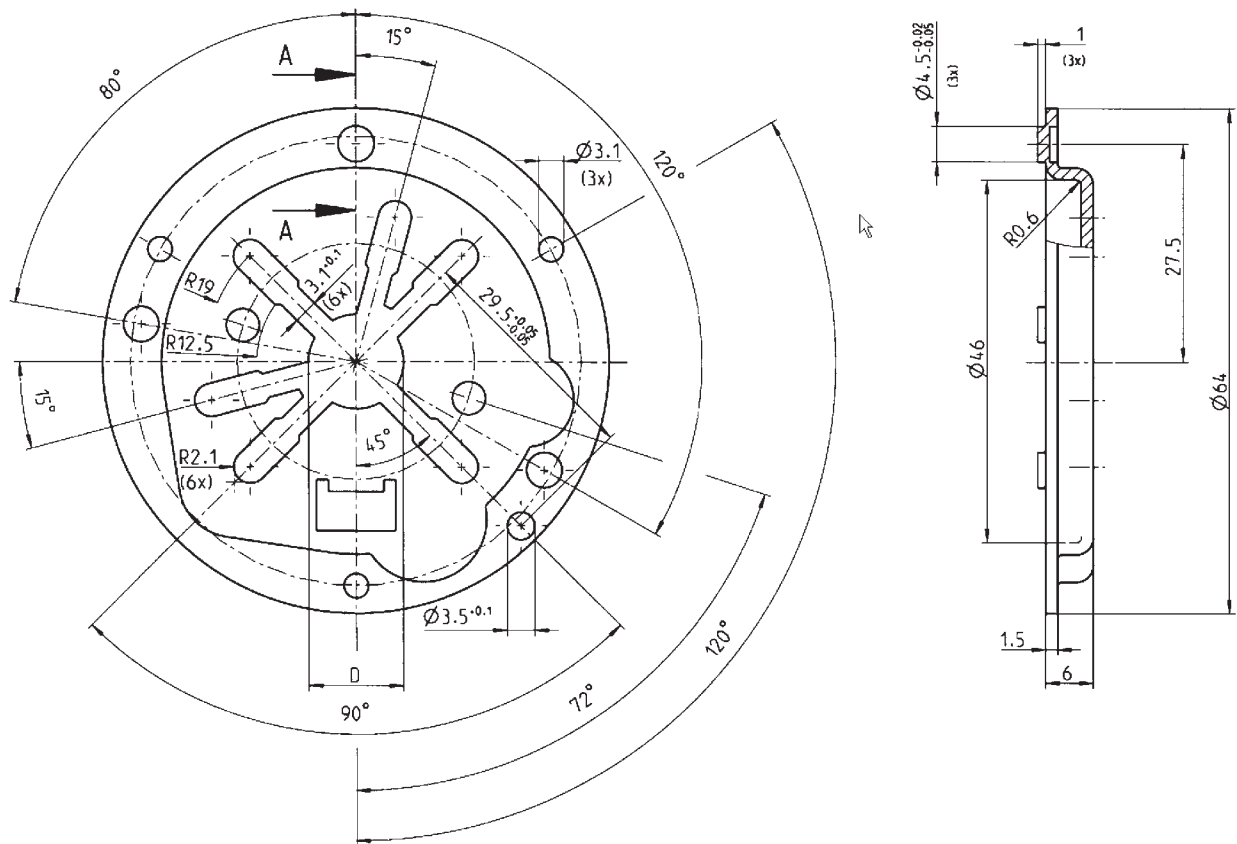
Dimensions (mm) $\varnothing 64$

Height (mm) 6

Adaptor Plate Data AP 60

Adaptor plate	Motor type	Manufacturer	Centring $\varnothing D$	Order Reference
AP 6012	G 30	Dunker	12	81B-001-002-010
AP 6022	G 42, GR 42		22	81B-001-002-016
AP 6014	M 28, M 32	GEFEG	14	81B-001-002-012
AP 6022	M 42, M 48		22	81B-001-002-016

Dimensions



UGJ

Dimensions (mm)	65 x 107
Hight (mm)	28
Max. torque (cNm)	1500
Ratios	4 ^{1/6} ... 36.000.000
Internal slipping clutch	none
Standard shaft (mm)	Ø 12 x 20
Weight (g)	480
Motor combination	Series UB, UD, UF, UH



Standard Data

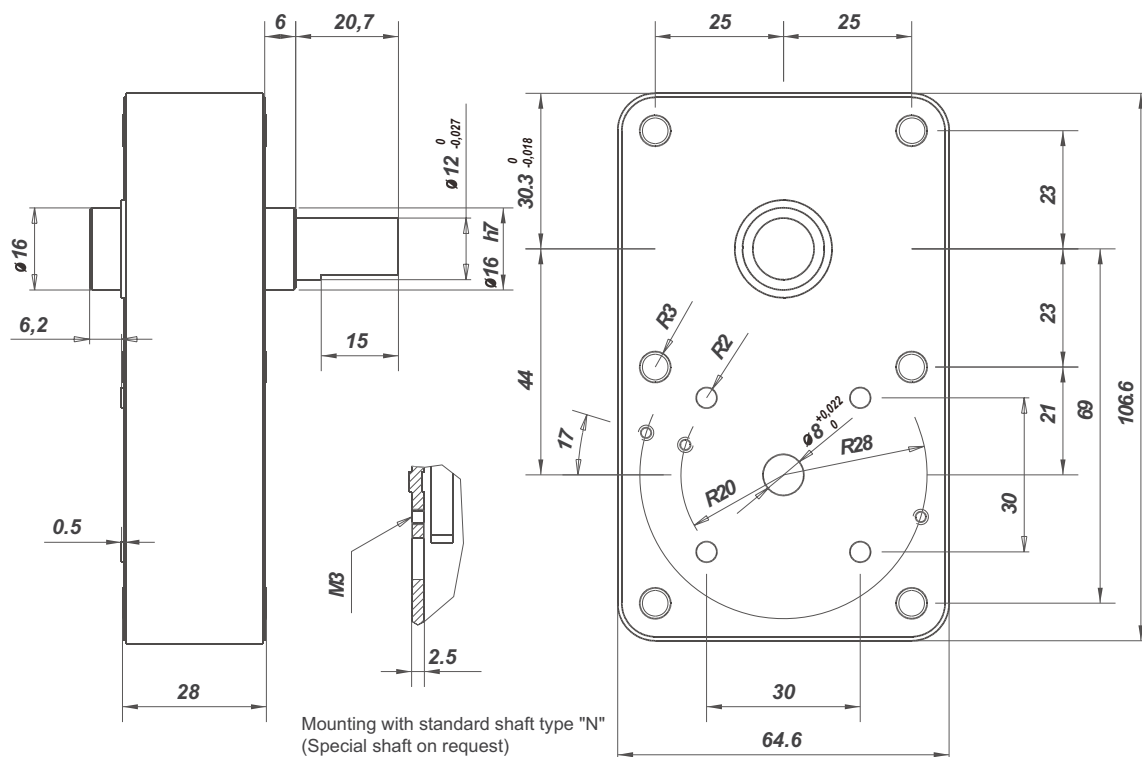
Mounting	any position
Axial thrust F _A	400 N
Lateral force F _R	600 N
Output shafts	Ø 12 x 20, other on request
Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15 ... +55
Ambient temperature storage	°C -40 ... +80

Ratios	4 ^{1/6}	8 ^{1/6}	16 ^{2/6}	33 ^{1/6}	41 ^{2/6}	50	66 ^{2/6}	83 ^{1/6}	100	125	150	166 ^{2/6}	200
	250	500	1000	2000	2500	3000	4000	5000	6250	8333 ^{1/6}	10000	12500	15000
	20000	25000	30000	37500	60000	75000	120000	150000	300000	375000	750000	1500000	1800000
	2250000	3000000	3600000	4500000	6000000	9000000	11250000	12000000	18000000	36000000			

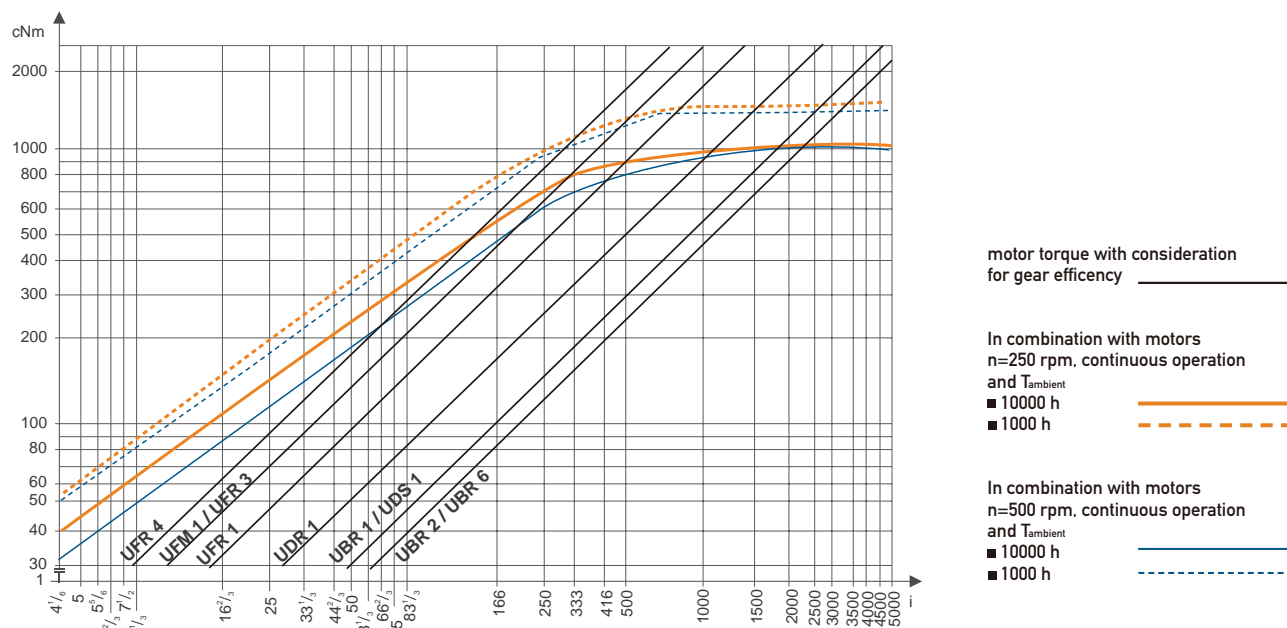
Order Reference

Type	Gearbox	UGJ	100	N	N
Ratio	100				
Slipping clutch	N	Without slipping clutch			
Shaft end	N	Ø 12 x 20, other on request			

Dimensions



Torque / ratio / life graph



UGR (STG 200)

Dimensions (mm)	70 x 130
Hight (mm)	38
Max. torque (cNm)	2000
Ratios	6 1/4 ... 375
Internal slipping clutch	none
Standard shaft (mm)	∅ 12 x 35
Weight (g)	depends on ratio
Motor combination	5021-, 5022-, 5032 RG-, 6443-, 6444- series UO and UP



Standard Data

Mounting	any position
Max. input speed *	3000 min ⁻¹
Max. output torque *	2000 cNm
Max. input -and output power *	please refer to table in Technical Data
Average back lash unload	0,75°
2/3 stages with 4/10 Nm	1,25°
4/5 stages with 15/20 Nm	2°
Max. axial force F _A	60 N
Max. lateral force F _R , 20 mm from lange	80 N
Max. axial play	0.3 mm
Max. radial play	83 µm
Working temperature	10 ... +50 °C
Ambient temperature storage	-40 ... +100 °C

Ratio	6 1/4	12 1/2	25	37 1/2	62 1/2	75	93 3/4	125	375
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* Depends on ratio, see next page

Order Reference

Type	Gearbox	STG 200 UGR	6 1/4
Ratio	6 1/4		
optional	motor pinion: see next pages Motor Pinion Data		

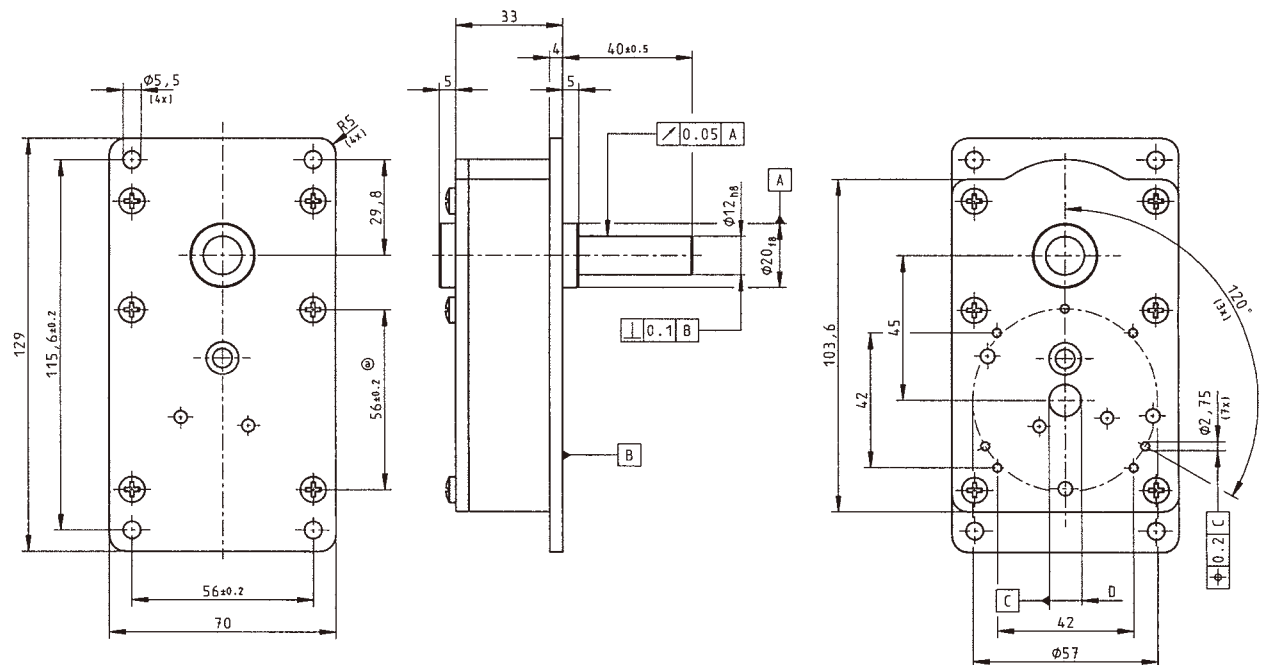
Technical Data

Ratio	Stages *	η	pinion type	Weight	Max. torque (Nm)	Max. input speed (rpm)
6 ¹ / ₄	2	0.77	1	560	1.8	750
12 ¹ / ₂	2	0.77	2	560	3.6	750
25	3	0.68	3	580	6.6	750
37 ¹ / ₂	3	0.68	4	580	9.9	750
62 ¹ / ₂	4	0.60	5	600	14,6	750
75	4	0.60	6	600	17,5	750
93 ³ / ₄	4	0.60	6	600	20	820
125	4	0.60	6	600	20	1100
375	5	0.53	4	620	20	3000

Technical Data valid for a working temperature 0 °C ... +50 °C

* Direction of rotation of output- and motor-shaft at
 2 and 4 stages - same
 3 and 5 stages - opposite

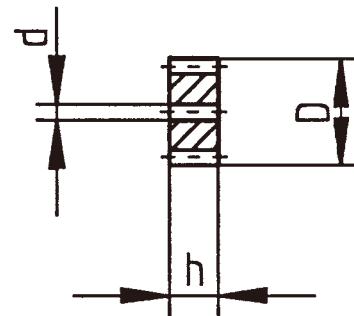
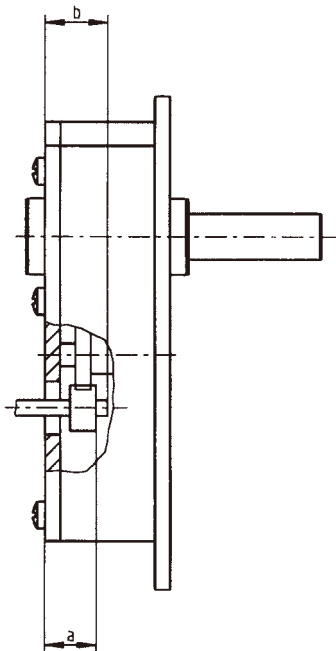
Dimensions



Diameter D = 14⁶⁸ for ratio $i \leq 25$
 10⁶⁸ for ratio $i > 25$

Motor Pinion Data

pinion type	d	h	D	module	no. of teeth	Order Reference
1	4,0 ^{X7}	11,5	12,65	0,56	20	022-100-020-100
	5,0 ^{S7}	11,5	12,65	0,56	20	022-100-020-110
2	4,0 ^{X7}	11,5	9,11	0,53	14	022-100-020-130
	5,0 ^{S7}	11,5	9,11	0,53	14	022-100-020-140
3	3,0 ^{S7}	6,8	12,02	0,57	18	022-100-020-200
	4,0 ^{X7}	6,8	12,02	0,57	18	022-100-020-210
	5,0 ^{S7}	6,8	12,02	0,57	18	022-100-020-220
4	3,0 ^{S7}	6,8	9,32	0,5	16	022-100-020-280
	4,0 ^{X7}	6,8	9,32	0,5	16	022-100-020-290
	5,0 ^{S7}	6,8	9,32	0,5	16	022-100-020-300
5	3,0 ^{S7}	11,5	9,82	0,38	24	022-100-020-360
	4,0 ^{X7}	11,5	9,82	0,38	24	022-100-020-370
	5,0 ^{S7}	11,5	9,82	0,38	24	022-100-020-380
6	3,0 ^{S7}	11,5	9,32	0,5	16	022-100-020-400
	4,0 ^{X7}	11,5	9,32	0,5	16	022-100-020-410
	5,0 ^{S7}	6,8	9,32	0,5	16	022-100-020-300

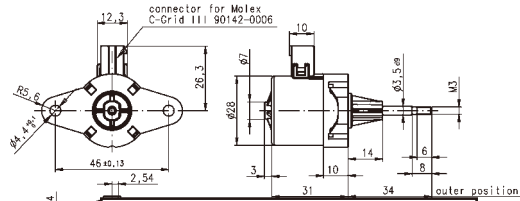


pinion position	Dimension	„a“	„b“ max.	„b“ min.
2 gear stages		16,1 _{-0,2}	28	10
3 gear stages		10,3 _{-0,2}	10,3	8,1
4 gear stages		15,1 _{-0,2}	15	8,1 (13,5 bei Ø 5)
5 gear stages		10,9 _{-0,2}	11	8,1

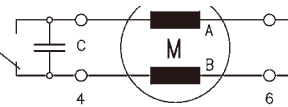
Synchronous Motors



Dimensions



Circuit diagram



UCC1/7

Dimensions (mm)	∅ 28 x 31
Travel (mm)	10/13
Voltage (V) **	12–230
Thread pitch (mm)	1,0
Speed (mm/s)	
50 Hz	4,16
60 Hz	5
Pole number	24
Max. Force (N)*	35



* Depends on winding, frequency and lifetime required. Values for connector versions (C, D) / lead wire versions (N) up to 20 % lower.
Drive against end stops only permissible after clarification of operating conditions and approval by Saia motors.

** regard circuit diagram and connector type

Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15 ... +60
Ambient temperature storage	°C -20 ... +100
Thermal resistance at f=0 R _{therm}	29 K/W
Thermal class	B according to DIN EN 60085
Winding coil temperature increase	K 60
Approval	standard
Mounting	any position
Electrical connection	connector type C, D, N
Protection	IP 40 according to DIN EN 60529
Weight	67 g
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	ball bearing

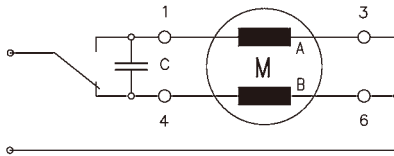
Order Reference

Type	Synchronous Motor		UCC	13	N	24 V / 50 Hz	B	1A
Configuration	13	standard magnet	73	stronger magnet				
Approval	N							
Voltage/frequency	see next pages							
Connection	C see next pages „Connection Types“ D							
Shaft	1A	Travel 10 mm ± 0,7 mm						
	1B	Travel 13 mm ± 0,7 mm						

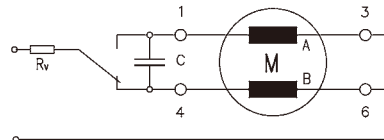
Technical Data

bipolar	Rated frequency	Hz	50		
	Axial speed	mm/s	4,16		
	Tolerance of voltage		standard power supply system +10% / -10%		
	Linear travel max.	mm	10/13		
	Axial play at ± 20 N force	mm	< 0,25		
	Duty cycle		100 %		
	Winding temperature T_{max}		130		
Capacitors	Rated voltage U_N	V	12	24	110
	Operating capacitor C_{50}	$\mu F/V\sim$	18/20	4,7/40	0,33/200

Circuit diagram Parallel circuit 12 V, 24 V, 48 V

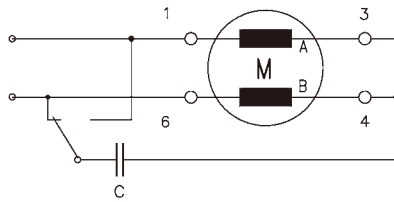


Parallel circuit 230 V (only for connector N) with 110 V motor and resistor R_V

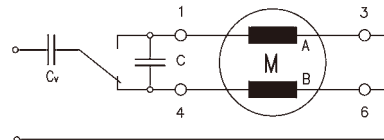


$R_V = 5,6 \text{ k}\Omega, 3 \text{ W}$

Series circuit 110 V (only for connector N)



Parallel circuit 230 V (only for connector N) with 110 V motor and capacitor C_V

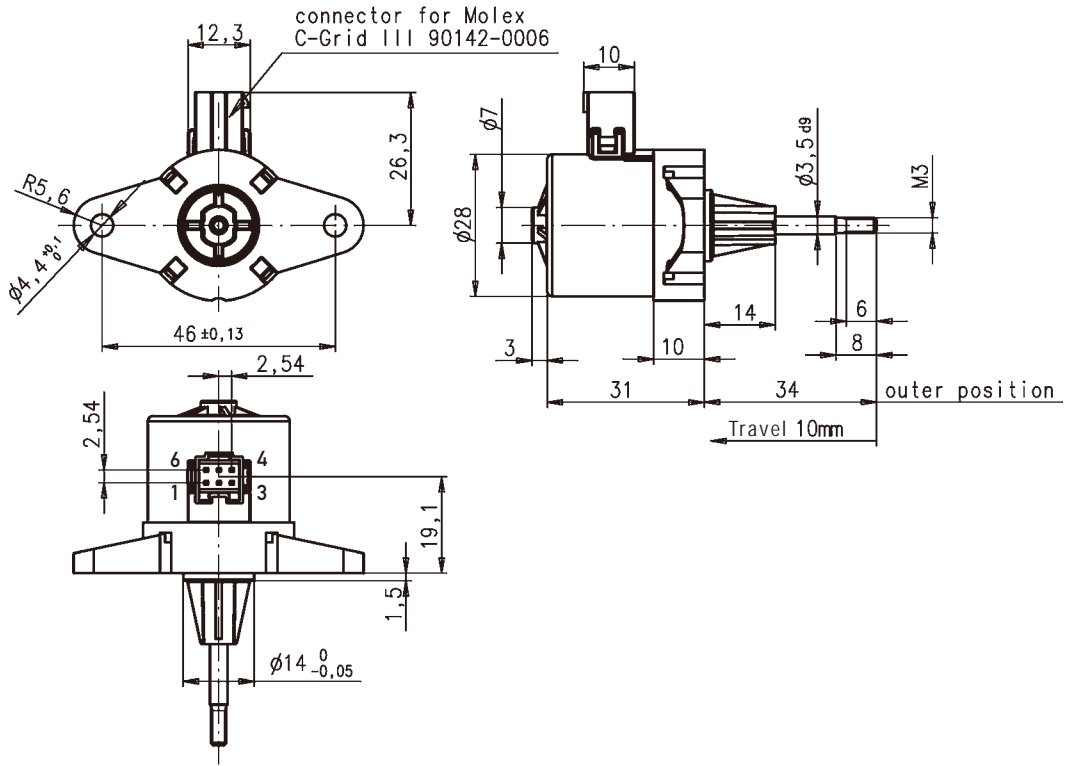


$C_V = 0,33 \mu F, 250 \text{ VAC}$

switch to

- 1 Pull (in)
- 4 Push (out)
- 6 Push (out)
(for series circuit)

Dimensions Version with Connector D, with 10 mm travel



UCK 1/7

Dimensions (mm) \varnothing 28 x 31

Travel (mm) 10/13

Voltage (V) ** 12–230

Thread pitch (mm) 1,0

Speed (mm/s)
 50 Hz 8,33
 60 Hz 10

Pole number 12

Max. Force (N)* 35



* Depends on winding, frequency and lifetime required. Values for connector versions (C, D) / lead wire versions (N) up to 20 % lower.
 Drive against end stops only permissible after clarification of operating conditions and approval by Saia motors.

** regard circuit diagram and connector type

Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15 ... +60
Ambient temperature storage	°C -20 ... +100
Thermal resistance at f=0 R _{therm}	29 K/W
Thermal class	B according to DIN EN 60085
Winding coil temperature increase	K 60
Approval	standard
Mounting	any position
Electrical connection	connector type C, D, N
Protection	IP 40 according to DIN EN 60529
Weight	67 g
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	ball bearing

Order Reference

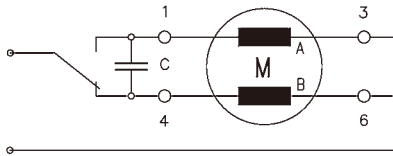
Type	Synchronous Motor	UCK	13	N	24 V / 50 Hz	D	1A
Configuration	13	standard magnet	73	stronger magnet			
Approval	N						
Voltage/frequency	see next page						
Connection	C see next pages „Connection Types“ D N						
Shaft	1A	Travel 10 mm ± 0,7 mm					
	1B	Travel 13 mm ± 0,7 mm					

Technical Data

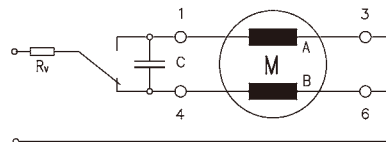
Rated frequency	Hz	50
Speed	mm/s	8.33
Tolerance of voltage		standard power supply system +10% / -10%
Linear travel max.	mm	10/13
Axial play at 20 N force	mm	< 0.25
Duty cycle		100 %
Winding temperature T_{max}		130

Capacitors	Rated voltage U_N	V	12	24	110
	Operating capacitor C_{50}	$\mu F/V\sim$	22/20	5.6/40	0.27/200

Circuit diagram Parallel circuit 12 V, 24 V, 48 V

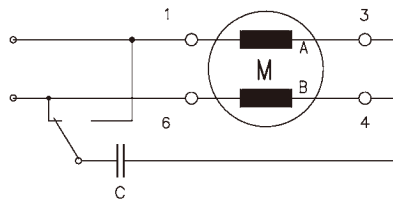


Parallel circuit 230 V (only for connector N) with 110 V motor and resistor R_V

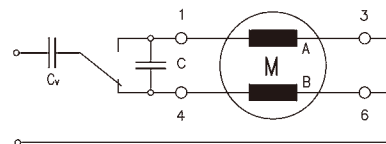


$R_V = 5,6 \text{ k}\Omega, 3 \text{ W}$

Series circuit 110 V (only for connector N)



Parallel circuit 230 V (only for connector N) with 110 V motor and capacitor C_V

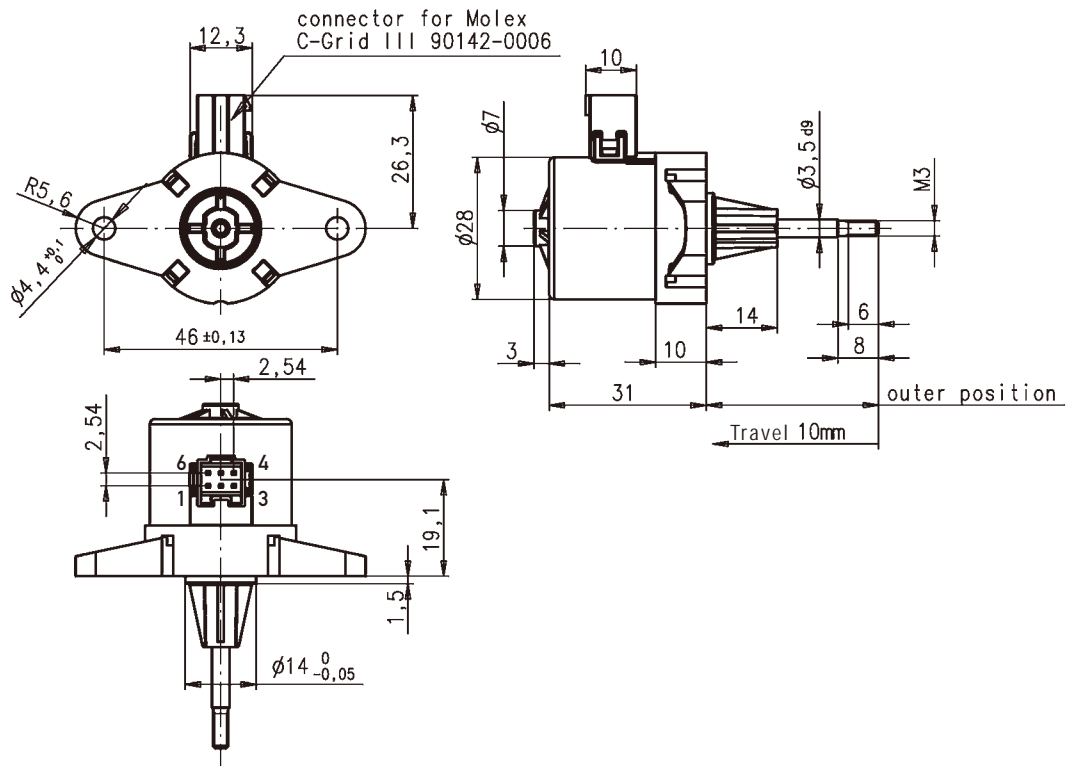


$C_V = 0,33 \mu F, 250 \text{ VAC}$

switch to

- 1 Pull (in)
- 4 Push (out)
- 6 Push (out)
(for series circuit)

Dimensions Version with Connector D, with 10 mm travel



UBK1

Dimensions (mm)	∅ 36 x 36
Travel (mm)	8/13/56 ± 0,7
Voltage (V)	12-230
Thread pitch (mm)	1,0
Speed (mm/s)	
50 Hz	6,67/8,33
60 Hz	8/10
Pole number	12
Max. Force (N)*	35
Lifetime	on request



*Depends on winding, frequency and lifetime required.
Drive against end stops only permissible after clarification of operating conditions and approval by Saia-Burgess.

Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15...+60
Ambient temperature storage	°C -20...+100
Thermal resistance at f=0 R _{therm}	27 K/W
Thermal class	A according to DIN EN 60085
Approval	Standard
Mounting	any position
Electrical connection	jack connector
Protection	IP 40 according to DIN EN 60529
Weight	90 g
Rotor stalling	motor can be stopped when voltage is applied without being overheated, with controlled duty cycle
Bearings	ball bearing, for live time lubricated
Electric strength	according to DIN EN 60034-1/DIN EN 60335-1

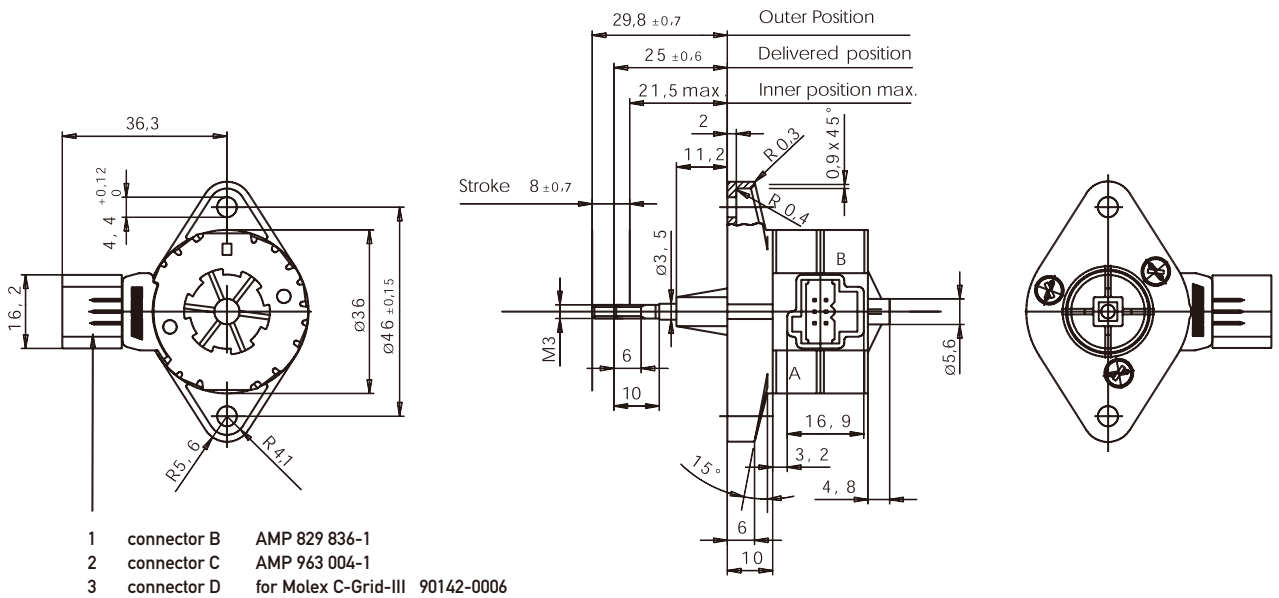
Order Reference

Type	Synchronous Motor	UBK1	N	12V/50Hz	B	3C
Approval	N Approval Standard					
Voltage/Frequency	See next page					
Connector	6 pole connector (other on request)					
Shaft	3C Travel 8 mm ± 0,7 mm (other on request)					

Technical Data

Rated frequency	Hz	50	60	
	Axial speed	mm/sec	8,33	10
	Tolerance of voltage	standard power supply system + 10% / - 10%		
	Linear travel max.	mm	8; 13; 56 ± 0.7	
	Axial play at ± 20 N force	mm	< 0,25	
	Duty cycle	100%		
Capacitors	Winding temperature T _{max}	°C	105°C	
	Rated voltage U _N	V	24	48
	Operation capacitor C ₅₀	μF/VAC	3,9/40	1,0/70
	Operation capacitor C ₆₀	μF/VAC	3,9/40	1,0/70

Dimensions



U0 Linear actuator (LA5021SM)

Dimensions (mm) \varnothing 50 x 76

Travel (mm) 45–50

Voltage (V) 12–230

Thread pitch (mm) 1,5/1,5/1,5

Speed (mm/s)

50 Hz 6,25/9,37/12,5

60 Hz 7,5/11,25/15

Pole number 24/16/12

Max. Force (N)* 45–50



* Depends on winding, frequency and lifetime required.

Drive against end stops only permissible after clarification of operating conditions and approval by Saia-Burgess.

Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15 ... +40
Ambient temperature storage	°C -20 ... +100
Thermal class	A according to DIN EN 60085
Winding coil temperature increase	K 85
Approval	standard
Mounting	any position
Electrical connection	cable
Protection	IP 40 according to DIN EN 60529
Weight	~ 220 g
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	ball bearing

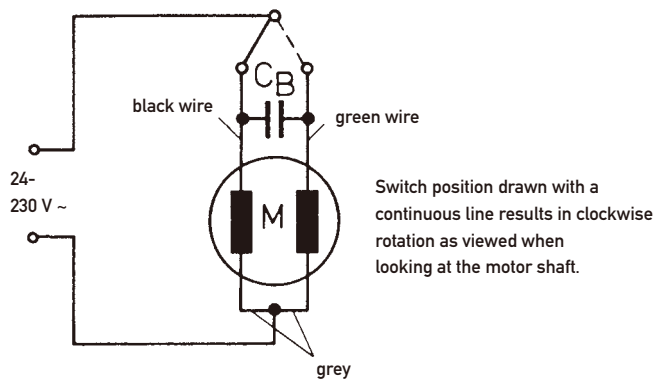
Order Reference

Type	Synchronous Motor	LA 5021 SM	24 V	6,25 mm/s	45 mm
Nominal Voltage	24 V 50/60 Hz 110 V 50/60 Hz 230 V 50/60 Hz				
Operating speed	6,25 mm/s at 50 Hz 9,375 mm/s 12,5 mm/s				
Travel	50 mm				

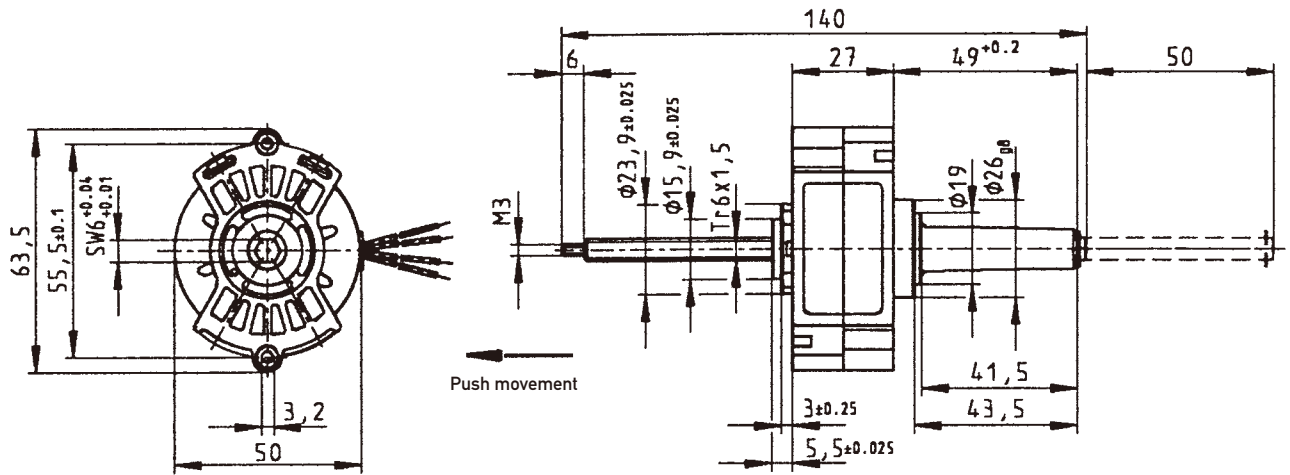
Technical Data

Speed 50 Hz	mm/s	6,25	9,375	12,5
60 Hz	mm/s	7,5	11,25	15
Push/Pull force	N	50	50	45
Linear travel	mm	50		
Axial play	mm	± 0,1		
Static axial force	N	max. 100		
self-locking by spindle/nut system		yes		
Drive		not stall-proof		
Anti-rotation guidance of spindle		built in		
Capacitors				
at U _N : 24 V	µF/V~	15/63		
at U _N : 110 V	µF/V~	0,75/250		
at U _N : 230 V	µF/V~	0,18/500		

Circuit diagram Parallel circuit

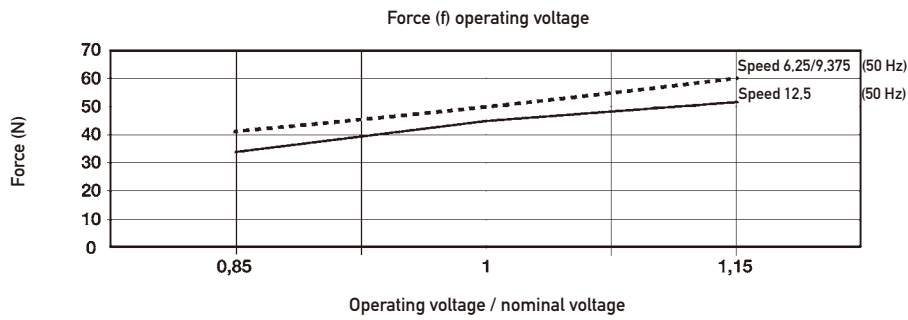


Dimensions



Standard - wire length: 100⁺²⁰ mm/6^{±1} stripped

Chart: Force versus voltage



U0 Spindle actuator (SP5021SM; SP5022SM)

Dimensions (mm)	∅ 50 x 27
Travel (mm)	68–130
Voltage (V)	12–230
Thread pitch (mm)	1,5/1,5/1,5
Speed (mm/s)	
50 Hz	6,25/9,375/12,5
60 Hz	7,5/11,25/15
Pole number	24/16/12
Max. Force (N)*	45–50 (SP5021SM); 50–70 (SP5022SM)



* Depends on winding, frequency and lifetime required.
Drive against end stops only permissible after clarification of operating conditions and approval by Saia-Burgess.

Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15 ... +40
Ambient temperature storage	°C -20 ... +100
Thermal class	A according to DIN EN 60085
Winding coil temperature increase	K 85
Approval	standard
Mounting	any position
Electrical connection	cable
Protection	IP 40 according to DIN EN 60529
Weight	~ 220 g
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	ball bearing

Order Reference

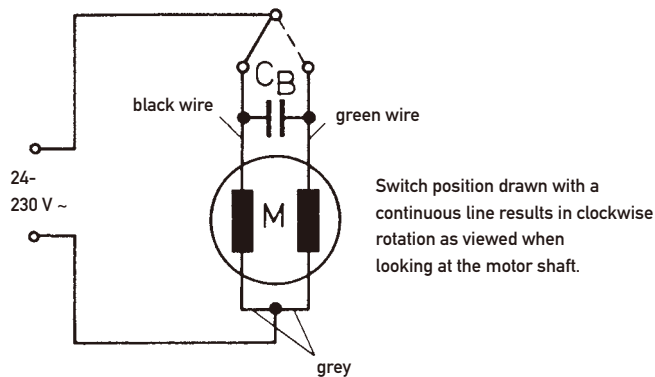
Type	Synchronous Motor	SP5021SM / SP5022SM	24 V	6,25 mm/s	68 mm
Nominal Voltage	24 V 50/60 Hz 110 V 50/60 Hz 230 V 50/60 Hz				
Speed at 50 Hz	6,25 mm/s 9,375 mm/s 12,5 mm/s				
Travel	68 mm 130 mm				

Technical Data

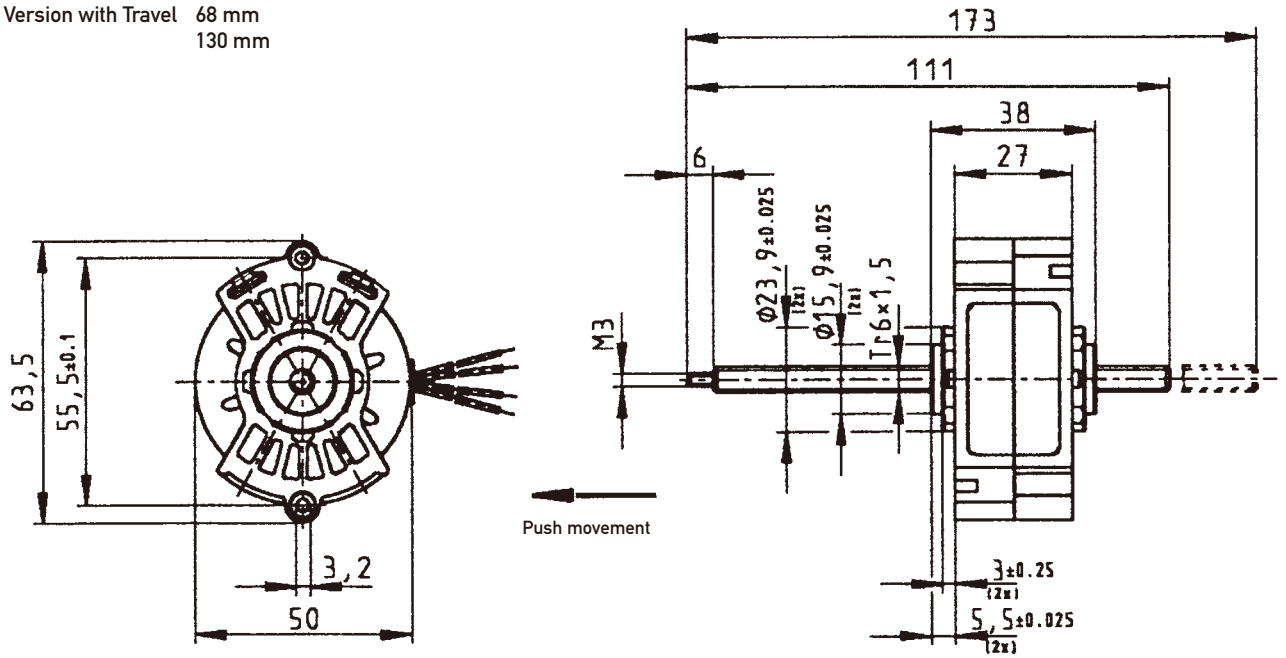
SP5021SM	Speed 50 Hz	mm/s	6,25	9,375	12,5
	60 Hz	mm/s	7,5	11,25	15
	Push/Pull force	N	50	50	45
	Linear travel	mm	~68/ ~130		
	Axial play	mm	± 0,1		
	Static axial force	N	max. 100		
	self-locking by spindle/nut system		yes		
	Drive		not stall-proof		
	Anti-rotation guidance of spindle		external required		
	Capacitors	at U_N : 24 V	$\mu\text{F}/V\sim$	15/63	
	at U_N : 110 V	$\mu\text{F}/V\sim$	0.75/250		
	at U_N : 230 V	$\mu\text{F}/V\sim$	0.18/500		

SP5022SM	Speed 50 Hz	mm/s	6,25	9,375	12,5
	60 Hz	mm/s	7,5	11,25	15
	Push/Pull force	N	70	70	50
	Linear travel	mm	~68/ ~130		
	Axial play	mm	± 0,1		
	Static axial force	N	max. 100		
	self-locking by spindle/nut system		yes		
	Drive		not stall-proof		
	Anti-rotation guidance of spindle		external required		
	Capacitors	at U_N : 24 V	$\mu\text{F}/V\sim$	15/63	
	at U_N : 110 V	$\mu\text{F}/V\sim$	0.75/250		
	at U_N : 230 V	$\mu\text{F}/V\sim$	0.18/500		

Circuit diagram Parallel circuit



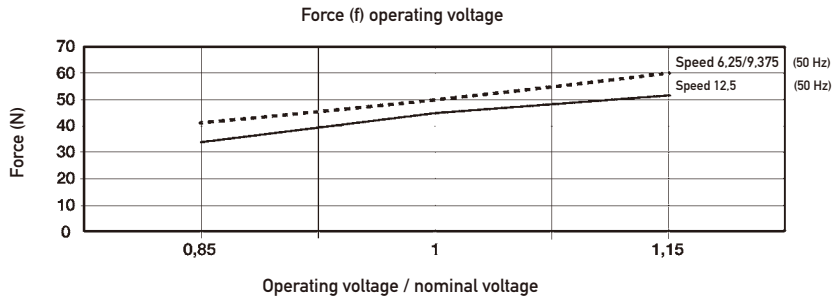
Dimensions Version with Travel 68 mm
130 mm



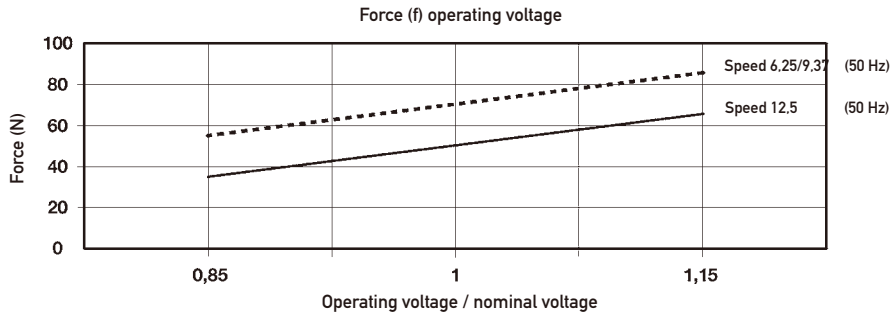
Standard - wire length: $100^{+20} \text{ mm} / 6^{\pm 1}$ stripped

Chart: Force versus voltage

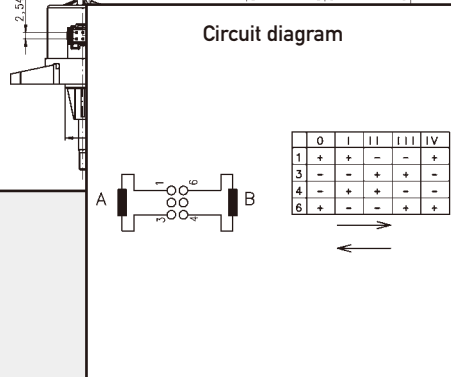
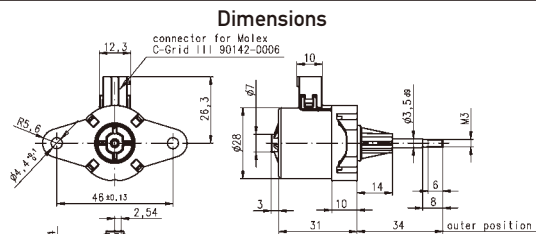
SP5021SM



SP5022SM



Stepper Motors



UCE1/7; UCE2/8

Dimensions (mm) \varnothing 28 x 31

Travel (mm) 10/13

Travel per step (mm) 0,021

Thread pitch (mm) 1,0

Speed (mm/s) at 200 Hz 4,16

Step angle (°) 7,5

Max. Force (N)* 35



*Depends on winding, frequency and lifetime required.

Drive against end stops only permissible after clarification of operating conditions and approval by Saia-Burgess.

Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15 ... +60
Ambient temperature storage	°C -20 ... +100
Thermal resistance at f=0 R _{therm}	29 K/W
Thermal class	B according to DIN EN 60085
Approval	standard
Mounting	any position
Electrical connection	connector type C, D
Protection	IP 40 according to DIN EN 60529
Weight	67 g
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	ball bearing

Order Reference

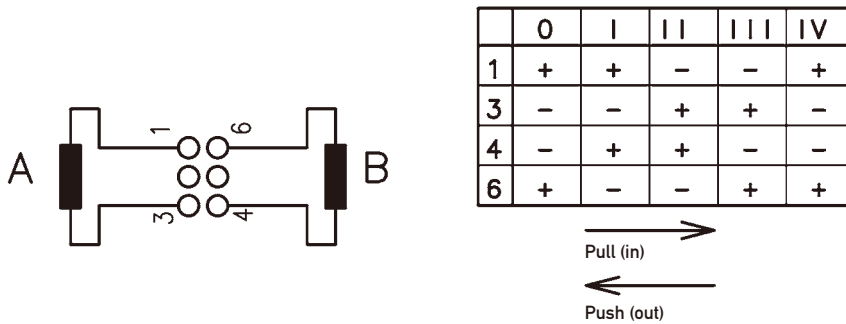
Type	Stepper Motor	UCE	13	N	24 Ω	B	1A
Configuration	13 bipolar, standard magnet	73 bipolar, stronger magnet	23 unipolar, standard magnet	83 unipolar, stronger magnet			
Approval	N						
Resistance	see next page, Resistance per winding for bipolar or unipolar						
Connection	C see next pages „Connection Types“ D						
Shaft	1A Travel 10 mm ± 0,7 mm		1B Travel 13 mm ± 0,7 mm				

Technical Data

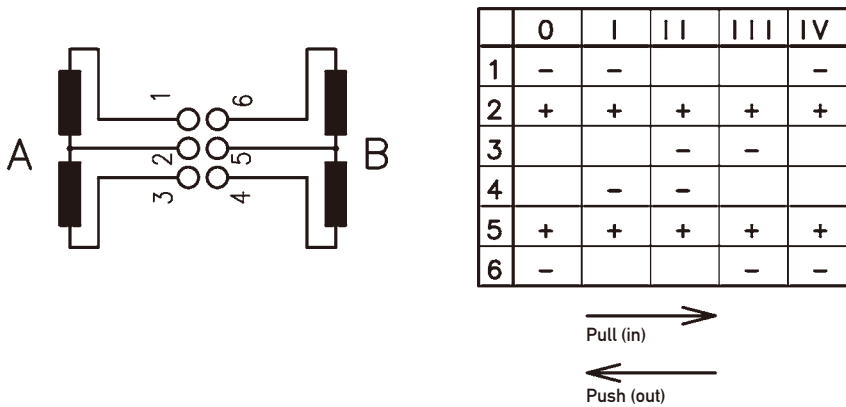
bipolar	type		UCE1	UCE1	UCE5	UCE5
	Operating frequency	Hz	100	200	100	200
	max. Push/Pull force *	30% duty cycle 100% duty cycle	N	49 42	42 28	50 49
unipolar	type		UCE2	UCE2	UCE6	UCE6
	Operating frequency	Hz	100	200	100	200
	max. Push/Pull force *	30% duty cycle 100% duty cycle	N	35 21	28 17	49 29
Rated voltage U_N :		V	6	12	24	
Resistance per winding R_{20}		Ω	24	90	380	
Steps per mm			48			
Duty cycle			100 %			
Winding temperature T_{max}		$^{\circ}C$	130			
Linear travel max.		mm	10/13			
Axial play at ± 20 N force		mm	< 0.25			

* measured at 23 $^{\circ}C$, lifetime depends on load characteristics and ambient conditions

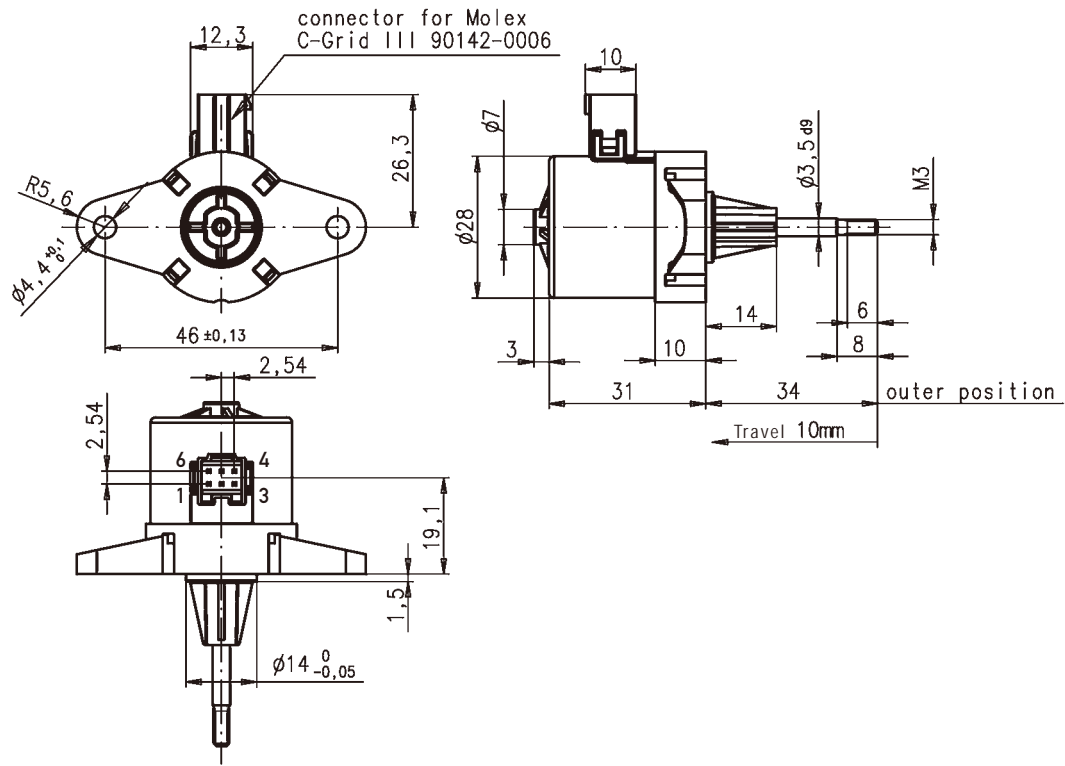
Circuit diagram bipolar



unipolar



Dimensions Version with connector D, 10 mm travel



UCL1/7; UCL2/8

Dimensions (mm) $\varnothing 28 \times 31$

Travel (mm) 10/13

Travel per step (mm) 0,041

Thread pitch (mm) 1,0

Speed (mm/s) at 200 Hz 8,33

Step angle (°) 15

Max. Force (N)* 35



*Depends on winding, frequency and lifetime required.
Drive against end stops only permissible after clarification of operating conditions and approval by Saia-Burgess.

Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15 ... +60
Ambient temperature storage	°C -20 ... +100
Thermal resistance at f=0 R _{therm}	29 K/W
Thermal class	B according to DIN EN 60085
Approval	standard
Mounting	any position
Electrical connection	connector type C, D
Protection	IP 40 according to DIN EN 60529
Weight	67 g
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	ball bearing

Order Reference

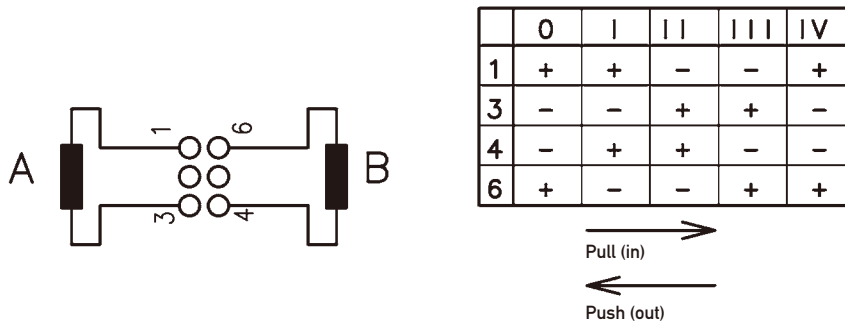
Type	Stepper Motor	UCL	13	N	24 Ω	B	1A
Configuration	13 bipolar, standard magnet	73 bipolar, stronger magnet					
	23 unipolar, standard magnet	83 unipolar, stronger magnet					
Approval	N						
Resistance	see next page, Resistance per winding for bipolar or unipolar						
Connection	C see next pages „Connection Types“ D						
Shaft	1A Travel 10 mm ± 0,7 mm						
	1B Travel 13 mm ± 0,7 mm						

Technical Data

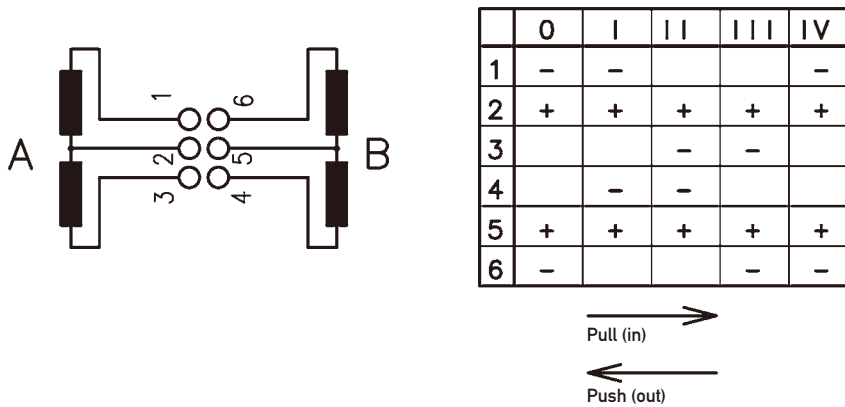
bipolar	type		UCL1	UCL1	UCL5	UCL5
	Operating frequency	Hz	100	200	100	200
	max. Push/Pull force *	30% ED 100% ED	N N	35 30	30 20	50 35
unipolar	type		UCL2	UCL2	UCL6	UCL6
	Operating frequency	Hz	100	200	100	200
	max. Push/Pull force *	30% ED 100% ED	N N	25 15	20 12	35 21
Rated voltage U_N :		V	6	12	24	
Resistance per winding R_{20}		Ω	24	90	380	
Steps per mm			24			
Duty cycle			100 %			
Winding temperature T_{max}		$^{\circ}C$	130			
Linear travel max.		mm	10/13			
Axial play at ± 20 N force		mm	< 0.25			

* measured at 23 °C. lifetime depends on load characteristics and ambient conditions

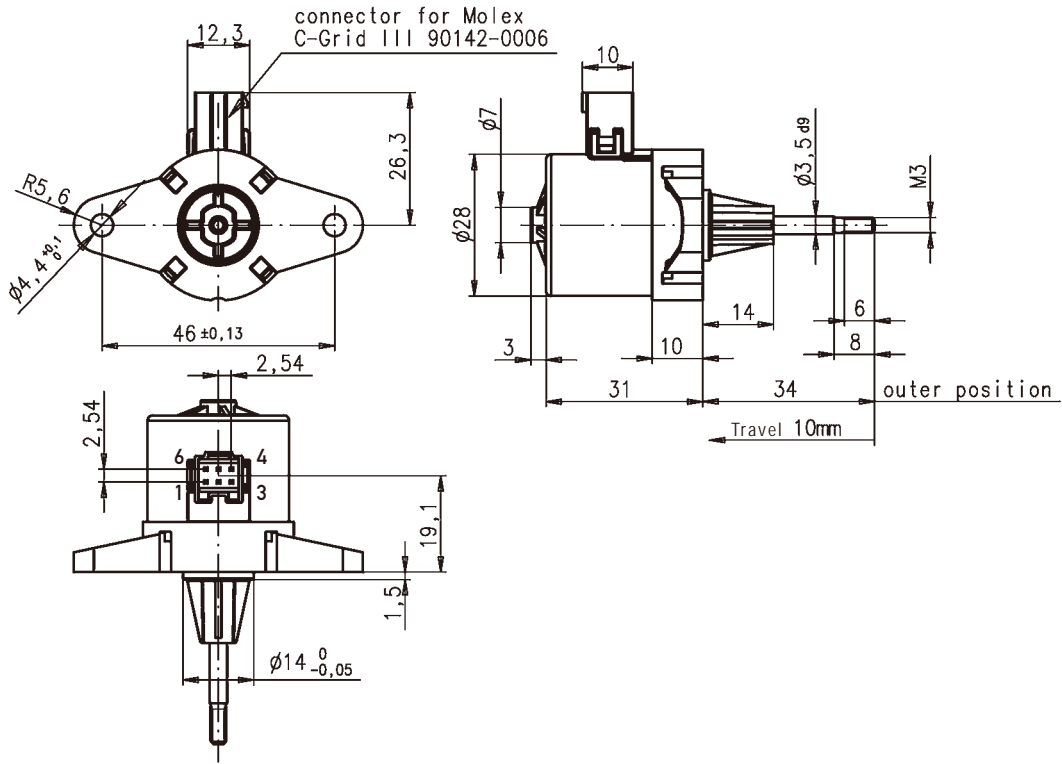
Circuit diagram bipolar



unipolar



Dimensions Version with connector D, 10 mm travel



UBL1/2

Dimensions (mm)	∅ 36 x 36
Travel (mm)	8; 13; 56 ± 0,7
Travel per step (mm)	0,041
Thread pitch (mm)	0,8
Speed (mm/s) at 200 Hz	8.33
Step angle (°)	15
Max. Force (N)*	35 (for special winding, lower lifetime)
Lifetime	on request



*Depends on winding, frequency and lifetime required.
Drive against end stops only permissible after clarification of operating conditions and approval by Saia-Burgess.

Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15...+60
Ambient temperature storage	°C -20...+100
Thermal resistance at f=0 R _{therm}	27 K/W
Thermal class	A according to DIN EN 60085
Approval	standard
Mounting	any position
Electrical connection	jack connector
Protection	IP 40 according to DIN EN 60529
Weight	90 g
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	ball bearing, for live lubricated
Electric strength	according to DIN EN 60034-1/DIN EN 60335-1

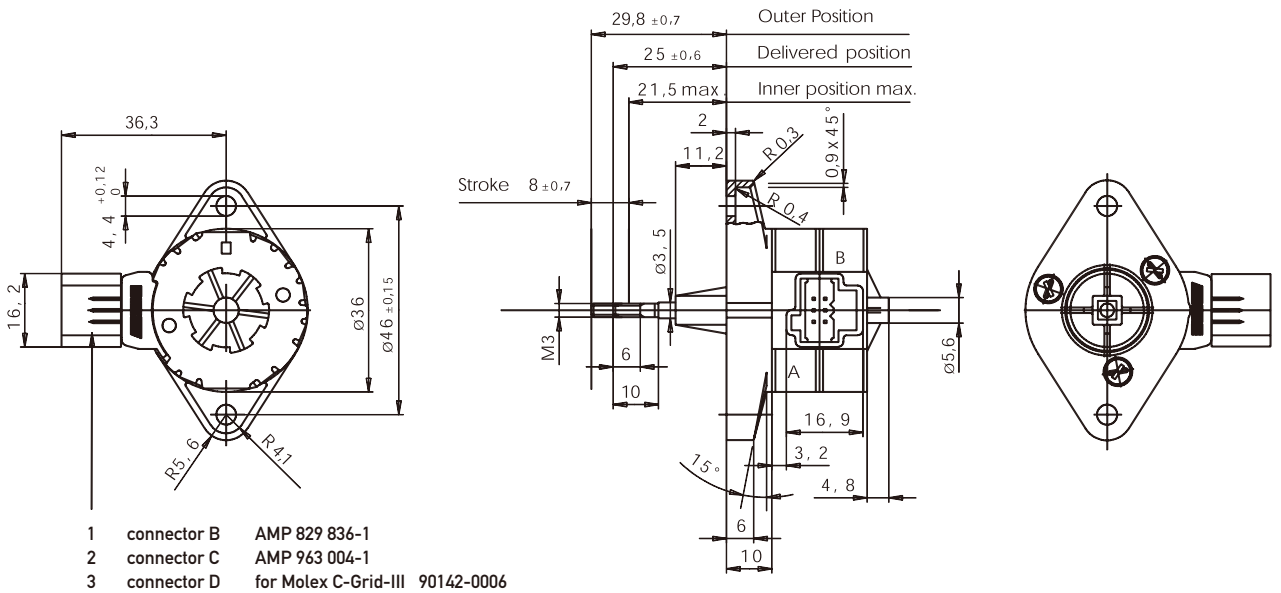
Order Reference

Type	Stepper Motor	UBL	13	N	100	B	3C
Configuration	13 bipolar 23 unipolar						
Approval	N Approval Standard						
Resistance	See next page Resistance per winding for bipolar or unipolar.						
Connection	Jack connector 6 pin (other on request)						
Shaft	3C Travel 8 mm ± 0.7 mm / Tr. 3.7 x 1 (other on request)						

Technical Data

bipolar (UBL1)	Rated voltage U_N	V	6	12	24
	Resistance per winding R_{20}	Ω	18,5	100	460
unipolar (UBL2)	Rated voltage U_N	V	6	12	24
	Resistance per winding R_{20}	Ω	28	120	500
Steps per revolution			24		
Steps per mm			30/24		
Winding temperature T_{max}			105° C		
Duty cycle			100%		
Linear travel max.			8; 13; 56 ± 0,7		
Axial play at ± 20 N force			< 0,25 mm		
Axial force at 200 Hz F_A			10 N		

Dimensions



U0 Linear actuator (LA5021ST)

Dimensions (mm) \varnothing 50 x 76

Travel (mm) 45–50

Travel per step (mm) 0,031/0,047/0,063

Thread pitch (mm) 1,5/1,5/1,5

Speed (mm/s) at 200 Hz 6,25/9,37/12,5

Step angle (°) 7,5/11,25/15

Max. Force (N)* 45–50



*Depends on winding, frequency and lifetime required.

Drive against end stops only permissible after clarification of operating conditions and approval by Saia-Burgess.

Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15 ... +40
Ambient temperature storage	°C -20 ... +105
Thermal resistance at f=0 R _{therm}	K/W 20
Thermal class	A according to DIN EN 60085
Approval	standard
Mounting	any position
Electrical connection	cable
Protection	IP 40 according to DIN EN 60529
Weight	~220 g
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	ball bearing
Electric strength	According to DIN EN 60034-1/DIN EN 60335-1

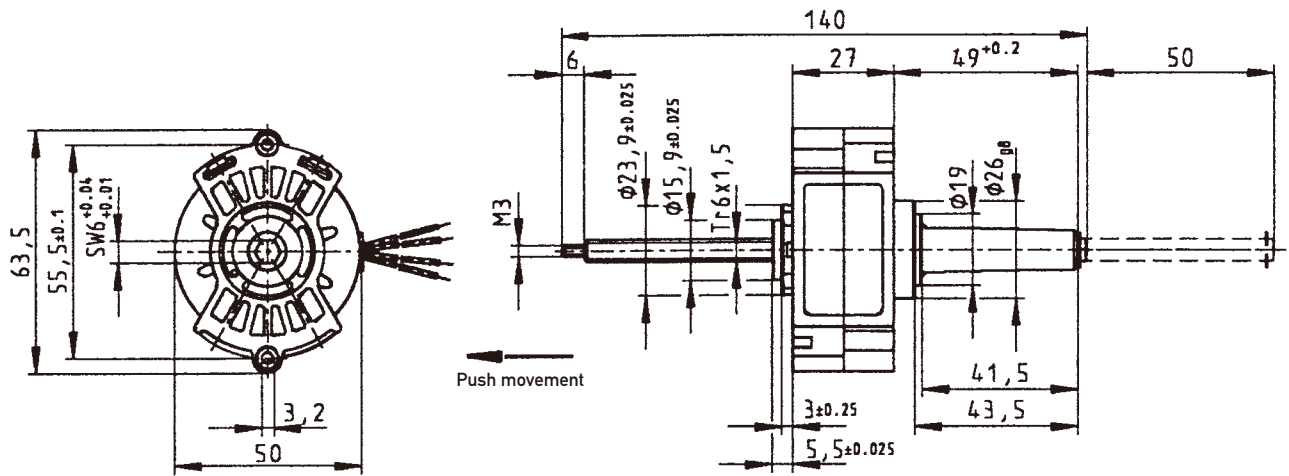
Order Reference

Type	Stepper Motor	LA5021ST	7 Ω	0,031 mm	50 mm
Resistance	7 Ω				
Travel per step	0,031 mm 0,047 mm 0,063 mm				
Travel	50 mm				

Technical Data

bipolar	Rated voltage U_N :	V	4 (Chopper drive)		
	Resistance per winding R_{20}	Ω	7		
	Step angle	$^\circ$	7.5	11.25	15
	Travel per step	mm	0.031	0.047	0.063
	Steps per mm		32	21	16
	Winding temperature T_{max}	$^\circ C$	130		
	Duty cycle		100%		
	Linear travel max.	mm	50		
	Axial play at 20 N force	mm	<0.25		

Dimensions



Standard - wire length: 100^{+20} mm/ 6 ± 1 stripped

U0 Spindle actuator (SP5022ST)

Dimensions (mm) \varnothing 50 x 27

Travel (mm) 68–130

Travel per step (mm) 0,031/0,047/0,063

Thread pitch (mm) 1,5/1,5/1,5

Speed (mm/s) at 200 Hz 6,25/9,37/12,5

Step angle (°) 7,5/11,25/15

Max. Force (N)* 50–70



*Depends on winding, frequency and lifetime required.

Drive against end stops only permissible after clarification of operating conditions and approval by Saia-Burgess.

Standard Data

Climatic class	wide-spread according to DIN IEC 60721-2-1
Ambient temperature operation	°C -15 ... +40
Ambient temperature storage	°C -20 ... +105
Thermal resistance at f=0 R _{therm}	K/W 20
Thermal class	A according to DIN EN 60085
Approval	standard
Mounting	any position
Electrical connection	cable
Protection	IP 40 according to DIN EN 60529
Weight	~220 g
Rotor stalling	motor can be stopped when voltage is applied, without being overheated
Bearings	ball bearing
Electric strength	According to DIN EN 60034-1/DIN EN 60335-1

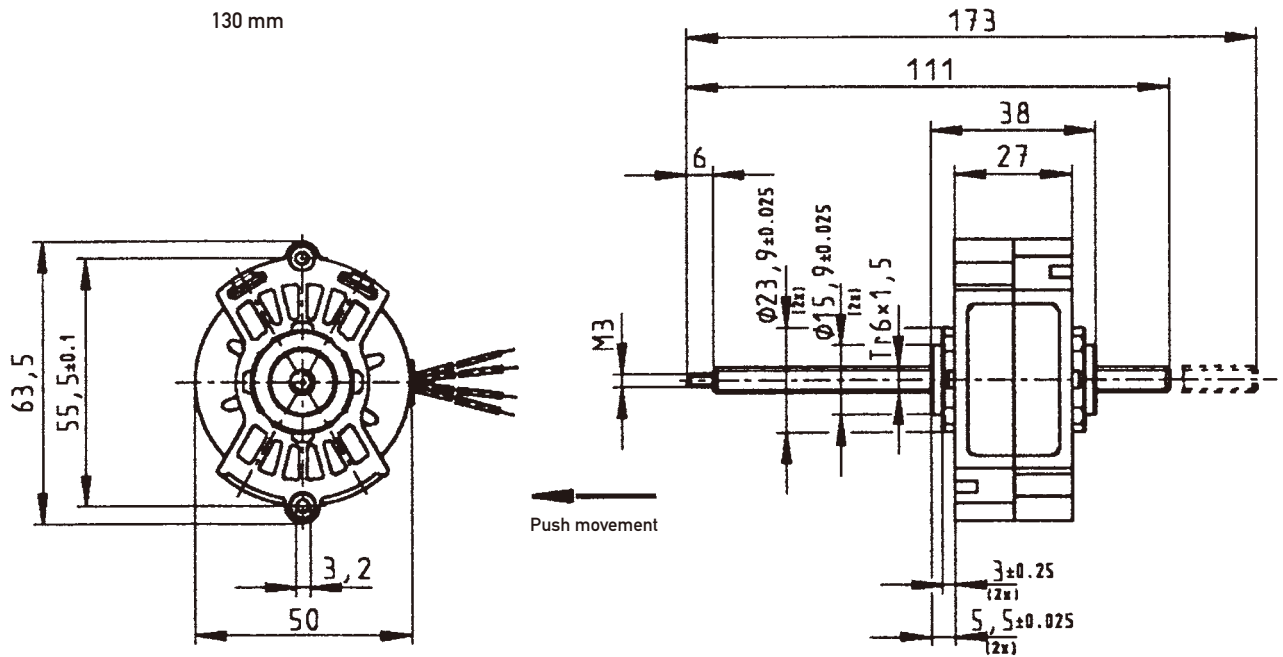
Order Reference

Type	Stepper Motor	SP5022ST	7 Ω	0,031 mm	68 mm
Resistance	7 Ω				
Travel per step	0,031 mm 0,047 mm 0,063 mm				
Travel	68 mm 130 mm				

Technical Data

bipolar	Rated voltage U_N :	V	4 (Chopper drive)		
	Resistance per winding R_{20}	Ω	7		
	Step angle	$^\circ$	7.5	11.25	15
	Travel per step	mm	0,031	0,047	0,063
	Steps per mm		32	21	16
	Winding temperature T_{max}	$^\circ C$	130		
	Travel	mm	-68/+130		
	Positioning accuracy (incl. axial play)	mm	$\pm 0,15$		
	Static axial force	N	max. 50		
	Self-locking by spindle/nut system		yes		
	Drive		not stall-proof		
	Anti-rotation guidance of spindle		external required		

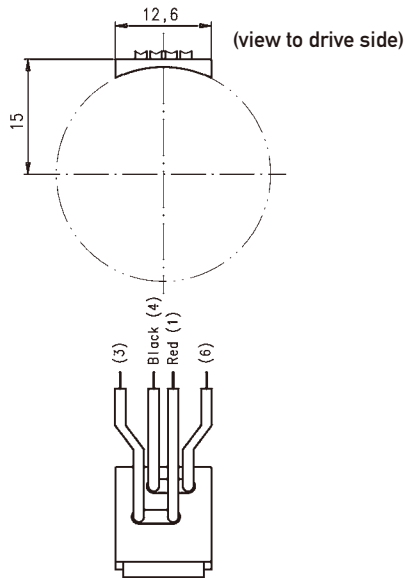
Dimensions Version with Travel 68 mm
130 mm



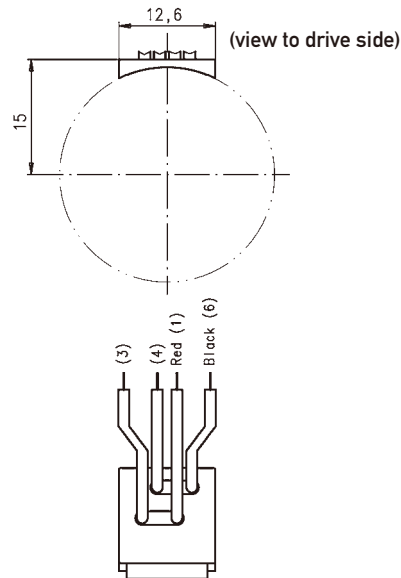
Standard - wire length: 100^{+20} mm/6 ± 1 stripped

Connection Types

Lead wire **Connection N**



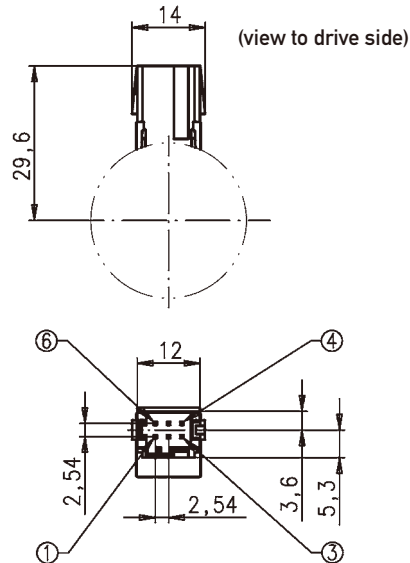
up to 48 V
for rotary motors
(bipolar, synchronous in parallel circuit)



different lead colours for 110 V (230 V)
for rotary synchronous motors in series circuit

Connector **Connector C**

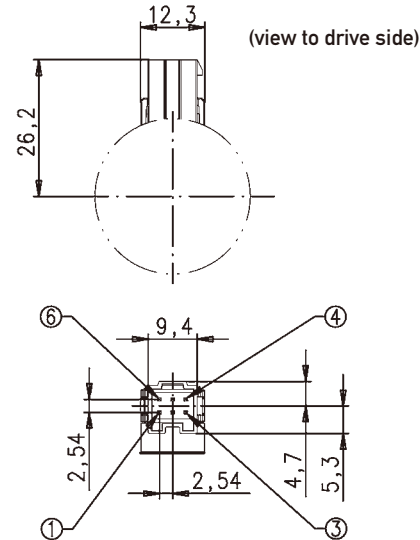
for Tyco Tyco Modu IV 0-1740209-6



up to 48 V
for linear motors
(bipolar, unipolar, synchronous)

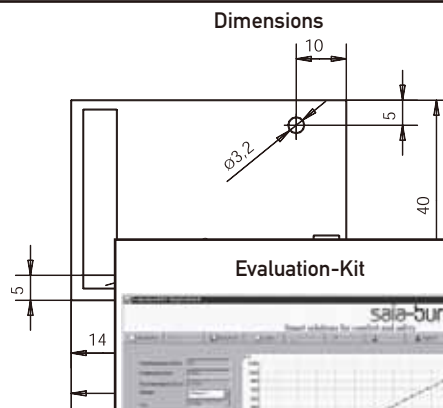
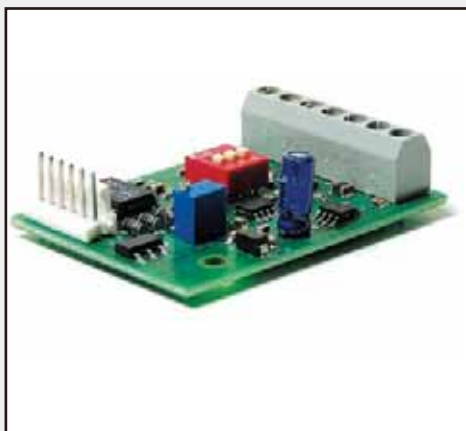
Connector **Connector D**

for Molex C-Grid III 90142-006



up to 48 V
for rotary and linear motors
(bipolar, unipolar, synchronous)

Electronics for Stepper Motors



Driver Board

SAMOTRONIC101

Driver	for unipolar motors
Dimensions (mm)	55 x 40
Supply voltage (VDC)	10-24
Motor current	constant voltage drive
Step mode	full/half step
Clock source	internal or external
Control inputs to	<ul style="list-style-type: none"> ■ inhibit internal clock ■ inhibit motor current ■ change direction of rotations
Configuration	via DIP-switch, potentiometer



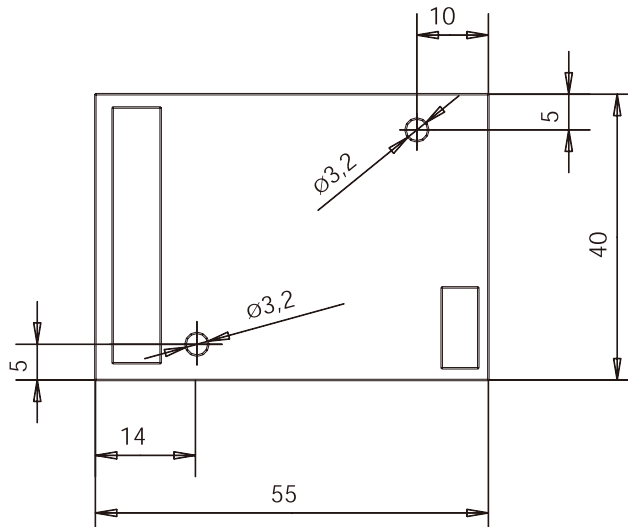
Preferred Range

Ordering Reference	
4 636 6608 0	If motors are also to be ordered please state: "with MTA-100 receptacles for use with SAMOTRONIC101".
4 636 6608 3	with screw terminal for motor connection, max 0,5 mm ²

Technical Data

Supply voltage	10-24 VDC
Phase current	≤ 350 mA
Control signal level	LS-TTL (0-5V) for all control inputs
Internal clock	50-360 Hz
External clock	up to 2 kHz
Dimensions	55 x 40 mm
Operating temperature	-5 to +50 °C
Storage temperature	-20 to +70 °C

Dimensions



For latest technical and safety compliance information regarding these products, please download the relevant data sheet from our web site:
www.saia-burgess.com/drivers

SAMOTRONIC102

Driver	for bipolar motors
Dimensions (mm)	84 x 54
Supply voltage (VDC)	<ul style="list-style-type: none"> ■ standard version 10 DC-24 ■ enhanced version 10 DC-42
Motor current	<ul style="list-style-type: none"> ■ constant current drive (chopper controlled) ■ adjustable via potentiometer
Step mode	full/half step
Clock source	internal or external
Control inputs to	<ul style="list-style-type: none"> ■ inhibit internal clock ■ inhibit motor current ■ change direction of rotations
Configuration	via DIP-switch, potentiometer
Test pins	<ul style="list-style-type: none"> ■ motor current ■ step frequency



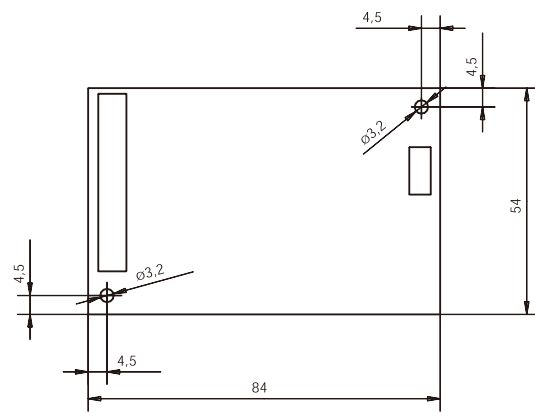
Preferred Range

Ordering Reference	
4 636 6733 0	10-24VDC supply voltage (standard version)
4 636 6733 3	10-42VDC supply voltage (enhanced version)
If motors are also to be ordered please state: "with MTA-100 receptacles for use with SAMOTRONIC102".	

Technical Data

Supply voltage	10-24 (42)VDC
Phase current	71-500 mA, on request max. 735mA/ph
Chopper frequency	typ. 20kHz
Control signal level	LS-TTL (0-5V) for all control inputs
Internal clock	50-1325 Hz
External clock	up to 2 kHz
Dimensions	84 x 54 mm
Operating temperature	-20 to +60 °C
Storage temperature	-20 to +80 °C

Dimensions



For latest technical and safety compliance information regarding these products, please download the relevant data sheet from our web site:
www.saia-burgess.com/drivers

Evaluation-Kit 2

Evaluation-Kit 2

Driver	for unipolar and bipolar motors
Dimensions (mm)	metal case 164 x 130 x 45
Supply voltage (VDC)	3–48
(VAC)	24
Motor current	constant voltage drive and constant current drive (chopper controlled)
Step mode	full/half/micro step
Clock source	internal, programmable
Control inputs to	<ul style="list-style-type: none">■ 3 digital inputs■ 4 signal outputs■ 1 analog input 0...10 VDC■ relay contact
Configuration	RS 232, USB



Order Reference

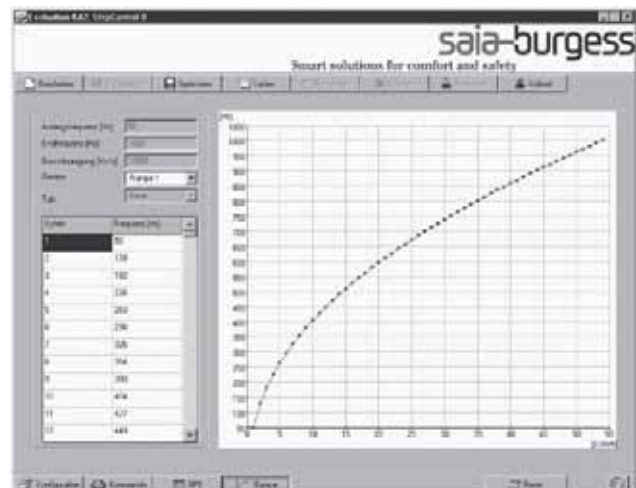
4 717 4898 0

Power supply (on request)

Technical Data

Supply voltage	10–48 VDC/24 VAC
Phase current	≤ up to 2.3 A
Step modes	11 (full, half, wave ... microstep)
Max. step frequency	10 kHz
PLC	max. 256 steps, 65536 loops
Operating temperature	0 ... +55 °C
Storage temperature	-20 to +80 °C

Test the Stepconfreeware without hardware in a special demo mode (www.saia-burgess.com/evaluationkit2).



For further information please contact your Saia-Burgess sales company or see our website www.saia-burgess.com.

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